

G_2 conifolds: A survey

Spiro Karigiannis

*Department of Pure Mathematics
University of Waterloo*

“Special Geometric Structures in Mathematics and Physics”
Universität Hamburg

12 September, 2014

Results include separate joint works with
Jason Lotay (University College London)
Dominic Joyce (University of Oxford).

Physics?

M-theory?

M-theory is an 11-dimensional theory that is “compactified” on a 7-dimensional manifold M^7 , which (for supersymmetry) admits a *parallel spinor*. Such manifolds are known as G_2 manifolds, and have Riemannian holonomy contained in the exceptional Lie group $G_2 \subseteq SO(7)$.

M-theory?

M-theory is an 11-dimensional theory that is “compactified” on a 7-dimensional manifold M^7 , which (for supersymmetry) admits a *parallel spinor*. Such manifolds are known as G_2 manifolds, and have Riemannian holonomy contained in the exceptional Lie group $G_2 \subseteq SO(7)$.

- G_2 manifolds are always Ricci-flat. They are 7-dimensional analogues of Calabi-Yau 3-folds, which are the 6-dimensional compactification spaces in 10-dimensional string theory.
- They possess 3-dimensional “instantons”: *associative submanifolds*, the analogue of J -holomorphic curves.
- They possess 4-dimensional “branes”: *coassociative submanifolds*, the analogue of special Lagrangian 3-folds.

Mirror Symmetry?

In type IIA/IIB string theory, very different Calabi-Yau 3-folds can determine the same physics – this is *mirror symmetry*.

Mirror Symmetry?

In type IIA/IIB string theory, very different Calabi-Yau 3-folds can determine the same physics – this is *mirror symmetry*.

- The Strominger–Yau–Zaslow conjecture describes a *differential geometric* explanation/construction of mirror symmetry, motivated by physical considerations (T-duality?).
- SYZ: a Calabi-Yau 3-fold X should admit a *fibration* $f : X \rightarrow B$ over a real 3-manifold B , whose generic fibre is a *special Lagrangian torus*. To obtain the mirror, one “dualizes the non-singular fibres”, then does something(?) to compactify and obtain “the mirror” \hat{X} .

Mirror Symmetry?

In type IIA/IIB string theory, very different Calabi-Yau 3-folds can determine the same physics – this is *mirror symmetry*.

- The Strominger–Yau–Zaslow conjecture describes a *differential geometric* explanation/construction of mirror symmetry, motivated by physical considerations (T-duality?).
- SYZ: a Calabi-Yau 3-fold X should admit a *fibration* $f : X \rightarrow B$ over a real 3-manifold B , whose generic fibre is a *special Lagrangian torus*. To obtain the mirror, one “dualizes the non-singular fibres”, then does something(?) to compactify and obtain “the mirror” \hat{X} .
- A notion of “mirror symmetry” should(?) also exist for G_2 manifolds. Work of Acharya and others suggests that a G_2 manifold M should admit a fibration $f : M \rightarrow B$ over a real 3-manifold B , whose generic fibres are *coassociative tori or $K3$'s*.

Mirror Symmetry?

In type IIA/IIB string theory, very different Calabi-Yau 3-folds can determine the same physics – this is *mirror symmetry*.

- The Strominger–Yau–Zaslow conjecture describes a *differential geometric* explanation/construction of mirror symmetry, motivated by physical considerations (T-duality?).
- SYZ: a Calabi-Yau 3-fold X should admit a *fibration* $f : X \rightarrow B$ over a real 3-manifold B , whose generic fibre is a *special Lagrangian torus*. To obtain the mirror, one “dualizes the non-singular fibres”, then does something(?) to compactify and obtain “the mirror” \hat{X} .
- A notion of “mirror symmetry” should(?) also exist for G_2 manifolds. Work of Acharya and others suggests that a G_2 manifold M should admit a fibration $f : M \rightarrow B$ over a real 3-manifold B , whose generic fibres are *coassociative tori or $K3$'s*.
- *No one really knows how to do this yet.*

Singularities necessary for good physics?

Singularities necessary for good physics?

M theory and Singularities of Exceptional Holonomy Manifolds

Bobby S. Acharya¹ and Sergei Gukov²

¹*Abdus Salam International Centre for Theoretical Physics,
Strada Costiera 11, 34100 Trieste, Italy.
bacharya@ictp.trieste.it*

²*Jefferson Physical Laboratory, Harvard University,
Cambridge, MA 02138, U.S.A.
gukov@schwinger.harvard.edu*

Abstract

M theory compactifications on G_2 holonomy manifolds, whilst supersymmetric, require *singularities* in order to obtain non-Abelian gauge groups, chiral fermions and other properties necessary for a realistic model of particle physics. We review recent progress in understanding the physics of such singularities. Our main aim is to describe the techniques which have been used to develop our understanding of *M* theory physics near these singularities. In parallel, we also describe similar sorts of singularities in $Spin(7)$ holonomy manifolds which correspond to the properties of three dimensional field theories. As an application, we review how various aspects of strongly coupled gauge theories, such as confinement, mass gap and non-perturbative phase transitions may be given a simple explanation in *M* theory.

arXiv:hep-th/0409191v2 21 Dec 2004

Singularities necessary for good physics?

M theory and Singularities of Exceptional Holonomy Manifolds

Bobby S. Acharya¹ and Sergei Gukov²

¹*Abdus Salam International Centre for Theoretical Physics,
Strada Costiera 11, 34100 Trieste, Italy.
bacharya@ictp.trieste.it*

²*Jefferson Physical Laboratory, Harvard University,
Cambridge, MA 02138, U.S.A.
gukov@schwinger.harvard.edu*

Abstract

M theory compactifications on G_2 holonomy manifolds, whilst supersymmetric, require *singularities* in order to obtain non-Abelian gauge groups, chiral fermions and other properties necessary for a realistic model of particle physics. We review recent progress in understanding the physics of such singularities. Our main aim is to describe the techniques which have been used to develop our understanding of M theory physics near these singularities. In parallel, we also describe similar sorts of singularities in $Spin(7)$ holonomy manifolds which correspond to the properties of three dimensional field theories. As an application, we review how various aspects of strongly coupled gauge theories, such as confinement, mass gap and non-perturbative phase transitions may be given a simple explanation in M theory.

- The simplest singularities that can be considered in physics are *isolated conical singularities*.

arXiv:hep-th/0409191v2 21 Dec 2004

G₂ manifolds

Manifolds with G₂ structure

Definition

Let M^7 be a smooth 7-manifold. A **G₂ structure** on M is a reduction of the structure group of the frame bundle from $GL(7, \mathbb{R})$ to $G_2 \subset SO(7)$.

Manifolds with G₂ structure

Definition

Let M^7 be a smooth 7-manifold. A **G₂ structure** on M is a reduction of the structure group of the frame bundle from $GL(7, \mathbb{R})$ to $G_2 \subset SO(7)$.

- A G₂ structure exists if and only if M is *orientable* and *spin*, which is equivalent to $w_1(M) = 0$ and $w_2(M) = 0$.
- A G₂ structure is encoded by a “non-degenerate” 3-form φ which nonlinearly determines a Riemannian metric g_φ and an orientation. We thus have a Hodge star operator $*_\varphi$ and dual 4-form $\psi = *_\varphi \varphi$.

Manifolds with G₂ structure

Definition

Let M^7 be a smooth 7-manifold. A **G₂ structure** on M is a reduction of the structure group of the frame bundle from $GL(7, \mathbb{R})$ to $G_2 \subset SO(7)$.

- A G₂ structure exists if and only if M is *orientable* and *spin*, which is equivalent to $w_1(M) = 0$ and $w_2(M) = 0$.
- A G₂ structure is encoded by a “non-degenerate” 3-form φ which nonlinearly determines a Riemannian metric g_φ and an orientation. We thus have a Hodge star operator $*_\varphi$ and dual 4-form $\psi = *_\varphi \varphi$.
- On a manifold (M, φ) with G₂ structure, each tangent space $T_p M$ can be canonically identified with the *imaginary octonions* $\mathbb{O} \cong \mathbb{R}^7$.

G₂ manifolds

Definition

Let (M, φ) be a manifold with G₂ structure. Let ∇ be the Levi-Civita connection of g_φ . We say that (M, φ) is a **G₂ manifold** if $\nabla\varphi = 0$. This is also called a **torsion-free** G₂ structure, where $T = \nabla\varphi$ is the torsion.

G₂ manifolds

Definition

Let (M, φ) be a manifold with G_2 structure. Let ∇ be the Levi-Civita connection of g_φ . We say that (M, φ) is a **G₂ manifold** if $\nabla\varphi = 0$. This is also called a **torsion-free** G_2 structure, where $T = \nabla\varphi$ is the torsion.

Properties of G_2 manifolds:

- The holonomy $\text{Hol}(g_\varphi)$ is contained in G_2 . If $\text{Hol}(g_\varphi) = G_2$, then (M, φ) is called an **irreducible** G_2 manifold. A *compact* G_2 manifold is irreducible if and only if $\pi_1(M)$ is finite.

G₂ manifolds

Definition

Let (M, φ) be a manifold with G₂ structure. Let ∇ be the Levi-Civita connection of g_φ . We say that (M, φ) is a **G₂ manifold** if $\nabla\varphi = 0$. This is also called a **torsion-free** G₂ structure, where $T = \nabla\varphi$ is the torsion.

Properties of G₂ manifolds:

- The holonomy $\text{Hol}(g_\varphi)$ is contained in G₂. If $\text{Hol}(g_\varphi) = \text{G}_2$, then (M, φ) is called an **irreducible** G₂ manifold. A *compact* G₂ manifold is irreducible if and only if $\pi_1(M)$ is finite.
- The metric g_φ is **Ricci-flat**.
- G₂ manifolds admit a parallel spinor. They play the role in M-theory that Calabi-Yau 3-folds play in string theory.

G₂ manifolds

Definition

Let (M, φ) be a manifold with G₂ structure. Let ∇ be the Levi-Civita connection of g_φ . We say that (M, φ) is a **G₂ manifold** if $\nabla\varphi = 0$. This is also called a **torsion-free** G₂ structure, where $T = \nabla\varphi$ is the torsion.

Properties of G₂ manifolds:

- The holonomy $\text{Hol}(g_\varphi)$ is contained in G₂. If $\text{Hol}(g_\varphi) = \text{G}_2$, then (M, φ) is called an **irreducible** G₂ manifold. A *compact* G₂ manifold is irreducible if and only if $\pi_1(M)$ is finite.
- The metric g_φ is **Ricci-flat**.
- G₂ manifolds admit a parallel spinor. They play the role in M-theory that Calabi-Yau 3-folds play in string theory.
- A G₂ structure is torsion-free if and only if $d\varphi = 0$ and $d*_\varphi\varphi = 0$. (Fernàndez–Gray, 1982.) Both φ and $*_\varphi\varphi$ are **calibrations**.

Comparison with Kähler and Calabi-Yau geometry

- G₂ manifolds are very similar to Kähler manifolds.
- Both admit **calibrated** *submanifolds* and *connections*.
- Both admit a Dolbeault-type decomposition of their cohomology, which implies restrictions on the topology.

Comparison with Kähler and Calabi-Yau geometry

- G₂ manifolds are very similar to Kähler manifolds.
- Both admit **calibrated** *submanifolds* and *connections*.
- Both admit a Dolbeault-type decomposition of their cohomology, which implies restrictions on the topology.
- **However**, unlike G₂ manifolds, *not all* Kähler manifolds are Ricci-flat. Those are the *Calabi-Yau* manifolds.
- By the Calabi-Yau theorem, we have a topological characterization of the Ricci-flat Kähler manifolds.
- We are still *very far* from knowing sufficient topological conditions for existence of a torsion-free G₂ structure.

G₂ geometry is more nonlinear

- In Kähler geometry, the $\partial\bar{\partial}$ lemma often reduces first order systems of PDEs to a single scalar equation.
- The natural PDEs which arise in G₂ geometry are usually first order **fully nonlinear systems**.

G₂ geometry is more nonlinear

- In Kähler geometry, the $\partial\bar{\partial}$ lemma often reduces first order systems of PDEs to a single scalar equation.
- The natural PDEs which arise in G₂ geometry are usually first order **fully nonlinear systems**.
- In Kähler geometry, the Kähler form ω and the complex structure J are essentially independent. Together they determine the metric g .
- Therefore, Kähler geometry can be thought of as 'decoupling' into complex geometry and symplectic geometry.

G₂ geometry is more nonlinear

- In Kähler geometry, the $\partial\bar{\partial}$ lemma often reduces first order systems of PDEs to a single scalar equation.
- The natural PDEs which arise in G₂ geometry are usually first order **fully nonlinear systems**.
- In Kähler geometry, the Kähler form ω and the complex structure J are essentially independent. Together they determine the metric g .
- Therefore, Kähler geometry can be thought of as 'decoupling' into complex geometry and symplectic geometry.
- **However**, if M admits a G₂ structure, the 3-form φ determines the metric g in a nonlinear way:

$$(u \lrcorner \varphi) \wedge (v \lrcorner \varphi) \wedge \varphi = C g_\varphi(u, v) \text{vol}_\varphi$$

- Thus, we cannot 'decouple' G₂ geometry in any way.

Examples of G₂ manifolds

Complete noncompact examples

- Bryant–Salamon (1989): these examples are total spaces of vector bundles $\Lambda_-^2(S^4)$, $\Lambda_-^2(\mathbb{C}\mathbb{P}^2)$, $\mathcal{S}(S^3)$; they are all **asymptotically conical**: far away from the base of the bundle, they “look like” *metric cones*.
- There exist many other complete examples with “nice” asymptotic behaviour at infinity, found by physicists.

Examples of G₂ manifolds

Complete noncompact examples

- Bryant–Salamon (1989): these examples are total spaces of vector bundles $\Lambda_-^2(S^4)$, $\Lambda_-^2(\mathbb{C}\mathbb{P}^2)$, $\mathcal{S}(S^3)$; they are all **asymptotically conical**: far away from the base of the bundle, they “look like” *metric cones*.
- There exist many other complete examples with “nice” asymptotic behaviour at infinity, found by physicists.
- These examples are all explicit **cohomogeneity one** G₂ manifolds — they have enough “symmetry” so that the nonlinear PDE reduces to a system of fully nonlinear ODEs, which can often be solved exactly.

Examples of G₂ manifolds

Complete noncompact examples

- Bryant–Salamon (1989): these examples are total spaces of vector bundles $\Lambda_-^2(S^4)$, $\Lambda_-^2(\mathbb{C}\mathbb{P}^2)$, $\mathcal{S}(S^3)$; they are all **asymptotically conical**: far away from the base of the bundle, they “look like” *metric cones*.
- There exist many other complete examples with “nice” asymptotic behaviour at infinity, found by physicists.
- These examples are all explicit **cohomogeneity one** G₂ manifolds — they have enough “symmetry” so that the nonlinear PDE reduces to a system of fully nonlinear ODEs, which can often be solved exactly.
- It can be shown (using the Bochner–Weitzenböck formula) that *compact* examples cannot have *any* symmetry. So the construction of compact examples is necessarily much more difficult.

Examples of G₂ manifolds

Compact examples

These are all found using **glueing techniques** — constructing an “almost” example and then proving there exists a genuine example by solving an elliptic nonlinear PDE.

Examples of G₂ manifolds

Compact examples

These are all found using **glueing techniques** — constructing an “almost” example and then proving there exists a genuine example by solving an elliptic nonlinear PDE.

- Joyce (1994) — analogue of the Kummer construction (glueing to resolve orbifold singularities)

Examples of G₂ manifolds

Compact examples

These are all found using **glueing techniques** — constructing an “almost” example and then proving there exists a genuine example by solving an elliptic nonlinear PDE.

- Joyce (1994) — analogue of the Kummer construction (glueing to resolve orbifold singularities)
- Kovalev (2000) — glueing asymptotically cylindrical manifolds together after “twisting”

Examples of G₂ manifolds

Compact examples

These are all found using **glueing techniques** — constructing an “almost” example and then proving there exists a genuine example by solving an elliptic nonlinear PDE.

- Joyce (1994) — analogue of the Kummer construction (glueing to resolve orbifold singularities)
- Kovalev (2000) — glueing asymptotically cylindrical manifolds together after “twisting”
- Corti–Haskins–Nördstom–Pacini (2012) — vast generalization of Kovalev construction

Examples of G₂ manifolds

Compact examples

These are all found using **glueing techniques** — constructing an “almost” example and then proving there exists a genuine example by solving an elliptic nonlinear PDE.

- Joyce (1994) — analogue of the Kummer construction (glueing to resolve orbifold singularities)
- Kovalev (2000) — glueing asymptotically cylindrical manifolds together after “twisting”
- Corti–Haskins–Nördstom–Pacini (2012) — vast generalization of Kovalev construction
- Joyce–Karigiannis (2014?) — glueing a 3-dimensional family of Eguchi–Hanson spaces

These compact constructions all invoke the following very general result.

These compact constructions all invoke the following very general result.

Theorem (Joyce, 1994)

Let M be a compact manifold with a *closed* G₂ structure φ such that the torsion is sufficiently small. (One needs good control of the L^{14} norm of the torsion and some other estimates.) Then there exists a *torsion-free* G₂ structure $\tilde{\varphi}$ close to φ in the C^0 norm, with $[\tilde{\varphi}] = [\varphi]$ in $H^3(M, \mathbb{R})$.

These compact constructions all invoke the following very general result.

Theorem (Joyce, 1994)

Let M be a compact manifold with a *closed* G₂ structure φ such that the torsion is sufficiently small. (One needs good control of the L^{14} norm of the torsion and some other estimates.) Then there exists a *torsion-free* G₂ structure $\tilde{\varphi}$ close to φ in the C^0 norm, with $[\tilde{\varphi}] = [\varphi]$ in $H^3(M, \mathbb{R})$.

Idea of the proof: Write $\tilde{\varphi} = \varphi + d\sigma$. Torsion-freeness of $\tilde{\varphi}$ is equivalent to $\Delta_d \sigma = Q(\sigma)$. Existence of a solution is established by iteration.

These compact constructions all invoke the following very general result.

Theorem (Joyce, 1994)

Let M be a compact manifold with a *closed* G₂ structure φ such that the torsion is sufficiently small. (One needs good control of the L^{14} norm of the torsion and some other estimates.) Then there exists a *torsion-free* G₂ structure $\tilde{\varphi}$ close to φ in the C^0 norm, with $[\tilde{\varphi}] = [\varphi]$ in $H^3(M, \mathbb{R})$.

Idea of the proof: Write $\tilde{\varphi} = \varphi + d\sigma$. Torsion-freeness of $\tilde{\varphi}$ is equivalent to $\Delta_d \sigma = Q(\sigma)$. Existence of a solution is established by iteration.

These constructions provide thousands of examples, but they are likely only a *very small part of the* “landscape.”

Moduli space of compact G₂ manifolds

- Let \mathcal{M} be the **moduli space** of torsion-free G₂ structures on M , modulo the appropriate notion of equivalence.

Moduli space of compact G₂ manifolds

- Let \mathcal{M} be the **moduli space** of torsion-free G₂ structures on M , modulo the appropriate notion of equivalence.

Theorem (Joyce, 1994)

The space \mathcal{M} is a smooth manifold, and is locally diffeomorphic to an open subset of the vector space $H^3(M, \mathbb{R})$.

Moduli space of compact G₂ manifolds

- Let \mathcal{M} be the **moduli space** of torsion-free G₂ structures on M , modulo the appropriate notion of equivalence.

Theorem (Joyce, 1994)

The space \mathcal{M} is a smooth manifold, and is locally diffeomorphic to an open subset of the vector space $H^3(M, \mathbb{R})$.

- Thus, deformations of compact G₂ manifolds are **unobstructed**, and the infinitesimal deformations have a topological interpretation.

Moduli space of compact G₂ manifolds

- Let \mathcal{M} be the **moduli space** of torsion-free G₂ structures on M , modulo the appropriate notion of equivalence.

Theorem (Joyce, 1994)

The space \mathcal{M} is a smooth manifold, and is locally diffeomorphic to an open subset of the vector space $H^3(M, \mathbb{R})$.

- Thus, deformations of compact G₂ manifolds are **unobstructed**, and the infinitesimal deformations have a topological interpretation.

The proof has the following ingredients:

- [1] Banach space implicit function theorem
- [2] Fredholm theory of elliptic operators
- [3] Hodge theory

Moduli space of compact G₂ manifolds

- Let \mathcal{M} be the **moduli space** of torsion-free G₂ structures on M , modulo the appropriate notion of equivalence.

Theorem (Joyce, 1994)

The space \mathcal{M} is a smooth manifold, and is locally diffeomorphic to an open subset of the vector space $H^3(M, \mathbb{R})$.

- Thus, deformations of compact G₂ manifolds are **unobstructed**, and the infinitesimal deformations have a topological interpretation.

The proof has the following ingredients:

- [1] Banach space implicit function theorem
- [2] Fredholm theory of elliptic operators
- [3] Hodge theory

Ingredients [2] and [3] require compactness of M , and thus need to be modified in any noncompact setting.

G_2 conifolds

G₂ cones

Definition

A **G₂ cone** is a 7-manifold $C = (0, \infty) \times \Sigma$, with Σ compact, and a torsion-free G₂ structure φ_C with induced metric

$$g_C = dr^2 + r^2 g_\Sigma \quad (\text{a Riemannian cone})$$

G₂ cones

Definition

A **G₂ cone** is a 7-manifold $C = (0, \infty) \times \Sigma$, with Σ compact, and a torsion-free G₂ structure φ_C with induced metric

$$g_C = dr^2 + r^2 g_\Sigma \quad (\text{a Riemannian cone})$$

- The *link* Σ of a G₂ cone C is necessarily a compact **strictly nearly Kähler** 6-manifold (also called a *Gray manifold*.)
- These are almost Hermitian manifolds (Σ, J, g, ω) with $c_1(\Sigma) = 0$, such that

$$d\omega = -3\text{Re}(\Omega) \quad d\text{Im}(\Omega) = 4 * \omega$$

G₂ cones

Definition

A **G₂ cone** is a 7-manifold $C = (0, \infty) \times \Sigma$, with Σ compact, and a torsion-free G₂ structure φ_C with induced metric

$$g_C = dr^2 + r^2 g_\Sigma \quad (\text{a Riemannian cone})$$

- The *link* Σ of a G₂ cone C is necessarily a compact **strictly nearly Kähler** 6-manifold (also called a *Gray manifold*.)
- These are almost Hermitian manifolds (Σ, J, g, ω) with $c_1(\Sigma) = 0$, such that

$$d\omega = -3\text{Re}(\Omega) \quad d\text{Im}(\Omega) = 4 * \omega$$

- There are **only three known compact examples**, all homogeneous, but there are expected to exist *many examples*.

Asymptotically conical (AC) G₂ manifolds

Definition

We say (N, φ_N) is an **AC G₂ manifold** of rate $\nu < 0$, asymptotic to the G₂ cone (C, φ_C) , if outside of a compact set $K \subseteq N$, we have $N \setminus K \cong (R, \infty) \times \Sigma$, and

$$\nabla^k(\varphi_N - \varphi_C) = O(r^{\nu-k}) \text{ as } r \rightarrow \infty \quad \forall k \geq 0$$

Asymptotically conical (AC) G₂ manifolds

Definition

We say (N, φ_N) is an **AC G₂ manifold** of rate $\nu < 0$, asymptotic to the G₂ cone (C, φ_C) , if outside of a compact set $K \subseteq N$, we have $N \setminus K \cong (R, \infty) \times \Sigma$, and

$$\nabla^k(\varphi_N - \varphi_C) = O(r^{\nu-k}) \text{ as } r \rightarrow \infty \quad \forall k \geq 0$$

- There are three known examples, the Bryant–Salamon manifolds, asymptotic to the three known G₂ cones.
- $\Lambda_-^2(S^4)$ and $\Lambda_-^2(\mathbb{C}\mathbb{P}^2)$ have rate $\nu = -4$.
- $\mathcal{S}(S^3)$ has rate $\nu = -3$.

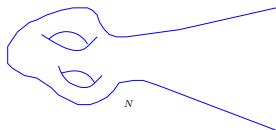
Asymptotically conical (AC) G₂ manifolds

Definition

We say (N, φ_N) is an **AC G₂ manifold** of rate $\nu < 0$, asymptotic to the G₂ cone (C, φ_C) , if outside of a compact set $K \subseteq N$, we have $N \setminus K \cong (R, \infty) \times \Sigma$, and

$$\nabla^k(\varphi_N - \varphi_C) = O(r^{\nu-k}) \text{ as } r \rightarrow \infty \quad \forall k \geq 0$$

- There are three known examples, the Bryant–Salamon manifolds, asymptotic to the three known G₂ cones.
- $\Lambda_-^2(S^4)$ and $\Lambda_-^2(\mathbb{C}\mathbb{P}^2)$ have rate $\nu = -4$.
- $\mathcal{S}(S^3)$ has rate $\nu = -3$.



Conically singular (CS) G₂ manifolds

Definition

Let \overline{M} be a topological space with $M = \overline{M} \setminus \{x_1, \dots, x_n\}$ a noncompact smooth 7-manifold. We say (M, φ_M) is an **CS G₂ manifold** of rate (ν_1, \dots, ν_n) , where $\nu_i > 0$, asymptotic to the G₂ cones (C_i, φ_{C_i}) , if outside of a compact set $K \subseteq M$, we have $M \setminus K \cong \bigsqcup_{i=1}^n (0, R) \times \Sigma_i$, and

$$\nabla^k(\varphi_M - \varphi_{C_i}) = O(r_i^{\nu_i - k}) \text{ as } r_i \rightarrow 0 \quad \forall k \geq 0, i = 1, \dots, n$$

where r_i is the distance to the vertex of C_i .

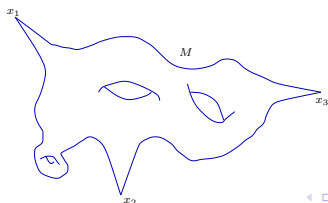
Conically singular (CS) G₂ manifolds

Definition

Let \overline{M} be a topological space with $M = \overline{M} \setminus \{x_1, \dots, x_n\}$ a noncompact smooth 7-manifold. We say (M, φ_M) is an **CS G₂ manifold** of rate (ν_1, \dots, ν_n) , where $\nu_i > 0$, asymptotic to the G₂ cones (C_i, φ_{C_i}) , if outside of a compact set $K \subseteq M$, we have $M \setminus K \cong \bigsqcup_{i=1}^n (0, R) \times \Sigma_i$, and

$$\nabla^k(\varphi_M - \varphi_{C_i}) = O(r_i^{\nu_i - k}) \text{ as } r_i \rightarrow 0 \quad \forall k \geq 0, i = 1, \dots, n$$

where r_i is the distance to the vertex of C_i .



Conically singular (CS) G_2 manifolds

- Physics of M-theory/supergravity requires compact CS G_2 manifolds.

Conically singular (CS) G_2 manifolds

- Physics of M-theory/supergravity requires compact CS G_2 manifolds.

Examples:

Conically singular (CS) G₂ manifolds

- Physics of M-theory/supergravity requires compact CS G₂ manifolds.

Examples:

- There are **no known examples**.

Conically singular (CS) G₂ manifolds

- Physics of M-theory/supergravity requires compact CS G₂ manifolds.

Examples:

- There are **no known examples**.
- They are expected to exist in abundance. (see below and next slide)

Conically singular (CS) G₂ manifolds

- Physics of M-theory/supergravity requires compact CS G₂ manifolds.

Examples:

- There are **no known examples**.
- They are expected to exist in abundance. (see below and next slide)
- Possible construction of CS G₂ manifolds by generalizing Joyce–Karigiannis glueing construction. (2015?)

Conically singular (CS) G_2 manifolds

- Physics of M-theory/supergravity requires compact CS G_2 manifolds.

Examples:

- There are **no known examples**.
- They are expected to exist in abundance. (see below and next slide)
- Possible construction of CS G_2 manifolds by generalizing Joyce–Karigiannis glueing construction. (2015?)
- CS G_2 manifolds should arise as **boundary points** in the moduli space of compact smooth G_2 manifolds, as *singular limits* of families of compact smooth G_2 manifolds.

Conically singular (CS) G₂ manifolds

- Physics of M-theory/supergravity requires compact CS G₂ manifolds.

Examples:

- There are **no known examples**.
- They are expected to exist in abundance. (see below and next slide)
- Possible construction of CS G₂ manifolds by generalizing Joyce–Karigiannis glueing construction. (2015?)
- CS G₂ manifolds should arise as **boundary points** in the moduli space of compact smooth G₂ manifolds, as *singular limits* of families of compact smooth G₂ manifolds.
- One way to show this, and thus to provide evidence for their likely existence, is to prove that they would *often* be **desingularizable** into families of compact smooth G₂ manifolds.

Conically singular (CS) G₂ manifolds

- Physics of M-theory/supergravity requires compact CS G₂ manifolds.

Examples:

- There are **no known examples**.
- They are expected to exist in abundance. (see below and next slide)
- Possible construction of CS G₂ manifolds by generalizing Joyce–Karigiannis glueing construction. (2015?)
- CS G₂ manifolds should arise as **boundary points** in the moduli space of compact smooth G₂ manifolds, as *singular limits* of families of compact smooth G₂ manifolds.
- One way to show this, and thus to provide evidence for their likely existence, is to prove that they would *often* be **desingularizable** into families of compact smooth G₂ manifolds.
- A way to desingularize them is to cut out a neighbourhood of the singular points, and **glue** in AC G₂ manifolds, such as the Bryant–Salamon examples.

Desingularization of CS G₂ manifolds

Theorem (Karigiannis, Geometry & Topology, 2009)

Let M be a CS G₂ manifold with isolated conical singularities x_1, \dots, x_n , modelled on G₂ cones C_1, \dots, C_n . Suppose that N_1, \dots, N_n are AC G₂ manifolds modelled on the same G₂ cones, with all rates $\nu_i \leq -3$.

Desingularization of CS G₂ manifolds

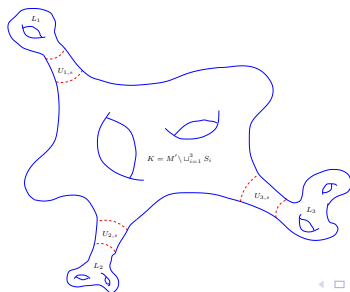
Theorem (Karigiannis, Geometry & Topology, 2009)

Let M be a CS G₂ manifold with isolated conical singularities x_1, \dots, x_n , modelled on G₂ cones C_1, \dots, C_n . Suppose that N_1, \dots, N_n are AC G₂ manifolds modelled on the same G₂ cones, with all rates $\nu_i \leq -3$. If a certain necessary topological condition (relating all the singular points) is satisfied, then the N_i 's can always be glued to $M \setminus \{x_1, \dots, x_n\}$ to obtain a smooth compact G₂ manifold.

Desingularization of CS G₂ manifolds

Theorem (Karigiannis, Geometry & Topology, 2009)

Let M be a CS G₂ manifold with isolated conical singularities x_1, \dots, x_n , modelled on G₂ cones C_1, \dots, C_n . Suppose that N_1, \dots, N_n are AC G₂ manifolds modelled on the same G₂ cones, with all rates $\nu_i \leq -3$. If a certain necessary topological condition (relating all the singular points) is satisfied, then the N_i 's can always be glued to $M \setminus \{x_1, \dots, x_n\}$ to obtain a smooth compact G₂ manifold.



Deformation theory of G₂ conifolds

- Understanding the *moduli space* of AC G₂ manifolds tells us something about **how many ways we can desingularize a CS G₂ manifold.**

Deformation theory of G₂ conifolds

- Understanding the *moduli space* of AC G₂ manifolds tells us something about **how many ways we can desingularize a CS G₂ manifold.**
- Understanding the *moduli space* of CS G₂ manifolds tells us something about **how much of the “boundary” of the moduli space of compact *smooth* G₂ manifolds consists of CS manifolds.**

Deformation theory of G₂ conifolds

- Understanding the *moduli space* of AC G₂ manifolds tells us something about **how many ways we can desingularize a CS G₂ manifold.**
- Understanding the *moduli space* of CS G₂ manifolds tells us something about **how much of the “boundary” of the moduli space of compact *smooth* G₂ manifolds consists of CS manifolds.**

Definition

Let M be a G₂ conifold of rate ν . Define \mathcal{M}_ν to be the *moduli space* of all torsion-free G₂ structures on M , asymptotic to the same G₂ cones at the ends, with the same rates ν_i , modulo the action of diffeomorphisms which preserve this condition.

Deformation theory of G₂ conifolds

- Understanding the *moduli space* of AC G₂ manifolds tells us something about **how many ways we can desingularize a CS G₂ manifold.**
- Understanding the *moduli space* of CS G₂ manifolds tells us something about **how much of the “boundary” of the moduli space of compact smooth G₂ manifolds consists of CS manifolds.**

Definition

Let M be a G₂ conifold of rate ν . Define \mathcal{M}_ν to be the *moduli space* of all torsion-free G₂ structures on M , asymptotic to the same G₂ cones at the ends, with the same rates ν_i , modulo the action of diffeomorphisms which preserve this condition.

There are natural maps $\Upsilon^k : H^k(M) \rightarrow \bigoplus_{i=1}^n H^k(\Sigma_i)$. Let $K_i(\lambda)$ be the space of *homogeneous* closed and coclosed 3-forms on C_i of rate λ .

Deformation theory of G_2 conifolds

Theorem (Karigiannis–Lotay, 2012)

For generic ν (away from a finite set of “critical rates”):

Deformation theory of G₂ conifolds

Theorem (Karigiannis–Lotay, 2012)

For generic ν (away from a finite set of “critical rates”):

- In the AC case with $\nu \in (-4, -\frac{5}{2})$, the moduli space \mathcal{M}_ν is a smooth manifold with $\dim \mathcal{M}_\nu$ equal to

$$\dim H_{CS}^3(M); \quad -4 < \nu < -3$$

$$\dim H_{CS}^3(M) + \text{rank}(\Upsilon^3); \quad -3 < \nu < -3 + \epsilon$$

$$\dim H_{CS}^3(M) + \text{rank}(\Upsilon^3) + \sum_{\lambda \in (-3, \nu)} \dim K(\lambda); \quad -3 + \epsilon < \nu < -\frac{5}{2}$$

Deformation theory of G₂ conifolds

Theorem (Karigiannis–Lotay, 2012)

For generic ν (away from a finite set of “critical rates”):

- In the AC case with $\nu \in (-4, -\frac{5}{2})$, the moduli space \mathcal{M}_ν is a smooth manifold with $\dim \mathcal{M}_\nu$ equal to

$$\dim H_{\text{CS}}^3(M); \quad -4 < \nu < -3$$

$$\dim H_{\text{CS}}^3(M) + \text{rank}(\Upsilon^3); \quad -3 < \nu < -3 + \epsilon$$

$$\dim H_{\text{CS}}^3(M) + \text{rank}(\Upsilon^3) + \sum_{\lambda \in (-3, \nu)} \dim K(\lambda); \quad -3 + \epsilon < \nu < -\frac{5}{2}$$

- In the AC case with $\nu < -4$, the moduli space may be obstructed, and its virtual dimension $\nu\text{-dim } \mathcal{M}_\nu$ is

$$\dim H_{\text{CS}}^3(M) - \text{rank}(\Upsilon^4); \quad -4 - \epsilon < \nu < -4$$

$$\dim H_{\text{CS}}^3(M) - \text{rank}(\Upsilon^4) - \sum_{\lambda \in (\nu, -4)} \dim K(\lambda); \quad \nu < -4 - \epsilon$$

Deformation theory of G₂ conifolds

Theorem (Karigiannis–Lotay, 2012)

For generic $\nu = (\nu_1, \dots, \nu_n)$:

Deformation theory of G₂ conifolds

Theorem (Karigiannis–Lotay, 2012)

For generic $\nu = (\nu_1, \dots, \nu_n)$:

- In the CS case, one must define a reduced moduli space $\check{\mathcal{M}}_\nu$, which in many cases equals \mathcal{M}_ν , because of a technical issue with the “slice theorem”. The reduced moduli space may be obstructed, and its virtual dimension $v\text{-dim } \check{\mathcal{M}}_\nu$ is

$$\dim H^3(M) - \text{rank}(\Upsilon^4) - \sum_{i=1}^n \sum_{\lambda \in (-3, \nu_i)} \dim K_i(\lambda)$$

Deformation theory of G₂ conifolds

Theorem (Karigiannis–Lotay, 2012)

For generic $\nu = (\nu_1, \dots, \nu_n)$:

- In the CS case, one must define a reduced moduli space $\check{\mathcal{M}}_\nu$, which in many cases equals \mathcal{M}_ν , because of a technical issue with the “slice theorem”. The reduced moduli space may be obstructed, and its virtual dimension $v\text{-dim } \check{\mathcal{M}}_\nu$ is

$$\dim H^3(M) - \text{rank}(\Upsilon^4) - \sum_{i=1}^n \sum_{\lambda \in (-3, \nu_i)} \dim K_i(\lambda)$$

- In all cases, the **obstruction space** is a space of forms on the cones, of degree $2 + 4$, which are in the kernel of $d + d^*$ but whose pure degree components are *not* independently closed and coclosed.

Deformation theory of G₂ conifolds

Theorem (Karigiannis–Lotay, 2012)

For generic $\nu = (\nu_1, \dots, \nu_n)$:

- In the CS case, one must define a reduced moduli space $\check{\mathcal{M}}_\nu$, which in many cases equals \mathcal{M}_ν , because of a technical issue with the “slice theorem”. The reduced moduli space may be obstructed, and its virtual dimension $v\text{-dim } \check{\mathcal{M}}_\nu$ is

$$\dim H^3(M) - \text{rank}(\Upsilon^4) - \sum_{i=1}^n \sum_{\lambda \in (-3, \nu_i)} \dim K_i(\lambda)$$

- In all cases, the **obstruction space** is a space of forms on the cones, of degree $2 + 4$, which are in the kernel of $d + d^*$ but whose pure degree components are *not* independently closed and coclosed.
- The proof uses the Lockhart–McOwen machinery of weighted Sobolev spaces and its associated Fredholm theory, plus new Hodge-theoretic results in this context, and other G₂ specific ingredients (surjectivity of Dirac operator, L^2 harmonic 1-forms are parallel, more ...)

Applications

- [1] The Bryant–Salamon examples are *rigid* as AC G_2 manifolds. That is, they have *no deformations*, apart from trivial scalings.

Applications

- [1] The Bryant–Salamon examples are *rigid* as AC G₂ manifolds. That is, they have *no deformations*, apart from trivial scalings.
- [2] If a CS G₂ manifold has singularities whose links are all from 2 of the 3 known examples (either $S^3 \times S^3$ or $\mathbb{C}P^3$) then the obstructions vanish, and $\check{\mathcal{M}}_\nu = \mathcal{M}_\nu$, so the CS moduli space is smooth.

Applications

- [1] The Bryant–Salamon examples are *rigid* as AC G₂ manifolds. That is, they have *no deformations*, apart from trivial scalings.
- [2] If a CS G₂ manifold has singularities whose links are all from 2 of the 3 known examples (either $S^3 \times S^3$ or $\mathbb{C}\mathbb{P}^3$) then the obstructions vanish, and $\check{\mathcal{M}}_\nu = \mathcal{M}_\nu$, so the CS moduli space is smooth. This remains true if we also allow singularities with links from the other known example, $SU(3)/T^2$, provided it has no strictly nearly Kähler deformations.

Applications

- [1] The Bryant–Salamon examples are *rigid* as AC G₂ manifolds. That is, they have *no deformations*, apart from trivial scalings.
- [2] If a CS G₂ manifold has singularities whose links are all from 2 of the 3 known examples (either $S^3 \times S^3$ or $\mathbb{C}\mathbb{P}^3$) then the obstructions vanish, and $\check{\mathcal{M}}_\nu = \mathcal{M}_\nu$, so the CS moduli space is smooth. This remains true if we also allow singularities with links from the other known example, $SU(3)/T^2$, provided it has no strictly nearly Kähler deformations.
- [3] In such cases, the dimension of the CS moduli space is *exactly one less* than the dimension of the moduli space of compact smooth desingularizations of the conifold, so **the CS singularities are the “highest dimensional stratum” of the boundary.**

Applications

- [1] The Bryant–Salamon examples are *rigid* as AC G₂ manifolds. That is, they have *no deformations*, apart from trivial scalings.
- [2] If a CS G₂ manifold has singularities whose links are all from 2 of the 3 known examples (either $S^3 \times S^3$ or $\mathbb{C}\mathbb{P}^3$) then the obstructions vanish, and $\check{\mathcal{M}}_\nu = \mathcal{M}_\nu$, so the CS moduli space is smooth. This remains true if we also allow singularities with links from the other known example, $SU(3)/T^2$, provided it has no strictly nearly Kähler deformations.
- [3] In such cases, the dimension of the CS moduli space is *exactly one less* than the dimension of the moduli space of compact smooth desingularizations of the conifold, so **the CS singularities are the “highest dimensional stratum” of the boundary**. That is, “most” of the ways the desingularized G₂ manifold can become singular is to develop such isolated conical singularities.

Applications

- [1] The Bryant–Salamon examples are *rigid* as AC G₂ manifolds. That is, they have *no deformations*, apart from trivial scalings.
- [2] If a CS G₂ manifold has singularities whose links are all from 2 of the 3 known examples (either $S^3 \times S^3$ or $\mathbb{C}\mathbb{P}^3$) then the obstructions vanish, and $\check{\mathcal{M}}_\nu = \mathcal{M}_\nu$, so the CS moduli space is smooth. This remains true if we also allow singularities with links from the other known example, $SU(3)/T^2$, provided it has no strictly nearly Kähler deformations.
- [3] In such cases, the dimension of the CS moduli space is *exactly one less* than the dimension of the moduli space of compact smooth desingularizations of the conifold, so **the CS singularities are the “highest dimensional stratum” of the boundary**. That is, “most” of the ways the desingularized G₂ manifold can become singular is to develop such isolated conical singularities.
- [4] Statements [2] and [3] will be true *in general* if certain conjectures about the spectrum of the Laplacian on forms are true for *all* compact strictly nearly Kähler 6-manifolds.

A new construction of compact G_2 manifolds

(which may possibly generalize to construct compact CS G_2 manifolds)

[Step 1] Construct an orbifold \widehat{M}

- Let $(N^6, g, \omega, \Omega, J)$ be a compact Calabi-Yau manifold admitting an *antiholomorphic isometric involution* τ :

$$\tau^*(g) = g, \quad \tau^*(\omega) = -\omega, \quad \tau^*(\Omega) = \overline{\Omega}, \quad \tau^*(J) = -J.$$

There exist many such manifolds. For example, on a quintic in $\mathbb{C}P^4$ with real coefficients, complex conjugation yields such an involution.

[Step 1] Construct an orbifold \widehat{M}

- Let $(N^6, g, \omega, \Omega, J)$ be a compact Calabi-Yau manifold admitting an *antiholomorphic isometric involution* τ :

$$\tau^*(g) = g, \quad \tau^*(\omega) = -\omega, \quad \tau^*(\Omega) = \overline{\Omega}, \quad \tau^*(J) = -J.$$

There exist many such manifolds. For example, on a quintic in $\mathbb{C}\mathbb{P}^4$ with real coefficients, complex conjugation yields such an involution.

- Define $M^7 = N^6 \times S^1$. Then

$$\varphi = \operatorname{Re}(\Omega) + d\theta \wedge \omega$$

is a torsion-free G_2 structure on M (with holonomy $SU(3) \subsetneq G_2$.)

[Step 1] Construct an orbifold \widehat{M}

- Let $(N^6, g, \omega, \Omega, J)$ be a compact Calabi-Yau manifold admitting an *antiholomorphic isometric involution* τ :

$$\tau^*(g) = g, \quad \tau^*(\omega) = -\omega, \quad \tau^*(\Omega) = \bar{\Omega}, \quad \tau^*(J) = -J.$$

There exist many such manifolds. For example, on a quintic in $\mathbb{C}\mathbb{P}^4$ with real coefficients, complex conjugation yields such an involution.

- Define $M^7 = N^6 \times S^1$. Then

$$\varphi = \operatorname{Re}(\Omega) + d\theta \wedge \omega$$

is a torsion-free G_2 structure on M (with holonomy $SU(3) \subsetneq G_2$.)

- Define $\sigma : M \rightarrow M$ by $\sigma(p, \theta) = (\tau(p), -\theta)$. Then σ is an involution of M such that $\sigma^*(\varphi) = \varphi$. The quotient space $\widehat{M} = M/\langle\sigma\rangle$ is a **G_2 orbifold**, with singularities locally of the form $\mathbb{R}^3 \times (\mathbb{C}^2/\{\pm 1\})$.

[Step 1] Construct an orbifold \widehat{M}

- Let $(N^6, g, \omega, \Omega, J)$ be a compact Calabi-Yau manifold admitting an *antiholomorphic isometric involution* τ :

$$\tau^*(g) = g, \quad \tau^*(\omega) = -\omega, \quad \tau^*(\Omega) = \bar{\Omega}, \quad \tau^*(J) = -J.$$

There exist many such manifolds. For example, on a quintic in $\mathbb{C}\mathbb{P}^4$ with real coefficients, complex conjugation yields such an involution.

- Define $M^7 = N^6 \times S^1$. Then

$$\varphi = \operatorname{Re}(\Omega) + d\theta \wedge \omega$$

is a torsion-free G_2 structure on M (with holonomy $SU(3) \subsetneq G_2$.)

- Define $\sigma : M \rightarrow M$ by $\sigma(p, \theta) = (\tau(p), -\theta)$. Then σ is an involution of M such that $\sigma^*(\varphi) = \varphi$. The quotient space $\widehat{M} = M/\langle\sigma\rangle$ is a **G_2 orbifold**, with singularities locally of the form $\mathbb{R}^3 \times (\mathbb{C}^2/\{\pm 1\})$.
- The singular set $L^3 = A^3 \times \{\pm 1\}$, where $A^3 = \operatorname{Fix}(\tau)$ is a compact **special Lagrangian submanifold** of N^6 , and L is totally geodesic in M .

[Step 2] Glue in a family of Eguchi-Hanson spaces

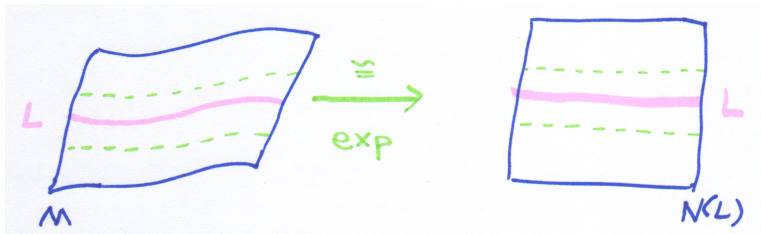
- We want to cut out a neighbourhood of the singular locus L in \widehat{M} and glue in a noncompact smooth manifold to get a smooth compact 7-manifold \widetilde{M} , which hopefully will admit a *closed* G_2 structure with *small enough torsion*, to to apply Joyce's existence theorem.

[Step 2] Glue in a family of Eguchi-Hanson spaces

- We want to cut out a neighbourhood of the singular locus L in \widehat{M} and glue in a noncompact smooth manifold to get a smooth compact 7-manifold \widetilde{M} , which hopefully will admit a *closed G_2 structure with small enough torsion*, to to apply Joyce's existence theorem.
- As L is compact in M , there exists an open neighbourhood $U \supset L$ of L in M which is diffeomorphic to a neighbourhood of the zero section in the normal bundle $N(L)$ of L in M , via the exponential map.

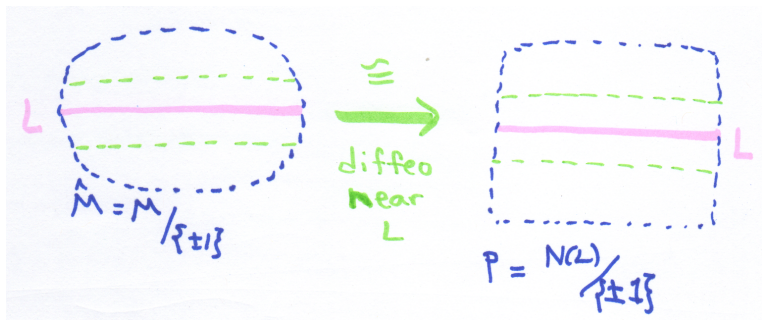
[Step 2] Glue in a family of Eguchi-Hanson spaces

- We want to cut out a neighbourhood of the singular locus L in \widehat{M} and glue in a noncompact smooth manifold to get a smooth compact 7-manifold \widetilde{M} , which hopefully will admit a *closed G_2 structure with small enough torsion*, to to apply Joyce's existence theorem.
- As L is compact in M , there exists an open neighbourhood $U \supset L$ of L in M which is diffeomorphic to a neighbourhood of the zero section in the normal bundle $N(L)$ of L in M , via the exponential map.

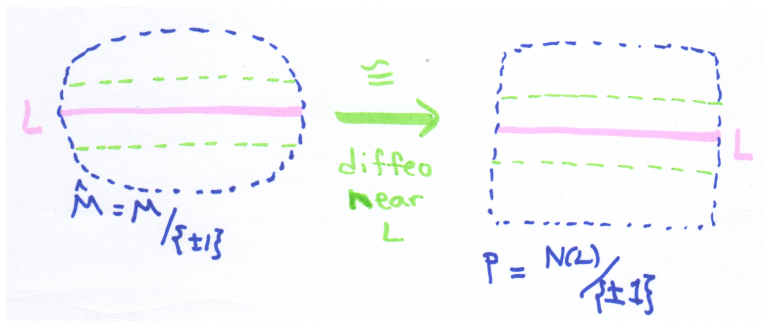


- The submanifold L is an **associative submanifold**. This implies that, given a nonvanishing 1-form α on L , the normal bundle $N(L)$ is actually a \mathbb{C}^2 **bundle** over L , and the above diffeomorphism descends to identify \widehat{M} with $P = N(L)/\{\pm 1\}$ near L .

- The submanifold L is an **associative submanifold**. This implies that, given a nonvanishing 1-form α on L , the normal bundle $N(L)$ is actually a \mathbb{C}^2 bundle over L , and the above diffeomorphism descends to identify \widehat{M} with $P = N(L)/\{\pm 1\}$ near L .



- The submanifold L is an **associative submanifold**. This implies that, given a nonvanishing 1-form α on L , the normal bundle $N(L)$ is actually a \mathbb{C}^2 bundle over L , and the above diffeomorphism descends to identify \widehat{M} with $P = N(L)/\{\pm 1\}$ near L .



- The fibres of $P = N(L)/\{\pm 1\}$ are $\mathbb{C}^2/\{\pm 1\}$. We resolve P to \widetilde{P} with a 'fibre-wise blow-up', replacing each fibre with $\widetilde{\mathbb{C}^2/\{\pm 1\}} \cong T^*S^2$.

- Each fibre T^*S^2 admits an $S^2 \times (0, \infty)$ family of *Eguchi-Hanson metrics* (holonomy $SU(2)$ metrics) that are parametrized by a choice of complex structure on $\mathbb{R}^4 = \mathbb{H}$ (a unit vector in \mathbb{R}^3) and a scaling.

- Each fibre T^*S^2 admits an $S^2 \times (0, \infty)$ family of *Eguchi-Hanson metrics* (holonomy $SU(2)$ metrics) that are parametrized by a choice of complex structure on $\mathbb{R}^4 = \mathbb{H}$ (a unit vector in \mathbb{R}^3) and a scaling.
- In fact $N(L)$ is trivial, so $P = N(L)/\{\pm 1\} \cong L \times (\mathbb{C}^2/\{\pm 1\})$. If in addition $L \cong T^3$, then we could take *any* E-H metric on T^*S^2 and the resolution $\tilde{P} \cong L \times T^*S^2$ would admit a torsion-free G_2 structure.

- Each fibre T^*S^2 admits an $S^2 \times (0, \infty)$ family of *Eguchi-Hanson metrics* (holonomy $SU(2)$ metrics) that are parametrized by a choice of complex structure on $\mathbb{R}^4 = \mathbb{H}$ (a unit vector in \mathbb{R}^3) and a scaling.
 - In fact $N(L)$ is trivial, so $P = N(L)/\{\pm 1\} \cong L \times (\mathbb{C}^2/\{\pm 1\})$. If in addition $L \cong T^3$, then we could take *any* E-H metric on T^*S^2 and the resolution $\tilde{P} \cong L \times T^*S^2$ would admit a torsion-free G_2 structure.
-
- In general, the singular set $L \not\cong T^3$, so there **does not exist** a canonical torsion-free G_2 structure on \tilde{P} .

- Each fibre T^*S^2 admits an $S^2 \times (0, \infty)$ family of *Eguchi-Hanson metrics* (holonomy $SU(2)$ metrics) that are parametrized by a choice of complex structure on $\mathbb{R}^4 = \mathbb{H}$ (a unit vector in \mathbb{R}^3) and a scaling.
 - In fact $N(L)$ is trivial, so $P = N(L)/\{\pm 1\} \cong L \times (\mathbb{C}^2/\{\pm 1\})$. If in addition $L \cong T^3$, then we could take *any* E-H metric on T^*S^2 and the resolution $\tilde{P} \cong L \times T^*S^2$ would admit a torsion-free G_2 structure.
-
- In general, the singular set $L \not\cong T^3$, so there **does not exist** a canonical torsion-free G_2 structure on \tilde{P} .
 - Since $S^2 \times (0, \infty) \cong \mathbb{R}^3 \setminus \{\mathbf{0}\}$, the particular choice of E-H metric in each fibre naturally corresponds to our nonvanishing 1-form α on L .

- Each fibre T^*S^2 admits an $S^2 \times (0, \infty)$ family of *Eguchi-Hanson metrics* (holonomy $SU(2)$ metrics) that are parametrized by a choice of complex structure on $\mathbb{R}^4 = \mathbb{H}$ (a unit vector in \mathbb{R}^3) and a scaling.
- In fact $N(L)$ is trivial, so $P = N(L)/\{\pm 1\} \cong L \times (\mathbb{C}^2/\{\pm 1\})$. If in addition $L \cong T^3$, then we could take *any* E-H metric on T^*S^2 and the resolution $\tilde{P} \cong L \times T^*S^2$ would admit a torsion-free G_2 structure.

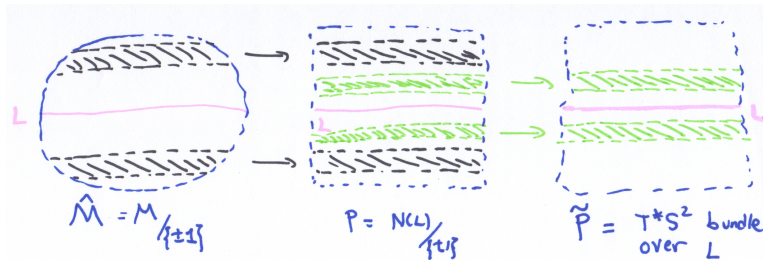
- In general, the singular set $L \not\cong T^3$, so there **does not exist** a canonical torsion-free G_2 structure on \tilde{P} .
- Since $S^2 \times (0, \infty) \cong \mathbb{R}^3 \setminus \{\mathbf{0}\}$, the particular choice of E-H metric in each fibre naturally corresponds to our nonvanishing 1-form α on L .
- We can use α to construct a closed G_2 structure $\varphi_{\tilde{P}}$ on \tilde{P} with small torsion, but for the torsion to have any chance of being small enough, **it is necessary that $d\alpha = 0$ and $d^*\alpha = 0$** . For now, let us assume that we have such a nowhere vanishing harmonic 1-form α .

[Step 3] Construct a compact smooth manifold \tilde{M}

- We construct a compact smooth manifold \tilde{M} as follows. Far from the zero section, identify P with \hat{M} using the *exponential map*. Close to the zero section, identify P with \tilde{P} using the *resolution map*.

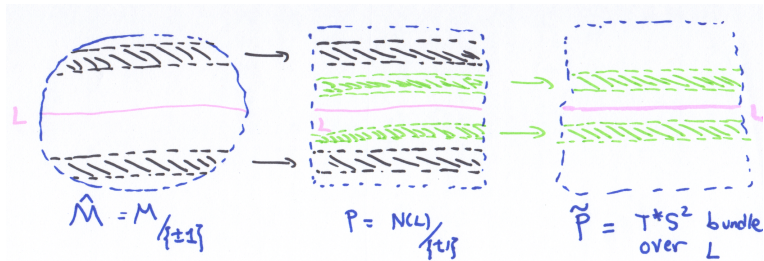
[Step 3] Construct a compact smooth manifold \tilde{M}

- We construct a compact smooth manifold \tilde{M} as follows. Far from the zero section, identify P with \hat{M} using the *exponential map*. Close to the zero section, identify P with \tilde{P} using the *resolution map*.



[Step 3] Construct a compact smooth manifold \tilde{M}

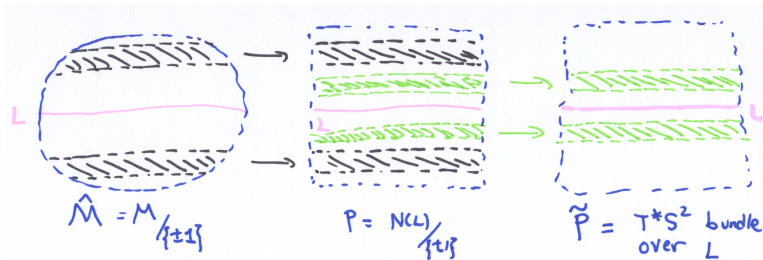
- We construct a compact smooth manifold \tilde{M} as follows. Far from the zero section, identify P with \hat{M} using the *exponential map*. Close to the zero section, identify P with \tilde{P} using the *resolution map*.



- There is a “canonical” G_2 structure $\bar{\varphi}$ on P obtained by taking the constant term in an expansion of $\varphi_{\hat{M}}$ in powers of t , the distance to L .

[Step 3] Construct a compact smooth manifold \tilde{M}

- We construct a compact smooth manifold \tilde{M} as follows. Far from the zero section, identify P with \hat{M} using the *exponential map*. Close to the zero section, identify P with \tilde{P} using the *resolution map*.



- There is a “canonical” G_2 structure $\bar{\varphi}$ on P obtained by taking the constant term in an expansion of $\varphi_{\hat{M}}$ in powers of t , the distance to L .
- We want to construct a closed G_2 structure $\tilde{\varphi}$ on \tilde{M} by interpolating between $\varphi_{\hat{M}}$ and $\varphi_{\tilde{P}}$ using $\bar{\varphi}$. We use the metric \bar{g} of $\bar{\varphi}$ to measure the torsion of $\tilde{\varphi}$, since we cannot compare \hat{M} and \tilde{P} directly.

- In fact, the G_2 structures $\bar{\varphi}$ on P and $\varphi_{\tilde{P}}$ on \tilde{P} are *not closed*, so these have to be slightly modified, using smooth cut-off functions, to “closed versions” before we can construct $\tilde{\varphi}$ on \tilde{M} by interpolation.

- In fact, the G_2 structures $\bar{\varphi}$ on P and $\varphi_{\tilde{P}}$ on \tilde{P} are *not closed*, so these have to be slightly modified, using smooth cut-off functions, to “closed versions” before we can construct $\tilde{\varphi}$ on \tilde{M} by interpolation.
- More significantly, however, is that the torsion of $\tilde{\varphi}$ is *always too big* to be able to apply Joyce’s theorem, even under the assumption of the existence of a nowhere vanishing harmonic 1-form α on L .

- In fact, the G_2 structures $\bar{\varphi}$ on P and $\varphi_{\tilde{P}}$ on \tilde{P} are *not closed*, so these have to be slightly modified, using smooth cut-off functions, to “closed versions” before we can construct $\tilde{\varphi}$ on \tilde{M} by interpolation.
- More significantly, however, is that the torsion of $\tilde{\varphi}$ is *always too big* to be able to apply Joyce’s theorem, even under the assumption of the existence of a nowhere vanishing harmonic 1-form α on L .
- *This does not happen in the Joyce or Kovalev/C-H-N-P constructions.*

- In fact, the G_2 structures $\bar{\varphi}$ on P and $\varphi_{\tilde{P}}$ on \tilde{P} are *not closed*, so these have to be slightly modified, using smooth cut-off functions, to “closed versions” before we can construct $\tilde{\varphi}$ on \tilde{M} by interpolation.
 - More significantly, however, is that the torsion of $\tilde{\varphi}$ is *always too big* to be able to apply Joyce’s theorem, even under the assumption of the existence of a nowhere vanishing harmonic 1-form α on L .
 - *This does not happen in the Joyce or Kovalev/C-H-N-P constructions.*
-
- The major problem is that the space \tilde{P} that we are “glueing in” does not have a natural torsion-free G_2 structure.

- In fact, the G_2 structures $\bar{\varphi}$ on P and $\varphi_{\tilde{P}}$ on \tilde{P} are *not closed*, so these have to be slightly modified, using smooth cut-off functions, to “closed versions” before we can construct $\tilde{\varphi}$ on \tilde{M} by interpolation.
 - More significantly, however, is that the torsion of $\tilde{\varphi}$ is *always too big* to be able to apply Joyce’s theorem, even under the assumption of the existence of a nowhere vanishing harmonic 1-form α on L .
 - *This does not happen in the Joyce or Kovalev/C-H-N-P constructions.*
-
- The major problem is that the space \tilde{P} that we are “glueing in” does not have a natural torsion-free G_2 structure.
 - Also, the fact that we need to introduce an “intermediary” manifold with G_2 structure $(P, \bar{\varphi})$ and use its metric \bar{g} to measure the size of the torsion creates additional complications. The G_2 structure $\bar{\varphi}$ is not a priori close enough to φ_M .

- In fact, the G_2 structures $\bar{\varphi}$ on P and $\varphi_{\tilde{P}}$ on \tilde{P} are *not closed*, so these have to be slightly modified, using smooth cut-off functions, to “closed versions” before we can construct $\tilde{\varphi}$ on \tilde{M} by interpolation.
 - More significantly, however, is that the torsion of $\tilde{\varphi}$ is *always too big* to be able to apply Joyce’s theorem, even under the assumption of the existence of a nowhere vanishing harmonic 1-form α on L .
 - *This does not happen in the Joyce or Kovalev/C-H-N-P constructions.*
-
- The major problem is that the space \tilde{P} that we are “glueing in” does not have a natural torsion-free G_2 structure.
 - Also, the fact that we need to introduce an “intermediary” manifold with G_2 structure $(P, \bar{\varphi})$ and use its metric \bar{g} to measure the size of the torsion creates additional complications. The G_2 structure $\bar{\varphi}$ is not a priori close enough to φ_M .
 - We need to perform two *corrections* to solve these problems.

[Step 4] 1st correction: bend horizontal and vertical

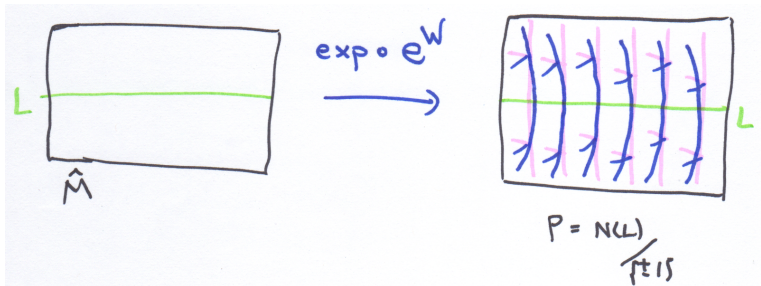
- We begin with the easier correction: modifying the identification between M and $N(L)$ so that the canonical G_2 structure $\bar{\varphi}$ on $P = N(L)/\{\pm 1\}$ is close enough to φ_M on \hat{M} .

[Step 4] 1st correction: bend horizontal and vertical

- We begin with the easier correction: modifying the identification between M and $N(L)$ so that the canonical G_2 structure $\bar{\varphi}$ on $P = N(L)/\{\pm 1\}$ is close enough to φ_M on \hat{M} .
- We can change the connection on $N(L)$ to “bend” the horizontal spaces and we can precompose the exponential mapping by a diffeomorphism of M generated by an appropriately chosen vector field W to “bend” the vertical directions as well.

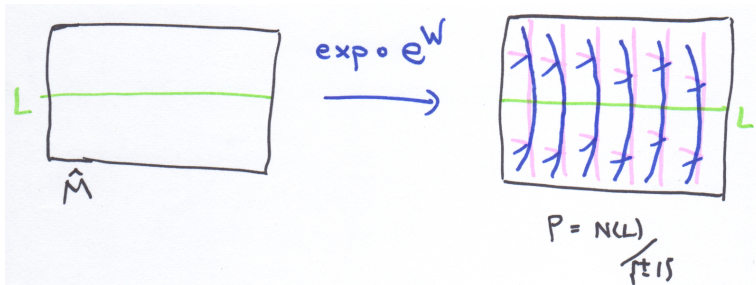
[Step 4] 1st correction: bend horizontal and vertical

- We begin with the easier correction: modifying the identification between M and $N(L)$ so that the canonical G_2 structure $\bar{\varphi}$ on $P = N(L)/\{\pm 1\}$ is close enough to φ_M on \hat{M} .
- We can change the connection on $N(L)$ to “bend” the horizontal spaces and we can precompose the exponential mapping by a diffeomorphism of M generated by an appropriately chosen vector field W to “bend” the vertical directions as well.



[Step 4] 1st correction: bend horizontal and vertical

- We begin with the easier correction: modifying the identification between M and $N(L)$ so that the canonical G_2 structure $\bar{\varphi}$ on $P = N(L)/\{\pm 1\}$ is close enough to φ_M on \hat{M} .
- We can change the connection on $N(L)$ to “bend” the horizontal spaces and we can precompose the exponential mapping by a diffeomorphism of M generated by an appropriately chosen vector field W to “bend” the vertical directions as well.



- These can in fact be chosen to make $\bar{\varphi}$ close enough to φ_M .

[Step 5] 2nd correction: solving a PDE on E-H space

- We also need to modify the G_2 structure $\varphi_{\tilde{P}}$ on \tilde{P} in order to make the torsion of $\tilde{\varphi}$ on \tilde{M} small enough to apply Joyce's theorem.

[Step 5] 2nd correction: solving a PDE on E-H space

- We also need to modify the G_2 structure $\varphi_{\tilde{P}}$ on \tilde{P} in order to make the torsion of $\tilde{\varphi}$ on \tilde{M} small enough to apply Joyce's theorem.
- To do this, we need to be able to *solve an elliptic PDE on the noncompact Eguchi-Hanson space T^*S^2* of the form

$$(d + d^*)\eta = \sigma$$

for some mixed-degree form σ given by the original G_2 structure $\varphi_{\tilde{P}}$.

[Step 5] 2nd correction: solving a PDE on E-H space

- We also need to modify the G_2 structure $\varphi_{\tilde{P}}$ on \tilde{P} in order to make the torsion of $\tilde{\varphi}$ on \tilde{M} small enough to apply Joyce's theorem.
- To do this, we need to be able to *solve an elliptic PDE on the noncompact Eguchi-Hanson space T^*S^2* of the form

$$(d + d^*)\eta = \sigma$$

for some mixed-degree form σ given by the original G_2 structure $\varphi_{\tilde{P}}$.

- This is done using Lockhart–McOwen theory of Fredholm operators on noncompact manifolds with “well-behaved” geometry at infinity.

[Step 5] 2nd correction: solving a PDE on E-H space

- We also need to modify the G_2 structure $\varphi_{\tilde{P}}$ on \tilde{P} in order to make the torsion of $\tilde{\varphi}$ on \tilde{M} small enough to apply Joyce's theorem.
- To do this, we need to be able to *solve an elliptic PDE on the noncompact Eguchi-Hanson space T^*S^2* of the form

$$(d + d^*)\eta = \sigma$$

for some mixed-degree form σ given by the original G_2 structure $\varphi_{\tilde{P}}$.

- This is done using Lockhart–McOwen theory of Fredholm operators on noncompact manifolds with “well-behaved” geometry at infinity.
- The theory says that such an equation can be solved if and only if σ has appropriate asymptotic behaviour at infinity, which it does.

Remarks on the construction

- Our construction is more general. We can take any G_2 manifold M admitting an involution σ such that $\sigma^*(\varphi) = \varphi$. Then $L = \text{Fix}(\sigma)$ is an associative submanifold and everything proceeds as before.

Remarks on the construction

- Our construction is more general. We can take any G_2 manifold M admitting an involution σ such that $\sigma^*(\varphi) = \varphi$. Then $L = \text{Fix}(\sigma)$ is an associative submanifold and everything proceeds as before.
- Choosing $M = N^6 \times S^1$ allows us to explicitly compute examples. These examples are very likely still only a small part of the landscape.

Remarks on the construction

- Our construction is more general. We can take any G_2 manifold M admitting an involution σ such that $\sigma^*(\varphi) = \varphi$. Then $L = \text{Fix}(\sigma)$ is an associative submanifold and everything proceeds as before.
- Choosing $M = N^6 \times S^1$ allows us to explicitly compute examples. These examples are very likely still only a small part of the landscape.

In general, we cannot guarantee that the submanifold L will admit a nowhere vanishing harmonic 1-form α . The metric on L is induced from the Calabi-Yau metric on N , which we do not know explicitly.

Remarks on the construction

- Our construction is more general. We can take any G_2 manifold M admitting an involution σ such that $\sigma^*(\varphi) = \varphi$. Then $L = \text{Fix}(\sigma)$ is an associative submanifold and everything proceeds as before.
- Choosing $M = N^6 \times S^1$ allows us to explicitly compute examples. These examples are very likely still only a small part of the landscape.

In general, we cannot guarantee that the submanifold L will admit a nowhere vanishing harmonic 1-form α . The metric on L is induced from the Calabi-Yau metric on N , which we do not know explicitly.

However, if N is near the “large complex structure limit” of the moduli space, from mirror symmetry arguments we expect it to contain a special Lagrangian torus that is *close to being flat*, so it will admit such 1-forms.

- Generically, a harmonic 1-form α on L has isolated zeroes. Then we can resolve M to \tilde{M} except for a finite number of singular points. In fact, near the singular points, \tilde{M} is *topologically* a cone over $\mathbb{C}P^3$.

- Generically, a harmonic 1-form α on L has isolated zeroes. Then we can resolve M to \tilde{M} except for a finite number of singular points. In fact, near the singular points, \tilde{M} is *topologically* a cone over $\mathbb{C}\mathbb{P}^3$.

Recall that there *is* a G_2 cone whose link is $\mathbb{C}\mathbb{P}^3$.

- Generically, a harmonic 1-form α on L has isolated zeroes. Then we can resolve M to \tilde{M} except for a finite number of singular points. In fact, near the singular points, \tilde{M} is *topologically* a cone over $\mathbb{C}P^3$.

Recall that there *is* a G_2 cone whose link is $\mathbb{C}P^3$.

- We would like to prove that in this case we can do a further perturbation to construct a *compact CS G_2 manifold*. This is (partially) what physicists need to incorporate matter into M-theory.

- Generically, a harmonic 1-form α on L has isolated zeroes. Then we can resolve M to \tilde{M} except for a finite number of singular points. In fact, near the singular points, \tilde{M} is *topologically* a cone over $\mathbb{C}P^3$.

Recall that there *is* a G_2 cone whose link is $\mathbb{C}P^3$.

- We would like to prove that in this case we can do a further perturbation to construct a *compact CS G_2 manifold*. This is (partially) what physicists need to incorporate matter into M-theory.
- To do this, we need: (i) a version of Joyce's existence theorem for such manifolds; (ii) to understand how the Eguchi-Hanson metric is analytically related to the G_2 cone as the E-H parameter goes to zero.

- Generically, a harmonic 1-form α on L has isolated zeroes. Then we can resolve M to \tilde{M} except for a finite number of singular points. In fact, near the singular points, \tilde{M} is *topologically* a cone over $\mathbb{C}\mathbb{P}^3$.

Recall that there *is* a G_2 cone whose link is $\mathbb{C}\mathbb{P}^3$.

- We would like to prove that in this case we can do a further perturbation to construct a *compact CS G_2 manifold*. This is (partially) what physicists need to incorporate matter into M-theory.
- To do this, we need: (i) a version of Joyce's existence theorem for such manifolds; (ii) to understand how the Eguchi-Hanson metric is analytically related to the G_2 cone as the E-H parameter goes to zero.
- These would be the first such examples. If this can be done, then one can use my theorem (2009) to *desingularize further* and obtain a compact smooth G_2 manifold.

- Generically, a harmonic 1-form α on L has isolated zeroes. Then we can resolve M to \tilde{M} except for a finite number of singular points. In fact, near the singular points, \tilde{M} is *topologically* a cone over $\mathbb{C}\mathbb{P}^3$.

Recall that there *is* a G_2 cone whose link is $\mathbb{C}\mathbb{P}^3$.

- We would like to prove that in this case we can do a further perturbation to construct a *compact CS G_2 manifold*. This is (partially) what physicists need to incorporate matter into M-theory.
- To do this, we need: (i) a version of Joyce's existence theorem for such manifolds; (ii) to understand how the Eguchi-Hanson metric is analytically related to the G_2 cone as the E-H parameter goes to zero.
- These would be the first such examples. If this can be done, then one can use my theorem (2009) to *desingularize further* and obtain a compact smooth G_2 manifold.

This is work in progress, with Jason Lotay.
We have done (i). We are working on (ii).

Thank you for your attention.