
Derived n -plectic geometry:
towards non-perturbative BV-BFV quantisation and M-theory

Luigi Alfonsi

Joint work with Charles Young to appear soon



Talk at

M-Theory and Mathematics 2023

New York University Abu Dhabi

15/01/2023

Table of contents

- 1 Introduction
- 2 Formal derived smooth stacks
- 3 Ordinary n -plectic geometry
- 4 Derived n -plectic geometry
- 5 Outlook

Table of Contents

- 1 Introduction
- 2 Formal derived smooth stacks
- 3 Ordinary n -plectic geometry
- 4 Derived n -plectic geometry
- 5 Outlook

Introduction: Batalin–Vilkovisky (BV) theory

The space of solutions of the field equations of a classical field theory is exactly the critical locus $\text{Crit}(S)$ of its action functional S .

Introduction: Batalin–Vilkovisky (BV) theory

The space of solutions of the field equations of a classical field theory is exactly the critical locus $\text{Crit}(S)$ of its action functional S .

Idea of BV-theory

Look at its **derived critical locus** $\mathbb{R}\text{Crit}(S)$, a derived enhancement of $\text{Crit}(S)$.

Introduction: Batalin–Vilkovisky (BV) theory

The space of solutions of the field equations of a classical field theory is exactly the critical locus $\text{Crit}(S)$ of its action functional S .

Idea of BV-theory

Look at its **derived critical locus** $\mathbb{R}\text{Crit}(S)$, a derived enhancement of $\text{Crit}(S)$.

Main approaches to make classical (and quantum) BV-theory precise in the literature:

① ***NQP*-manifolds approach.** [Jurčo, Raspollini, Sämann, Wolf, ...]

Algebra of classical observables is given by a Poisson dg-Lie algebra of functions on an *NQP*-manifold, i.e. a differential-graded manifold (dg-manifold) equipped with a (-1) -shifted symplectic form. (Equivalently, a symplectic L_∞ -algebroid.)

Introduction: Batalin–Vilkovisky (BV) theory

The space of solutions of the field equations of a classical field theory is exactly the critical locus $\text{Crit}(S)$ of its action functional S .

Idea of BV-theory

Look at its **derived critical locus** $\mathbb{R}\text{Crit}(S)$, a derived enhancement of $\text{Crit}(S)$.

Main approaches to make classical (and quantum) BV-theory precise in the literature:

- 1 ***NQP*-manifolds approach.** [Jurčo, Raspollini, Sämann, Wolf, ...]
Algebra of classical observables is given by a Poisson dg-Lie algebra of functions on an *NQP*-manifold, i.e. a differential-graded manifold (dg-manifold) equipped with a (-1) -shifted symplectic form. (Equivalently, a symplectic L_∞ -algebroid.)
- 2 **Factorisation Algebras approach.** [Costello, Gwilliam, Williams, ...]
Algebra of classical observables is given by the \mathbb{P}_0 -algebra of functions on a (-1) -shifted symplectic formal moduli problem (i.e. a derived stack on Artinian dg-algebras), which is sheaved on spacetime.

Introduction: Batalin–Vilkovisky (BV) theory

The space of solutions of the field equations of a classical field theory is exactly the critical locus $\text{Crit}(S)$ of its action functional S .

Idea of BV-theory

Look at its **derived critical locus** $\mathbb{R}\text{Crit}(S)$, a derived enhancement of $\text{Crit}(S)$.

Main approaches to make classical (and quantum) BV-theory precise in the literature:

- 1 ***NQP*-manifolds approach.** [Jurčo, Raspollini, Sämann, Wolf, ...]
Algebra of classical observables is given by a Poisson dg-Lie algebra of functions on an *NQP*-manifold, i.e. a differential-graded manifold (dg-manifold) equipped with a (-1) -shifted symplectic form. (Equivalently, a symplectic L_∞ -algebroid.)
- 2 **Factorisation Algebras approach.** [Costello, Gwilliam, Williams, ...]
Algebra of classical observables is given by the \mathbb{P}_0 -algebra of functions on a (-1) -shifted symplectic formal moduli problem (i.e. a derived stack on Artinian dg-algebras), which is sheaved on spacetime.
- 3 **Perturbative Algebraic Quantum Field Theory (pAQFT).** [Rejzner, ...]
Algebra of observables is given by a net of locally convex topological Poisson $*$ -algebras on spacetime.

Approaches (1) & (2) very close, (2) & (3) related by [Schenkel, Benini, ...]

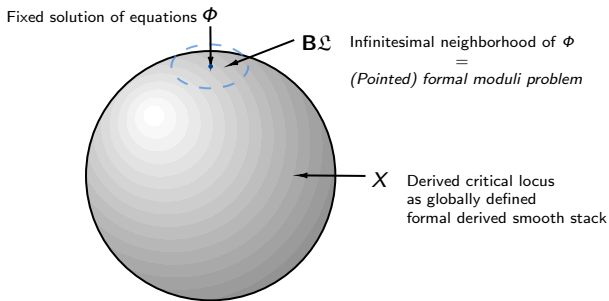
Motivation: towards global smooth BV-theory

Formal Moduli Problem: (algebraic) derived stack on Artinian dg-algebras, i.e.

$$F : \text{dgArt}^{\leq 0} \longrightarrow \text{sSet}$$

Artinian dg-algebras \simeq algebras of function on "derived thickened points".

A (-1) -symplectic Formal Moduli Problem can be seen as the **formal completion** of a fully-fledged (-1) -symplectic derived stack at some given point.



Motivation: towards global smooth BV-theory

We have the following picture:

$$\begin{aligned} \text{Formal Moduli Problem} &\longleftrightarrow \text{Perturbative physics} \\ \text{Formal derived smooth stack} &\longleftrightarrow \text{Non-perturbative physics} \end{aligned}$$

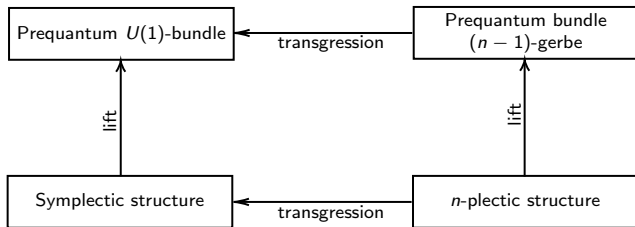
Example (Stack of G -bundles with connection)

$$\underbrace{[\Omega^1(M, \mathfrak{g})/\mathcal{C}^\infty(M, \mathfrak{g})]}_{L_\infty\text{-algebroid}} \neq \underbrace{\mathbf{Bun}_G^\nabla(M)}_{\text{stack of } G\text{-bundles}} := [M, \mathbf{B}G_{\text{conn}}]$$

- M-theory includes **(higher) gauge theories**
 - ▶ Quantisation requires BV-theory, i.e. **derived geometry**
 - ▶ Finite (higher) gauge transformations and global properties require stacks, i.e. **higher geometry** (e.g. Aharonov-Bohm phase and magnetic charge for electromagnetic field)
- Moreover, we have global string (and M-)dualities and non-perturbative effects
- It's not totally clear how the 0-symplectic (BFV) structure at the boundary would fit in this derived geometric picture.

Motivation: higher geometric (pre)quantisation

n -plectic geometry (or higher symplectic geometry) [Rogers, Baez, Saemann, Szabo, Bunk, Fiorenza, Schreiber, Sati, ...] naturally fits in the following picture:

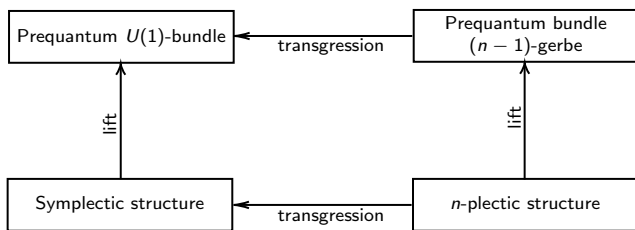


Example (Closed string)

[Waldorf 2009]: transgression of a bundle gerbe on a smooth manifold M to a principal $U(1)$ -bundle on the loop space $\mathcal{L}M = [S^1, M]$.

Motivation: higher geometric (pre)quantisation

n -plectic geometry (or higher symplectic geometry) [Rogers, Baez, Saemann, Szabo, Bunk, Fiorenza, Schreiber, Sati, ...] naturally fits in the following picture:



Example (Closed string)

[Waldorf 2009]: transgression of a bundle gerbe on a smooth manifold M to a principal $U(1)$ -bundle on the loop space $\mathcal{L}M = [S^1, M]$.

- [Ševera 2000]: Courant 2-algebroid and Vinogradov n -algebroid are higher generalisations of the Poisson 1-algebroid (as symplectic L_∞ -algebroids).
- [Rogers 2011], [Sämann, Ritter 2015]: relation between the L_∞ -algebras of observables on n -plectic manifolds and Vinogradov n -algebroids.

Table of Contents

- 1 Introduction
- 2 Formal derived smooth stacks
- 3 Ordinary n -plectic geometry
- 4 Derived n -plectic geometry
- 5 Outlook

Geometry as theory of sheaves and stacks

- An **ordinary geometric space** can be encoded by its **functor of points**, i.e. a functor

$$\text{space} : \text{probing spaces}^{\text{op}} \longrightarrow \text{sets}$$

which satisfies the sheaf condition.

Geometry as theory of sheaves and stacks

- An **ordinary geometric space** can be encoded by its **functor of points**, i.e. a functor

$$\text{space} : \text{probing spaces}^{\text{op}} \longrightarrow \text{sets}$$

which satisfies the sheaf condition.

- In the same spirit, a **higher geometric space** can be defined as a **stack**, i.e. a functor

$$\text{higher space} : \text{probing spaces}^{\text{op}} \longrightarrow \infty\text{-groupoids}$$

which is fibrant-cofibrant respect to a certain simplicial model category structure.

Geometry as theory of sheaves and stacks

- An **ordinary geometric space** can be encoded by its **functor of points**, i.e. a functor

$$\text{space} : \text{probing spaces}^{\text{op}} \longrightarrow \text{sets}$$

which satisfies the sheaf condition.

- In the same spirit, a **higher geometric space** can be defined as a **stack**, i.e. a functor

$$\text{higher space} : \text{probing spaces}^{\text{op}} \longrightarrow \infty\text{-groupoids}$$

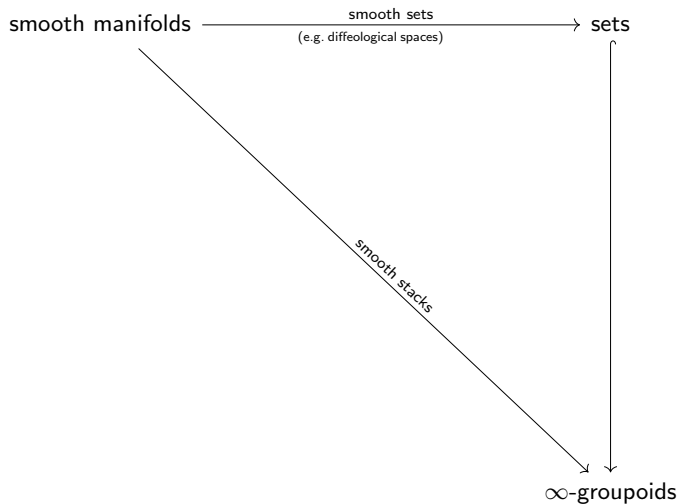
which is fibrant-cofibrant respect to a certain simplicial model category structure.

- A **higher derived geometric space** can be defined as a **derived stack**, i.e. a functor

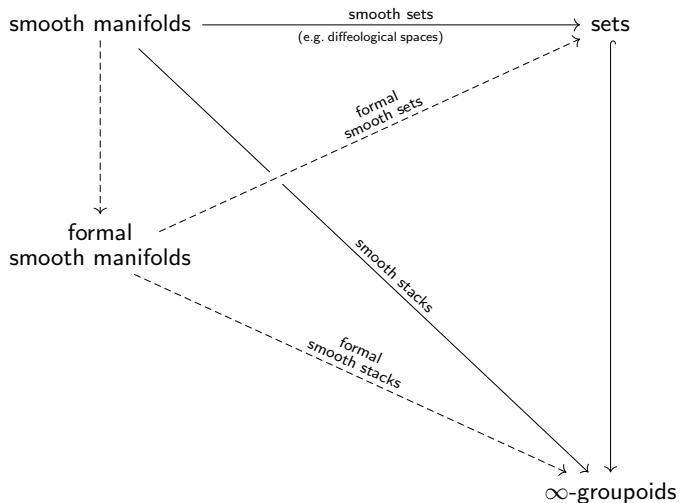
$$\text{higher derived space} : \text{derived probing spaces}^{\text{op}} \longrightarrow \infty\text{-groupoids}$$

which is fibrant-cofibrant respect to a certain simplicial model category structure.

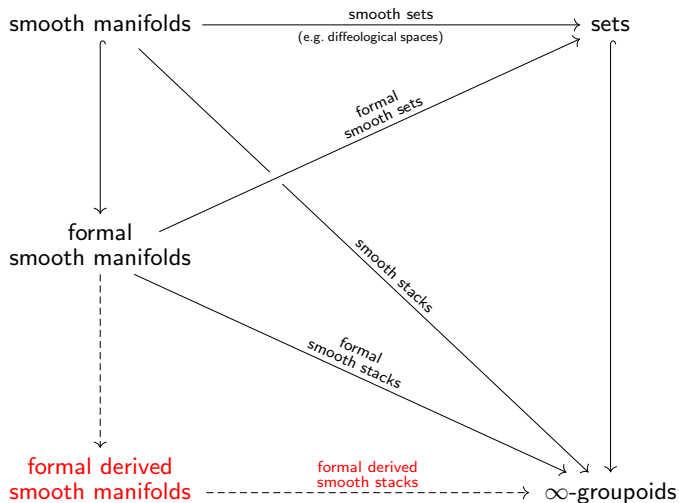
Family tree of smooth stacks



Family tree of smooth stacks



Family tree of smooth stacks



Formal derived smooth manifolds

Homotopy C^∞ -algebras: simplicial C^∞ -algebras with projective model structure, i.e.

$$\mathbf{h}C^\infty\mathbf{Alg} := [\Delta^{\text{op}}, C^\infty\mathbf{Alg}]_{\text{proj}}^{\circ},$$

where Δ is the simplex category.

Formal derived smooth manifolds

Homotopy \mathcal{C}^∞ -algebras: simplicial \mathcal{C}^∞ -algebras with projective model structure, i.e.

$$\mathrm{hC}^\infty\mathrm{Alg} := [\Delta^{\mathrm{op}}, \mathrm{C}^\infty\mathrm{Alg}]_{\mathrm{proj}}^{\circ},$$

where Δ is the simplex category.

The following will be our effective definition of formal derived manifolds.

Theorem [Carchedi, Steffens 2019]

There is a canonical equivalence of $(\infty, 1)$ -categories

$$\mathrm{dFMfd} \simeq \mathrm{hC}^\infty\mathrm{Alg}_{\mathrm{fp}}^{\mathrm{op}}$$

between the $(\infty, 1)$ -category of **formal derived manifolds**, and the opposite of the $(\infty, 1)$ -category of homotopically finitely presented homotopy \mathcal{C}^∞ -algebras.

At an intuitive level, $U \in \mathrm{dFMfd}$ is a geometric object whose algebra of smooth function is a homotopically finitely presented homotopy \mathcal{C}^∞ -algebra modelled as

$$\mathcal{O}(U) = \left(\cdots \begin{array}{c} \rightrightarrows \\ \rightrightarrows \\ \rightrightarrows \end{array} \mathcal{O}(U)_3 \begin{array}{c} \rightrightarrows \\ \rightrightarrows \\ \rightrightarrows \end{array} \mathcal{O}(U)_2 \begin{array}{c} \rightrightarrows \\ \rightrightarrows \\ \rightrightarrows \end{array} \mathcal{O}(U)_1 \rightrightarrows \mathcal{O}(U)_0 \right)$$

where each $\mathcal{O}(U)_i$ is an ordinary \mathcal{C}^∞ -algebra.

Formal derived smooth stacks

- We can define étale maps of formal derived smooth manifolds so that they truncate to local diffeomorphisms of ordinary manifolds.
- By using étale maps, we can make dFMfd into a $(\infty, 1)$ -site.
- By [Toen, Vezzosi 2006], we can define **formal derived smooth stacks** by

$$\mathbf{dFSmoothStack} := [\mathbf{dFMfd}^{\mathrm{op}}, \mathbf{sSet}]_{\mathrm{proj}, \mathrm{loc}}^{\circ}$$

Formal derived smooth stacks

- We can define étale maps of formal derived smooth manifolds so that they truncate to local diffeomorphisms of ordinary manifolds.
- By using étale maps, we can make dFMfd into a $(\infty, 1)$ -site.
- By [Toen, Vezzosi 2006], we can define **formal derived smooth stacks** by

$$\mathbf{dFSmoothStack} := [\mathbf{dFMfd}^{\text{op}}, \mathbf{sSet}]_{\text{proj, loc}}^{\circ}$$

Formal derived smooth sets can be defined as those stacks whose underived-truncation happens to be an ordinary formal smooth set, i.e. as an element of the pullback

$$\mathbf{dFSmoothSet} := \mathbf{dFSmoothStack} \times_{\mathbf{FSmoothStack}}^h \mathbf{FSmoothSet}$$

Thus, one has (co-)reflective embeddings

$$\begin{array}{ccc} \mathbf{dFSmoothStack} & \begin{array}{c} \leftarrow \\ \xrightarrow{t_0} \end{array} & \mathbf{FSmoothStack} \\ \begin{array}{c} \updownarrow \\ \tau_0 \end{array} & & \begin{array}{c} \updownarrow \\ \tau_0 \end{array} \\ \mathbf{dFSmoothSet} & \begin{array}{c} \leftarrow \\ \xrightarrow{t_0} \end{array} & \mathbf{FSmoothSet} \\ & \begin{array}{c} \leftarrow \\ \xrightarrow{i} \end{array} & \end{array}$$

On an **affine** derived formal smooth set $\mathbb{R}\text{Spec}(R)$, these maps amount to

$$t_0 \mathbb{R}\text{Spec}(R) \simeq \text{Spec}(\pi_0 R), \quad i \mathbb{R}\text{Spec}(R) \simeq \mathbb{R}\text{Spec}(R)$$

Derived differential cohesion

Let $C^\infty \text{Alg}^{\text{red}}$ be the sub-category of **reduced C^∞ -algebras**, i.e. with no non-zero nilpotent elements. The reduction functor is defined by

$$\begin{aligned} (-)^{\text{red}} : \mathbf{h}C^\infty \text{Alg} &\longrightarrow C^\infty \text{Alg}^{\text{red}} \\ R &\longmapsto R^{\text{red}} := \pi_0 R / \mathfrak{m}_{\pi_0 R} \end{aligned}$$

where $\mathfrak{m}_{\pi_0 R} \subset \pi_0 R$ is the ideal of nilpotent elements of $\pi_0 R$. This is right-adjoint to the natural embedding, i.e.

$$C^\infty \text{Alg}_{\text{fp}}^{\text{red}} \begin{array}{c} \xleftarrow{(-)^{\text{red}}} \\ \xrightarrow{\iota^{\text{red}}} \end{array} \mathbf{h}C^\infty \text{Alg}_{\text{fp}}.$$

Derived differential cohesion

Let $C^\infty \text{Alg}^{\text{red}}$ be the sub-category of **reduced C^∞ -algebras**, i.e. with no non-zero nilpotent elements. The reduction functor is defined by

$$\begin{aligned} (-)^{\text{red}} : \mathbf{h}C^\infty \text{Alg} &\longrightarrow C^\infty \text{Alg}^{\text{red}} \\ R &\longmapsto R^{\text{red}} := \pi_0 R / \mathfrak{m}_{\pi_0 R} \end{aligned}$$

where $\mathfrak{m}_{\pi_0 R} \subset \pi_0 R$ is the ideal of nilpotent elements of $\pi_0 R$. This is right-adjoint to the natural embedding, i.e.

$$C^\infty \text{Alg}_{\text{fp}}^{\text{red}} \begin{array}{c} \xleftarrow{(-)^{\text{red}}} \\ \xrightarrow{\iota^{\text{red}}} \end{array} \mathbf{h}C^\infty \text{Alg}_{\text{fp}}.$$

These give rise to a quadruplet of adjoint functors:

$$\begin{array}{ccc} & \begin{array}{c} \xleftarrow{\iota_!^{\text{red}}} \\ \xrightarrow{\iota^{\text{red}*} \simeq (-)_!^{\text{red}}} \\ \xleftarrow{\iota_*^{\text{red}} \simeq (-)^{\text{red}*}} \\ \xrightarrow{(-)_*^{\text{red}}} \end{array} & \\ \mathbf{dFSmoothStack} & & \mathbf{SmoothStack}, \end{array}$$

where $\mathbf{SmoothStack} := \mathbf{Stack}(\text{Mfd})$ is the $(\infty, 1)$ -topos of (non-formal) smooth stacks, i.e. of stacks on ordinary smooth manifolds.

This quadruplet is a **differential cohesion** structure, as defined by [Schreiber 2013]:

$$\begin{array}{ccccc}
 & \xleftarrow{\iota_!^{\text{red}}} & & \xrightarrow{\quad \Pi \quad} & \\
 \mathbf{dFSmoothStack} & \xrightarrow{\iota^{\text{red}*} \simeq (-)_!^{\text{red}}} & \mathbf{SmoothStack} & \xrightarrow{\text{Disc}} & \infty\mathbf{Grpd}, \\
 & \xleftarrow{\iota_*^{\text{red}} \simeq (-)^{\text{red}*}} & & \xleftarrow{\quad \Gamma \quad} & \\
 & \xrightarrow{(-)_*^{\text{red}}} & & \xrightarrow{\text{CoDisc}} & \\
 & \xrightarrow{\quad} & & \xrightarrow{\quad} &
 \end{array}$$

On an affine derived formal smooth set $\mathbb{R}\text{Spec}(R)$, the crucial maps amount to

$$\iota_!^{\text{red}}\mathbb{R}\text{Spec}(R) \simeq \mathbb{R}\text{Spec}(R) \quad \iota^{\text{red}*}\mathbb{R}\text{Spec}(R) \simeq \text{Spec}(R^{\text{red}}),$$

This quadruplet is a **differential cohesion** structure, as defined by [Schreiber 2013]:

$$\begin{array}{ccc}
 & \begin{array}{c} \xleftarrow{\iota_!^{\text{red}}} \\ \xrightarrow{\iota^{\text{red}*} \simeq (-)_!^{\text{red}}} \\ \xleftarrow{\iota_*^{\text{red}} \simeq (-)^{\text{red}*}} \\ \xrightarrow{(-)_*^{\text{red}}} \\ \xrightarrow{\quad\quad\quad} \end{array} & \text{SmoothStack} \\
 \text{dFSmoothStack} & & \begin{array}{c} \xrightarrow{\quad\quad\quad} \\ \xleftarrow{\text{Disc}} \\ \xrightarrow{\quad\quad\quad} \\ \xleftarrow{\text{CoDisc}} \end{array} \infty\text{Grpd},
 \end{array}$$

On an affine derived formal smooth set $\mathbb{R}\text{Spec}(R)$, the crucial maps amount to

$$\iota_!^{\text{red}}\mathbb{R}\text{Spec}(R) \simeq \mathbb{R}\text{Spec}(R) \quad \iota^{\text{red}*}\mathbb{R}\text{Spec}(R) \simeq \text{Spec}(R^{\text{red}}),$$

Infinitesimal shape modality

$$\mathfrak{J} : \text{dFSmoothSet} \longrightarrow \text{dFSmoothSet}$$

$$X \longmapsto \iota_*^{\text{red}} \circ \iota^{\text{red}*}(X).$$

Adjunction $\iota^{\text{red}*} \dashv \iota_*^{\text{red}}$ implies that there is an adjunction unit (**infinitesimal shape unit**):

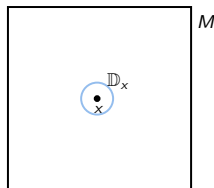
$$i_X : X \longrightarrow \mathfrak{J}(X)$$

Derived infinitesimal disks and jet bundles

Thanks to differential cohesion, we can do differential geometry on formal derived smooth sets, i.e. we can extend results of [Khavkine, Schreiber].

Roughly, this allows us to define **derived infinitesimal disks** by

$$\begin{array}{ccc} \mathbb{D}_x & \xleftarrow{\iota_x} & M \\ \downarrow & & \downarrow i_M \\ * & \xleftarrow{x} & \mathfrak{J}(M) \end{array}$$

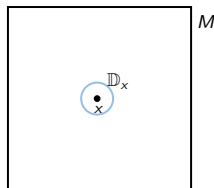


Derived infinitesimal disks and jet bundles

Thanks to differential cohesion, we can do differential geometry on formal derived smooth sets, i.e. we can extend results of [Khavkine, Schreiber].

Roughly, this allows us to define **derived infinitesimal disks** by

$$\begin{array}{ccc} \mathbb{D}_x & \xleftarrow{\iota_x} & M \\ \downarrow & & \downarrow i_M \\ * & \xleftarrow{x} & \mathfrak{J}(M) \end{array}$$



This allows us to study a number of geometric objects, including **jet bundles**:

$$\text{Jet}_M : E \longmapsto \text{Jet}_M E := (i_M)^*(i_M)_* E.$$

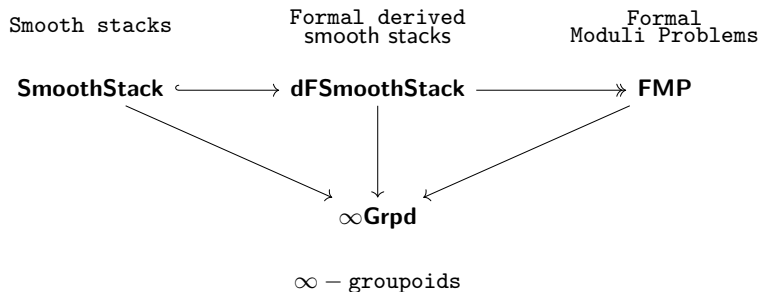
which are designed to satisfy the property

$$(\text{Jet}_M E)_x \simeq \Gamma(\mathbb{D}_x, E)$$

at any point $x \in M$.

Formal moduli problems as infinitesimal cohesion

Let **FMP** be the $(\infty, 1)$ -category of **Formal Moduli Problems**, which can be seen as formal derived stacks on derived infinitesimal disks.



Differential forms

The complex of p -forms on a formal derived smooth set is

$$A^p(X) := \mathbb{R}\Gamma(X, \wedge_{\mathbb{O}_X}^p \mathbb{L}_X)$$

This gives rise to a bi-complex

$$\begin{array}{ccccccc} & \vdots & & \vdots & & \vdots & \\ & \downarrow Q & & \downarrow Q & & \downarrow Q & \\ & A^0(X)_{-2} & \xrightarrow{d_{dR}} & A^1(X)_{-2} & \xrightarrow{d_{dR}} & A^2(X)_{-2} & \xrightarrow{d_{dR}} \dots \\ & \downarrow Q & & \downarrow Q & & \downarrow Q & \\ & A^0(X)_{-1} & \xrightarrow{d_{dR}} & A^1(X)_{-1} & \xrightarrow{d_{dR}} & A^2(X)_{-1} & \xrightarrow{d_{dR}} \dots \\ & \downarrow Q & & \downarrow Q & & \downarrow Q & \\ & A^0(X)_0 & \xrightarrow{d_{dR}} & A^1(X)_0 & \xrightarrow{d_{dR}} & A^2(X)_0 & \xrightarrow{d_{dR}} \dots \end{array}$$

$$\text{with } d_{dR}^2 = Q^2 = d_{dR} \circ Q + Q \circ d_{dR} = 0$$

Closed differential forms

The complex of closed p -forms on a formal derived smooth set is

$$A_{\text{cl}}^p(X) := \left(\prod_{n \geq p} A^n(X)[-n] \right)[p]$$

with total differential $d_{\text{dR}} + Q$.

Definition (Closed form)

An n -shifted closed p -form on a derived formal smooth set X is defined as an n -cocycle $(\omega_i) \in Z^n A_{\text{cl}}^p(X)$, i.e. as an element $\omega \in A_{\text{cl}}^p(X)$ such that $(d_{\text{dR}} + Q)\omega = 0$.

In other words, an n -cocycle in $A_{\text{cl}}^p(X)$ is given by a formal sum $\omega = (\omega_p + \omega_{p+1} + \dots)$, where each form $\omega_i \in A^i(X)$ is an element of degree $n + p - i$, satisfying the equations

$$\begin{aligned} Q\omega_p &= 0, \\ d_{\text{dR}}\omega_p + Q\omega_{p+1} &= 0, \\ d_{\text{dR}}\omega_{p+1} + Q\omega_{p+2} &= 0, \\ &\vdots \end{aligned}$$

or, more compactly, $(d_{\text{dR}} + Q)\omega = 0$.

Table of Contents

- 1 Introduction
- 2 Formal derived smooth stacks
- 3 Ordinary n -plectic geometry**
- 4 Derived n -plectic geometry
- 5 Outlook

Ordinary n -plectic geometry

Definition (Ordinary n -plectic structure)

Given a formal smooth set $X \in \text{SmoothSet}$, an n -plectic structure on X is a closed differential $(n + 1)$ -form $\Omega \in \Omega_{\text{cl}}^{n+1}(X)$ such that the induced map

$$\Omega^\sharp : T_X \longrightarrow \wedge^n T_X^*$$

is a monomorphism.

Example (Symplectic structure)

A symplectic structure is a 1-plectic structure.

Poisson L_∞ -algebra of observables

[Rogers 2011] Define **Hamiltonian forms** by

$$\Omega_{\text{Ham}}^{n-1}(X) := \{ \alpha \in \Omega^{n-1}(X) \mid \iota_{V_\alpha} \Omega = d_{\text{dR}} \alpha \}$$

We call V_α is the Hamiltonian vector of α .

The differential graded vector space

$$\text{Ham}(X, \Omega) = \left(\mathcal{C}^\infty(X) \xrightarrow{d_{\text{dR}}} \Omega^1(X) \xrightarrow{d_{\text{dR}}} \dots \xrightarrow{d_{\text{dR}}} \Omega^{n-2}(X) \xrightarrow{d_{\text{dR}}} \Omega_{\text{Ham}}^{n-1}(X) \right)$$

equipped with brackets for all $k > 1$:

$$\begin{aligned} \ell_1(\alpha) &= \begin{cases} 0 & \text{if } |\alpha| = 0, \\ d_{\text{dR}} \alpha & \text{if } |\alpha| \neq 0, \end{cases} \\ \ell_k(\alpha_1, \dots, \alpha_k) &= \begin{cases} (-1)^{\binom{k+1}{2}} \iota_{V_{\alpha_1}} \cdots \iota_{V_{\alpha_k}} \Omega & \text{if } |\alpha_1 \otimes \cdots \otimes \alpha_k| = 0, \\ 0 & \text{if } |\alpha_1 \otimes \cdots \otimes \alpha_k| \neq 0, \end{cases} \end{aligned}$$

is an L_∞ -algebra.

Variational bi-complex

On the jet bundle there is a canonical splitting horizontal/vertical

$$d_{dR} = d_h + d_v$$

which gives rise to the *variational bi-complex* [Anderson 1989], i.e.

$$\begin{array}{ccccccc} \mathcal{O}(\text{Jet}E) & \xrightarrow{d_h} & \Omega^{1,0}(\text{Jet}E) & \xrightarrow{d_h} & \Omega^{2,0}(\text{Jet}E) & \xrightarrow{d_h} & \dots & \xrightarrow{d_h} & \Omega^{m,0}(\text{Jet}E) \\ \downarrow d_v & & \downarrow d_v & & \downarrow d_v & & & & \downarrow d_v \\ \Omega^{1,0}(\text{Jet}E) & \xrightarrow{d_h} & \Omega^{1,1}(\text{Jet}E) & \xrightarrow{d_h} & \Omega^{1,2}(\text{Jet}E) & \xrightarrow{d_h} & \dots & \xrightarrow{d_h} & \Omega^{m,1}(\text{Jet}E) \\ \downarrow d_v & & \downarrow d_v & & \downarrow d_v & & & & \downarrow d_v \\ \Omega^{2,0}(\text{Jet}E) & \xrightarrow{d_h} & \Omega^{2,1}(\text{Jet}E) & \xrightarrow{d_h} & \Omega^{2,2}(\text{Jet}E) & \xrightarrow{d_h} & \dots & \xrightarrow{d_h} & \Omega^{m,2}(\text{Jet}E) \\ \downarrow d_v & & \downarrow d_v & & \downarrow d_v & & & & \downarrow d_v \\ \vdots & & \vdots & & \vdots & & & & \vdots \end{array}$$

Pre-symplectic current of a field theory

Consider a Lagrangian density $\mathcal{L} \in \Omega^{m,0}(\text{Jet}E)$.

[Anderson 1989] tells us that its differential can be decomposed by

$$d_{\text{dR}}\mathcal{L} = \delta_{\text{EL}}\mathcal{L} - d_{\text{h}}\Theta_{\text{pre}},$$

where

- $\delta_{\text{EL}}\mathcal{L} \in \Omega^{m,1}(\text{Jet}E)$ is a "source" $(m, 1)$ -form
- $\Theta_{\text{pre}} \in \Omega^{m-1,1}(\text{Jet}E)$ is a $(m-1, 1)$ -form.

Definition (Pre-symplectic current)

The *pre-symplectic current* $\Omega_{\text{pre}} \in \Omega^{m-1,2}(\text{Jet}E)$ of a classical field theory is defined by the vertical derivative

$$\Omega_{\text{pre}} := d_{\text{v}}\Theta_{\text{pre}}$$

This form is not closed: in fact, one has

$$d_{\text{dR}}\Omega_{\text{pre}} = -d_{\text{v}}(\delta_{\text{EL}}\mathcal{L})$$

Euler-Lagrange critical locus

The following is an application of [Khavkine, Schreiber 2017].

Euler-Lagrange critical locus

The *Euler-Lagrange critical locus* $\text{Crit}_{\text{EL}}(\mathcal{L})$ can be defined as the pullback of formal smooth sets

$$\begin{array}{ccc} \text{Crit}_{\text{EL}}(\mathcal{L}) & \hookrightarrow & \text{Jet}_M E \\ \downarrow & & \downarrow \Delta_E \\ \text{Jet}_M \ker(\delta_{\text{EL}} L) & \xrightarrow{\text{Jet}_M e} & \text{Jet}_M(\text{Jet}_M E), \end{array}$$

where $e : \ker(\delta_{\text{EL}} L) \hookrightarrow \text{Jet} E$ is the natural embedding.

This has the crucial property that its fiber at any point $x \in M$ is given by germs of solutions of the field equations, i.e

$$\text{Crit}_{\text{EL}}(\mathcal{L})_x \simeq \text{Crit}(S)(\mathbb{D}_x)$$

Crucial example of n -plectic structure

Let $e_{\text{EL}} : \text{Crit}_{\text{EL}}(\mathcal{L}) \hookrightarrow \text{Jet}E$ the natural embedding and define the pullback

$$\Omega := e_{\text{EL}}^* \Omega_{\text{pre}}.$$

Example

The pair $(\text{Crit}_{\text{EL}}(\mathcal{L}), \Omega)$ is an n -plectic formal smooth set with $n = \dim(M)$.

Crucial example of n -plectic structure

Let $e_{\text{EL}} : \text{Crit}_{\text{EL}}(\mathcal{L}) \hookrightarrow \text{Jet}E$ the natural embedding and define the pullback

$$\Omega := e_{\text{EL}}^* \Omega_{\text{pre}}.$$

Example

The pair $(\text{Crit}_{\text{EL}}(\mathcal{L}), \Omega)$ is an n -plectic formal smooth set with $n = \dim(M)$.

Moreover, consider the transgression functor

$$\begin{aligned} \mathfrak{T}_{\Sigma} : \Omega^{\dim(\Sigma), p}(\text{Crit}_{\text{EL}}(\mathcal{L})) &\longrightarrow \Omega^p(\text{Crit}(S)(\Sigma_{\text{th}})) \\ \xi &\longmapsto \mathfrak{T}_{\Sigma} \xi := \int_{\Sigma} j(-)^* \xi, \end{aligned}$$

which sends a $(n-1, p)$ -form on $\text{Crit}_{\text{EL}}(\mathcal{L})$ to a p -form on the phase space $\text{Crit}(S)(\Sigma_{\text{th}})$ of the theory by integrating on a codimension 1 submanifold $\Sigma \subset M$.

This sends our n -plectic form to the honest symplectic form on the (infinite-dimensional) phase space of the theory, i.e.

$$\omega(\phi) = \int_{\Sigma} j(\phi)^* \Omega$$

Table of Contents

- 1 Introduction
- 2 Formal derived smooth stacks
- 3 Ordinary n -plectic geometry
- 4 Derived n -plectic geometry**
- 5 Outlook

Derived n -plectic structure

Definition (Derived n -plectic geometry)

Let $X \in \mathbf{dFSmoothSet}$ be a formal derived smooth set. A p -shifted n -plectic form is a cocycle $\Omega \in Z^p A_{\text{cl}}^{n+1}(X)$ such that the induced morphism of quasi-coherent sheaves

$$\Omega^\sharp : \mathbb{T}_X \longrightarrow \wedge^n \mathbb{L}_X[p]$$

gives rise to a monomorphism of the ∞ -groupoids of their sections

$$\Omega^\sharp : \mathfrak{X}(X, 0) \hookrightarrow \mathcal{A}^n(X, p)$$

Example (Derived symplectic structure)

A derived symplectic structure is, in particular, a derived 1-plectic structure.

Euler-Lagrange critical locus as a zero locus

It is possible to show that there are pullback squares

$$\begin{array}{ccccc}
 \text{Crit}_{\text{EL}}(\mathcal{L}) & \xleftarrow{e_{\text{EL}}} & \text{Jet}E & & \\
 \swarrow e_{\text{EL}} & & \downarrow \Delta_E & & \\
 \text{Jet}E & & \text{Jet} \ker(\delta_{\text{EL}}L) & \xrightarrow{\text{Jet}(e)} & \text{Jet}(\text{Jet}E) \\
 \downarrow \Delta_E & \swarrow \text{Jet}(e) & & & \swarrow \text{Jet}(\delta_{\text{EL}}L) \\
 \text{Jet}(\text{Jet}E) & \xleftarrow{\text{Jet}(0)} & \text{Jet}(T_{\text{src}}^* \text{Jet}E) & &
 \end{array}$$

Euler-Lagrange critical locus as a zero locus

It is possible to show that there are pullback squares

$$\begin{array}{ccc}
 \text{Crit}_{\text{EL}}(\mathcal{L}) & \xleftarrow{e_{\text{EL}}} & \text{Jet}E \\
 \swarrow e_{\text{EL}} & & \searrow \delta_{\text{EL}}^\infty L \\
 \text{Jet}E & \xrightarrow{0} & \text{Jet}(T_{\text{ver}}^\vee E) \\
 \downarrow \Delta_E & & \downarrow \Delta_E \\
 \text{Jet} \ker(\delta_{\text{EL}} L) & \xleftarrow{\text{Jet}(e)} & \text{Jet}(\text{Jet}E) \\
 \swarrow \text{Jet}(e) & & \searrow \text{Jet}(\delta_{\text{EL}} L) \\
 \text{Jet}(\text{Jet}E) & \xleftarrow{\text{Jet}(0)} & \text{Jet}(T_{\text{src}}^* \text{Jet}E)
 \end{array}$$

$\hat{\Delta}_E$ (red arrow from $\text{Jet}(T_{\text{ver}}^\vee E)$ to $\text{Jet}(T_{\text{src}}^* \text{Jet}E)$)

This recasts the Euler-Lagrange critical locus into the zero-locus of section $\delta_{\text{EL}}^\infty L$, i.e.

$$\text{Crit}_{\text{EL}}(\mathcal{L}) \simeq \ker(\delta_{\text{EL}}^\infty L)$$

Derived Euler-Lagrange critical locus

The *derived Euler-Lagrange critical locus* is the formal derived smooth set defined by the homotopy pullback

$$\begin{array}{ccc} \mathbb{R}\mathrm{Crit}_{\mathrm{EL}}(\mathcal{L}) & \longrightarrow & \mathrm{Jet}E \\ \downarrow p_{\mathrm{EL}} & & \downarrow 0 \\ \mathrm{Jet}E & \xrightarrow{\delta_{\mathrm{EL}}^{\infty} L} & \mathrm{Jet}(T_{\mathrm{ver}}^{\vee}E) \end{array}$$

in the $(\infty, 1)$ -category of formal derived smooth sets.

Dually, we can compute the derived tensor product of \mathcal{C}^{∞} -algebras

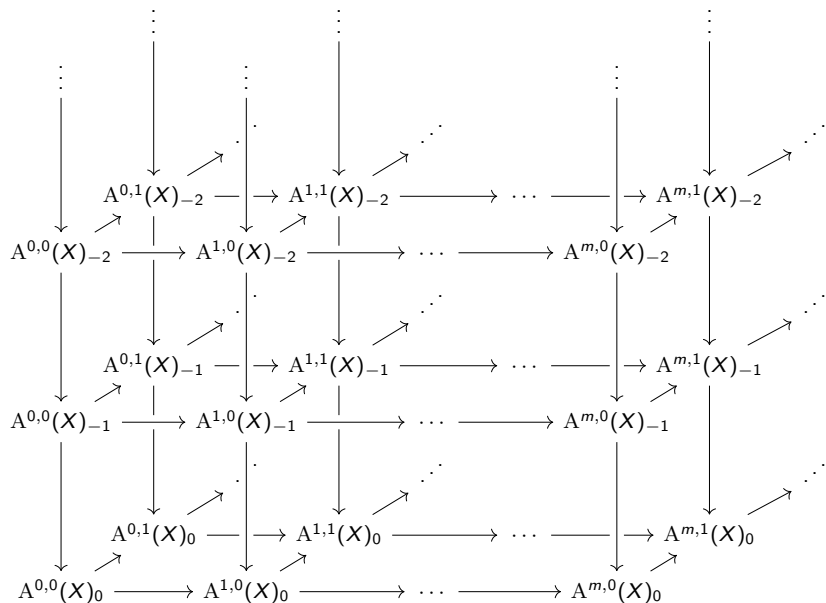
$$\mathcal{O}(\mathbb{R}\mathrm{Crit}_{\mathrm{EL}}(\mathcal{L})) \simeq \mathcal{O}(\mathrm{graph}(\delta_{\mathrm{EL}}^{\infty} L)) \widehat{\otimes}_{\mathcal{O}(\mathrm{Jet}(T_{\mathrm{ver}}^{\vee}E))}^{\mathbb{L}} \mathcal{O}(\mathrm{Jet}E)$$

The underlying dg-algebra is going to be of the form

$$\mathcal{O}(\mathbb{R}\mathrm{Crit}_{\mathrm{EL}}(\mathcal{L})) \simeq \Gamma(\mathrm{Jet}E, \wedge^{\bullet} \mathrm{Jet}^{\vee}(T_{\mathrm{ver}}^{\vee}E))$$

with differential given by contraction $Q = \langle \delta_{\mathrm{EL}}^{\infty} L, - \rangle$.

Derived variational *tri-complex* of $X = \mathbb{R}\text{Crit}_{\text{EL}}(\mathcal{L})$



To be a cocycle, these elements have to satisfy the following set of equations:

$$\begin{aligned}
 & \left\{ \begin{aligned} Q\Omega_n^{p,q} &= 0, \\ d_v\Omega_n^{p,q} + Q\Omega_{n-1}^{p,q+1} &= 0, \\ d_h\Omega_n^{p,q} + Q\Omega_{n-1}^{p+1,q} &= 0, \end{aligned} \right. \\
 & \left\{ \begin{aligned} d_v\Omega_{n-1}^{p,q+1} + Q\Omega_{n-2}^{p,q+2} &= 0, \\ d_h\Omega_{n-1}^{p,q+1} + d_v\Omega_{n-1}^{p+1,q} + Q\Omega_{n-2}^{p+1,q+1} &= 0, \\ d_h\Omega_{n-1}^{p+1,q} + Q\Omega_{n-2}^{p+2,q} &= 0, \end{aligned} \right. \\
 & \left\{ \begin{aligned} d_v\Omega_{n-2}^{p,q+2} + Q\Omega_{n-3}^{p,q+3} &= 0, \\ d_h\Omega_{n-2}^{p,q+2} + d_v\Omega_{n-2}^{p+1,q+1} + Q\Omega_{n-3}^{p+1,q+2} &= 0, \\ d_h\Omega_{n-2}^{p+1,q+1} + d_v\Omega_{n-2}^{p+2,q} + Q\Omega_{n-3}^{p+2,q+1} &= 0, \\ d_h\Omega_{n-2}^{p+2,q} + Q\Omega_{n-3}^{p+3,q} &= 0, \end{aligned} \right. \\
 & \vdots
 \end{aligned}$$

Transgression of shifted closed forms

Crucially, the following property holds still in the derived setting:

$$\mathbb{R}\mathrm{Crit}_{\mathrm{EL}}(\mathcal{L})_x \simeq \mathbb{R}\mathrm{Crit}(S)(\mathbb{D}_x)$$

at any point $x \in M$.

$$\begin{array}{ccc}
 \mathbb{R}\mathrm{Crit}_{\mathrm{EL}}(\mathcal{L})_x & \longrightarrow & (\mathrm{Jet}E)_x \\
 \swarrow \simeq & \downarrow & \searrow \simeq \\
 \mathbb{R}\mathrm{Crit}(S)(\mathbb{D}_x) & \longrightarrow & \Gamma(\mathbb{D}_x, E) \\
 \downarrow & \downarrow & \downarrow (\mathrm{d}_{\mathrm{dR}}S)|_{\mathbb{D}_x} \\
 & & (\mathrm{Jet}E)_x \longrightarrow (\mathrm{Jet}(T_{\mathrm{ver}}^\vee E))_x \\
 \downarrow & \swarrow \simeq & \downarrow & \searrow \simeq \\
 \Gamma(\mathbb{D}_x, E) & \longrightarrow & \Gamma(\mathbb{D}_x, T_{\mathrm{ver}}^\vee E)
 \end{array}$$

- Roughly, this tells us that there exists a "derived transgression":

$$\mathfrak{T}_M : \mathcal{A}^{\dim(M), q}(\mathbb{R}\mathrm{Crit}_{\mathrm{EL}}(\mathcal{L}), n) \longrightarrow \mathcal{A}^q(\mathbb{R}\mathrm{Crit}(S)(M), n).$$

from the derived Euler-Lagrange critical locus to the the critical locus of the action functional at M .

- Not too surprisingly, this derived transgression lifts to a map of closed forms

$$\mathfrak{T}_M : \mathcal{A}_{\mathrm{cl}}^{\dim(M), q}(\mathbb{R}\mathrm{Crit}_{\mathrm{EL}}(\mathcal{L}), n) \longrightarrow \mathcal{A}_{\mathrm{cl}}^q(\mathbb{R}\mathrm{Crit}(S)(M), n)$$

However, in the derived setting there is more!

- If $\partial M \simeq 0$ is trivial and $p \leq m$, we obtain a transgression map

$$\mathfrak{T}_M : \mathcal{A}_{\text{cl}}^{\dim(M)-p,q}(\mathbb{R}\text{Crit}_{\text{EL}}(\mathcal{L}), n) \longrightarrow \mathcal{A}_{\text{cl}}^q(\mathbb{R}\text{Crit}(S)(M), n-p).$$

- If $\partial M \not\simeq 0$ is not trivial and $p \leq m$, we obtain a transgression map

$$\mathfrak{T}_M : \mathcal{A}_{\text{cl}}^{\dim(M)-p,q}(\mathbb{R}\text{Crit}_{\text{EL}}(\mathcal{L}), n) \longrightarrow \mathcal{A}_{\text{BFV}}^q(\mathbb{R}\text{Crit}(S)(M), n-p),$$

where on the right-hand-side there is the ∞ -groupoids whose elements are couples

$$\omega \in \mathcal{A}_{\text{cl}}^q(\mathbb{R}\text{Crit}(S)(M))_{n-p} \quad \varpi \in \mathcal{A}_{\text{cl}}^q(\mathbb{R}\text{Crit}(S)(\partial M_{\text{th}}))_{n-p+1}$$

such that

$$\begin{aligned} (d_{\text{dR}} + Q)\omega + \pi_{\partial M}^* \varpi &= 0, \\ (d_{\text{dR}} + Q)\varpi &= 0. \end{aligned}$$

i.e. a shifted form ω whose failure to be closed amounts to the pullback of a closed form ϖ living on the boundary and 1 degree higher.

Canonical derived n -plectic structure of a classical field theory

Now, the derived Euler-Lagrange critical locus $\mathbb{R}\mathrm{Crit}_{\mathrm{EL}}(\mathcal{L})$

- comes with a canonical (-1) -shifted $(m, 2)$ -form Ω_{BV} ,
- inherits a 0 -shifted $(m - 1, 2)$ -form $\Omega_{\mathrm{BFV}} := p_{\mathrm{EL}}^* \Omega_{\mathrm{pre}}$ from $\mathrm{Jet}E$.

Canonical derived n -plectic structure of a classical field theory

Now, the derived Euler-Lagrange critical locus $\mathbb{R}\text{Crit}_{\text{EL}}(\mathcal{L})$

- comes with a canonical (-1) -shifted $(m, 2)$ -form Ω_{BV} ,
- inherits a 0 -shifted $(m - 1, 2)$ -form $\Omega_{\text{BFV}} := p_{\text{EL}}^* \Omega_{\text{pre}}$ from $\text{Jet}E$.

One can show that $\Omega_{\text{BFV}} + \Omega_{\text{BV}} \in Z^0 A_{\text{cl}}^{m-1,2}(\text{Crit}_{\text{EL}}(\mathcal{L}))$ is a closed form, i.e.

$$\begin{aligned} Q\Omega_{\text{BFV}} &= 0, \\ d_{\text{dR}}\Omega_{\text{BFV}} + Q\Omega_{\text{BV}} &= 0, \\ d_{\text{dR}}\Omega_{\text{BV}} &= 0. \end{aligned}$$

Example

$(\mathbb{R}\text{Crit}_{\text{EL}}(\mathcal{L}), \Omega_{\text{BFV}} + \Omega_{\text{BV}})$ is a 0 -shifted n -plectic structure with $n = \dim(M)$.

By derived transgression map of closed forms

$$\mathfrak{T}_M : \mathcal{A}_{\text{cl}}^{\dim(M)-1,2}(\mathbb{R}\text{Crit}_{\text{EL}}(\mathcal{L}), 0) \longrightarrow \mathcal{A}_{\text{BFV}}^2(\mathbb{R}\text{Crit}(S)(M), -1)$$

one makes contact with BV-BFV theory:

$$\begin{aligned} (d_{\text{dR}} + Q)\omega_{\text{BV}} + \pi_{\partial M}^* \varpi_{\text{BFV}} &= 0, \\ (d_{\text{dR}} + Q)\varpi_{\text{BFV}} &= 0. \end{aligned}$$

Extra: higher derived brackets?

- **Poisson structure:** bivector π_2 such that $[\pi_2, \pi_2] = 0$.

Poisson algebroid $\mathfrak{Pois}(X, \pi_2) = T_X^* \xrightarrow{\pi_2^b} T_X$ so that

$$\text{CE}(\mathfrak{Pois}(X, \pi_2)) = \left(\Gamma(X, \wedge^* T_X), d_{\text{CE}} = [\pi_2, -] \right)$$

"Derived" L_∞ -bracket:

$$\{f, g\} = [[\pi_2, f], g]$$

Extra: higher derived brackets?

- **Poisson structure:** bivector π_2 such that $[\pi_2, \pi_2] = 0$.

Poisson algebroid $\mathfrak{Pois}(X, \pi_2) = T_X^* \xrightarrow{\pi_2^b} T_X$ so that

$$\text{CE}(\mathfrak{Pois}(X, \pi_2)) = \left(\Gamma(X, \wedge^* T_X), d_{\text{CE}} = [\pi_2, -] \right)$$

"Derived" L_∞ -bracket:

$$\{f, g\} = [[\pi_2, f], g]$$

- **k -shifted Poisson structure:** formal sum $\pi = \pi_2 + \pi_3 + \pi_4 + \dots$ such that each π_p is a $(k + p - 2)$ -shifted p -vector and

$$Q\pi + \frac{1}{2}[\pi, \pi] = 0.$$

"Derived" Poisson algebroid $\mathfrak{Pois}(X, \pi)$ so that

$$\text{CE}(\mathfrak{Pois}(X, \pi)) = \left(\mathbb{R}\Gamma(X, \wedge^* T_X), d_{\text{CE}} = Q + [\pi, -] \right)$$

"Higher derived" L_∞ -bracket [Voronov 2004]:

$$\ell_1(f) = Qf, \quad \ell_p(f_1, f_2, \dots, f_p) = \text{Proj}[\dots [[\pi, f_1], f_2] \dots, f_p]$$

\Rightarrow Current work on Courant/Vinogradov version of this generalisation.

Table of Contents

- 1 Introduction
- 2 Formal derived smooth stacks
- 3 Ordinary n -plectic geometry
- 4 Derived n -plectic geometry
- 5 Outlook

- Setting to go beyond BV-quantisation
 - ▶ [Bunk, Sämann, Szabo], [Fiorenza, Sati, Schreiber]: higher geometric prequantisation of n -plectic structures and prequantum bundle n -gerbes
 - ▶ [Safronov]: geometric quantisation of derived symplectic structures in derived algebraic geometry via bundle k -gerbes

⇒ Beyond BV-quantisation by "higher derived" geometric (pre)quantisation?
- Setting to go beyond BV-BRST theory
 - ▶ Usually one would consider $\Omega^*(X, \mathfrak{g})$ with L_∞ -structure and take shifted cotangent bundle $T^*[-1]\Omega^*(X, \mathfrak{g})$
 - ▶ We can consider $\mathbf{Bun}_G^\nabla(X) := [X, \mathbf{BG}_{\text{conn}}]$ (or some concretification of this), and take derived critical locus $\mathbb{R}\text{Crit}(S)(M)$ for a given $S : \mathbf{Bun}_G^\nabla(X) \rightarrow \mathbb{R}$

⇒ Global geometric generalisation of BV-BRST theory?
- Investigate global and quantum aspects of dualities of string and M-theory

Thank you for your attention!

