

# Type Theory and the Opetopes

## HDACT - Ljubljana

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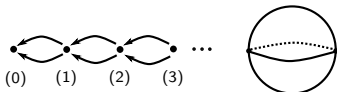
# Outline

- 1 What are the Opetopes?
- 2 Formalizing the Definition
- 3 Notation and Implementation
- 4 The Opetopes and Type Theory

# Shape Categories

Definitions of higher categories typically begin with the selection of a shape to represent higher dimensional cells:

- For example, there's the globe category  $\mathbb{G}^{op}$ :

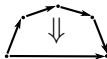


- We've got the simplicial category  $\Delta^{op}$ :



- But there's also the category of opetopes  $\mathcal{O}$ :

???



# The Idea of Opetopes

The two main principles behind the definition of the opetopes are the following:

## The Informal Version

- 1 Cells will be allowed to have many sources (input faces), but only a single target (output face)
- 2 Cells of dimension  $n + 1$  should be in bijection with *pasting diagrams* in dimension  $n$ , that is, all possible ways of attaching cells by gluing compatible sources and targets

We think of the process of turning a given pasting diagram into a cell as *extruding it* into the next dimension up.

## Low Dimensions

- In dimension 0, we have a point. It has no source and no target.

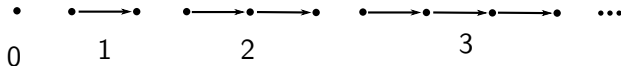


- The only way to arrange a family of points, gluing sources to targets is to simply have a single point. Points do not cohere in any meaningful way.
- Extending our unique 0-dimensional pasting diagram gives us the unique 1-dimensional cell, the arrow.

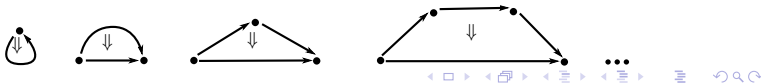


## Low Dimensions (cont'd)

- Now in dimension 1, we have the arrow: it has a single source and a single target.
- What are all the ways of coherently gluing sources to targets in a collection of arrows?
- There are an  $\mathbb{N}$ 's worth:

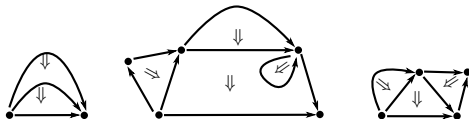


- Now we extrude each pasting diagram into the next dimension, and give it an “appropriate” target. In the case at hand, we have only one choice: the arrow.
- So our two cells look like this:

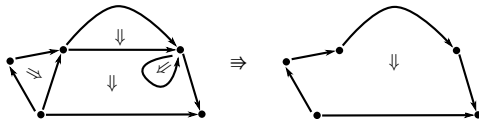


## Low Dimensions (cont'd)

- Here are some 2-dimensional pasting diagrams:

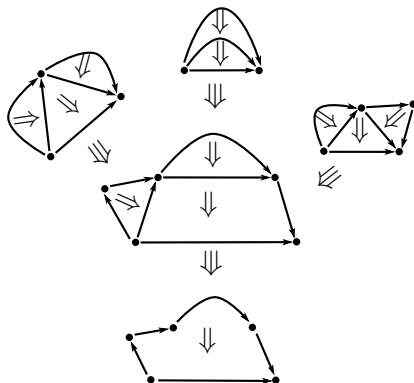


- And an example 3-dimensional cell:



## Low Dimensions (cont'd)

And finally a 3-pasting diagram:





# Opetopes from Polynomial Functors

- 1 How can we make this intuitive definition precise?
- 2 One of the simplest ways to do this (due to Kock, Joyal, Batanin and Mascari) is to realize these shapes as a canonical sequence *polynomial functors*
- 3 These have different names in the computer science community: inductive families, indexed containers, indexed  $W$ -types, . . .

# Polynomial Functors

## Definition

A *polynomial*  $P$  is a diagram of sets

$$\begin{array}{ccccc} & & E & \xrightarrow{p} & B & & \\ & \swarrow t & & & & \searrow r & \\ I & & & & & & I \end{array}$$

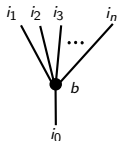
Any polynomial determines a functor  $\llbracket P \rrbracket : \mathcal{Set}/I \rightarrow \mathcal{Set}/I$  (its *extension*) defined for an  $I$ -Set  $X \rightarrow I$  by the formula:

$$\llbracket P \rrbracket(X) = \sum_{b \in B} \prod_{p \in E_b} X_{t(p)}$$

(Lower subscripts indicate the fibers of appropriate maps.)

## Graphical Interpretation

- It's useful to represent the elements  $b \in B$  as *corollas*



- We can then picture the set  $\llbracket P \rrbracket(X)$  as the collection of such corollas labelled with elements from  $X$  of the correct type:

$$\llbracket P \rrbracket(X) = \left\{ \begin{array}{c} x_1 \quad x_2 \quad x_3 \quad \dots \quad x_n \\ \diagup \quad \diagdown \quad \diagup \quad \dots \quad \diagdown \\ \bullet \\ | \\ i_0 \end{array} \right\}_{b \in B}$$

That is,  $t(x_k) = i_k$ .

## Useful Special Cases

- Write  $1_I$  for the terminal object of  $\mathcal{Set}/I$ . Then it is easily seen that  $\llbracket P \rrbracket(1_I) = B$ . Graphically:

$$\llbracket P \rrbracket(1_I) = \left\{ \begin{array}{c} i_1 \quad i_2 \quad i_3 \quad \dots \quad i_n \\ \diagdown \quad \diagdown \quad \diagdown \quad \dots \quad \diagup \\ \bullet \\ | \\ i_0 \end{array} \right\} \quad b \in B$$

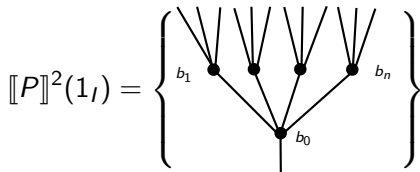
- For the initial object, we have

$$\llbracket P \rrbracket(\emptyset) = \left\{ \begin{array}{c} \bullet \\ | \\ i_0 \end{array} \right\} \quad b$$

i.e., the set of constructors with no places.

## Useful Special Cases (cont'd)

- By iterating the functor, we generate trees: for example,  $\llbracket P \rrbracket^2(1_I) = \llbracket P \rrbracket(B)$  is the set of two leveled trees

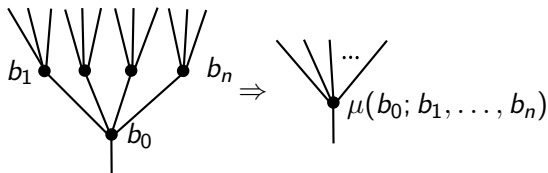


# Monads

- When is the extension of an indexed container a monad?
- In particular, we would need to have a map

$$\mu_1 : \llbracket P \rrbracket^2(1_I) \rightarrow \llbracket P \rrbracket(1_I) = B$$

- We can view this as a way to compose two-levelled trees:



- We say the monad is *cartesian* if the places of the multiplied constructor are in bijection with the leaves of the two-level tree (and their types match)

# The Free Monad

- We can freely generate a monad from any polynomial, and moreover, this functor is again the extension of a polynomial
- Write

$$tr(P) = \bigcup_{n \rightarrow \infty} (I + \llbracket P \rrbracket)^n(\emptyset)$$

- The elements are the finite tree's built from constructors in  $P$  (plus some units)

## The Free Monad (cont'd)

- For a tree  $t \in tr(P)$  write  $L(t)$  for its set of leaves
- Then the free monad on  $\llbracket P \rrbracket$  is given by the polynomial

$$\sum_{t \in tr(P)} L(t) \xrightarrow{\pi} tr(P)$$

The diagram shows a polynomial  $\sum_{t \in tr(P)} L(t)$  on the left, which maps via a natural transformation  $\pi$  to the set of trees  $tr(P)$  on the right. Below the polynomial, an arrow points to the set of leaves  $I$ . Similarly, below  $tr(P)$ , an arrow points to the set of leaves  $I$ .

- The multiplication in this monad is given by simply grafting trees together at their leaves



## The Slice Construction

- Observe that when  $P$  is a (cartesian) monad, we have a map

$$\mu^\infty : tr(P) \rightarrow B$$

which “collapses” each tree to a corolla

- Write  $N(t)$  for the set of internal nodes of a tree  $t \in tr(P)$
- The *slice construction*  $P^+$  on  $P$  is the polynomial

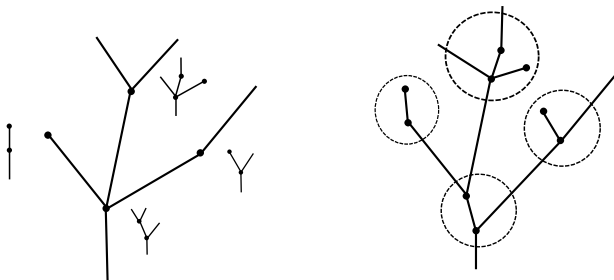
$$\begin{array}{ccc} \sum_{t \in tr(P)} N(t) & \xrightarrow{\pi} & tr(P) \\ \swarrow & & \searrow^{\mu^\infty} \\ B & & B \end{array}$$

# Multiplication in the Slice Construction

## Theorem

The slice construction  $P^+$  is again a (cartesian) monad

Multiplication is given by *substitution* of trees.



## Definition of the Opetopes

One useful monad is the identity functor on  $\mathcal{Set}$ , represented by the trivial polynomial:

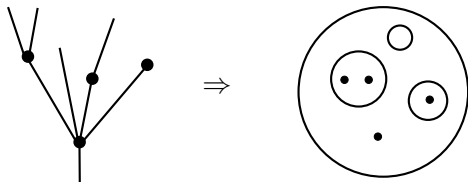
$$\begin{array}{ccc} & * & \longrightarrow * = \mathcal{O}(1) \\ & \swarrow & \searrow \mu^\infty \\ * & & * = \mathcal{O}(0) \end{array}$$

### Definition

The set  $\mathcal{O}(n)$  of  $n$ -dimensional opetopes is the indexing set of the  $n$ -th slice of the identity functor on  $\mathcal{Set}$ .

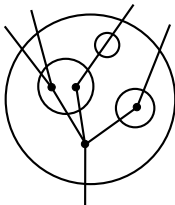
## Notation for the Opetopes

- Our picture of tree substitution above leads naturally to the following graphical notation for depicting opetopes in all dimensions
- A *nesting* is a configuration of non-intersecting circles and dots in the plane which corresponds to a tree



## Notation (cont'd)

- A *constellation* is a nesting and a tree *superimposed* so that the nodes of the tree are the dots in the nesting

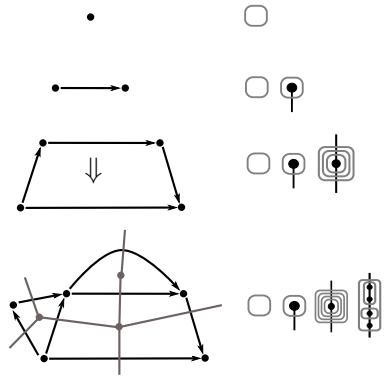


- These are subject to two rules
  - 1 There must be an outer circle containing all other dots and circles, except possibly if the tree contains exactly one node
  - 2 Every circle must cut a subtree (no “hanging” circles)

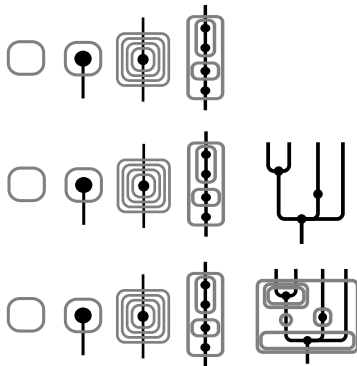
## Notation (cont'd)

- An opetope can now be represented by a sequence of such constellations, with the dimension given by the number of terms in the sequence
- This is subject to an initial condition and a simple rule for moving to higher dimensions
- You can play with this notation in a graphical editor here:  
<http://sma.epfl.ch/~finster/opetope/opetope.html>

# Notational Example



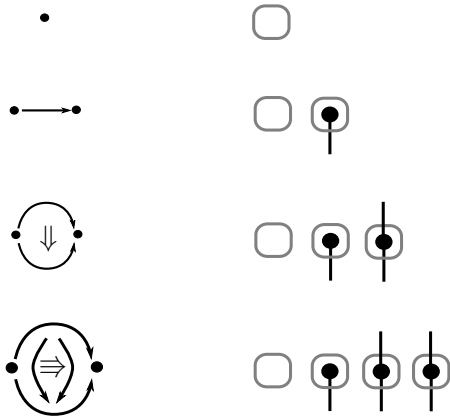
# Notation (cont'd)





# Opetopes and Globes

Globular shapes are a special case of opetopes:



## Implementation

- Opetopes can be represented by the following inductive type:

`data MTree (A : Set) : ℕ → Set where`

`obj : MTree A 0`

`drop : {n : ℕ} → MTree ⊤ n → MTree A (n + 2)`

`node : {n : ℕ} → A → MTree (MTree A (n + 1)) n  
→ MTree A (n + 1)`

- Elements of this type are “possible ill-typed  $A$ -labelled pasting diagrams”
- It is not hard to implement a “type-checker”

## The Derivative

For implementing type-checking, the following “higher-dimensional zipper” is extremely useful:

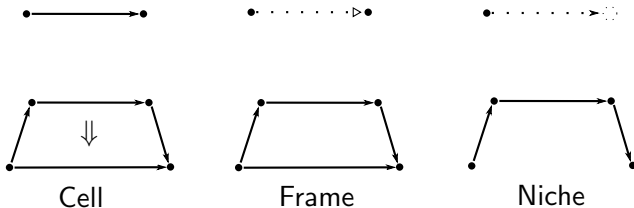
```
data Deriv (A : Set) : ℕ → Set where
  ∂ : {n : ℕ} → MTree (MTree A (n + 1)) n
    → Zipper A (n + 1) → Deriv A (n + 1)
```

```
data Zipper (A : Set) : ℕ → Set where
  Nil : {n : ℕ} → Zipper A (n + 1)
  Cons : {n : ℕ} → A → Deriv (MTree A (n + 1)) n
    → Zipper A (n + 1) → Zipper A (n + 1)
```

```
Context : Set → ℕ → Set
Context A n = Tree A n × Zipper A n
```

# Cells, Frames and Niches

- When working with simplicial sets, we have three canonical families
  - 1 Simplicies:  $\Delta^n$
  - 2 Boundaries:  $\partial\Delta^n$
  - 3 Horns:  $\Lambda_k^n$
- Opetopic sets have similar notations:



## Opetopic “Identity” Types

- Consider the formation rule for identity types:

$$\frac{\Gamma \vdash A : \text{Type}}{\Gamma, x : A, y : A \vdash \text{Id}_A(x, y) : \text{Type}}$$

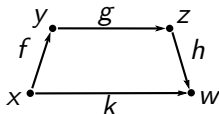
- Iteration gives a derived rule:

$$\frac{\Gamma \vdash A : \text{Type}}{\Gamma, x : A, y : A, f : \text{Id}_A(x, y), g : \text{Id}_A(x, y) \vdash \text{Id}_{\text{Id}_A(x, y)}(f, g) : \text{Type}}$$

- In each case, the data required in the context is exactly corresponds to a *frame* for a globular opetope.

## Opetopic "Identity" Types (cont'd)

- Let  $\pi$  denote an arbitrary opetope
- Write  $\Gamma, \llbracket F : A \rrbracket_{\pi} \vdash \dots$  as shorthand for the assumption of a variable for every face of the frame associated to  $\pi$
- Example: for  $\pi$  the 2-frame below



we would have

$$\Gamma, x : A, y : A, z : A, w : A, f : Id_A(x, y), \dots \vdash \dots$$

- Similarly,  $\Gamma, \llbracket N : A \rrbracket_{\pi} \vdash \dots$  means enough variables for the faces of the niche associated to  $\pi$

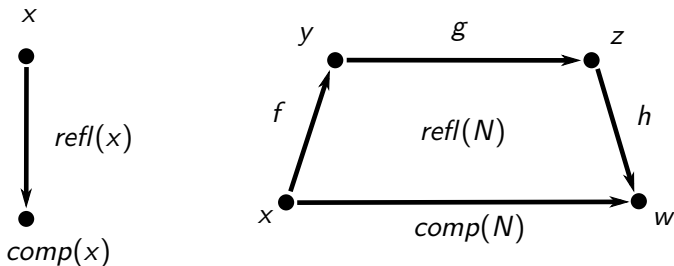
# Opetopic Formation and Introduction

$$\frac{\Gamma \vdash A : \text{Type}}{\Gamma, \llbracket F : A \rrbracket_{\pi} \vdash \text{Fill}(F) : \text{Type}} \quad \mathcal{O}\text{-Formation}$$

$$\frac{\Gamma \vdash [N : A]_{\pi}}{\Gamma \vdash \text{comp}(N) : \text{Fill}(N|_{\tau(\pi)})} \quad \mathcal{O}\text{-composition}$$

$$\frac{\Gamma \vdash [N : A]_{\pi}}{\Gamma \vdash \text{refl}(N) : \text{Fill}(N \triangleright \text{comp}(N))} \quad \mathcal{O}\text{-reflection}$$

## Introduction Examples



- When  $\pi$  is a glob, it contains a unique top dimensional source face, say  $x$ , and a new reduction rule says that  $comp(x) \rightarrow x$  in this case
- This corresponds to the slogan “a nullary composition is an isomorphism”



# A Generalized J-Rule

- The  $J$ -Rule

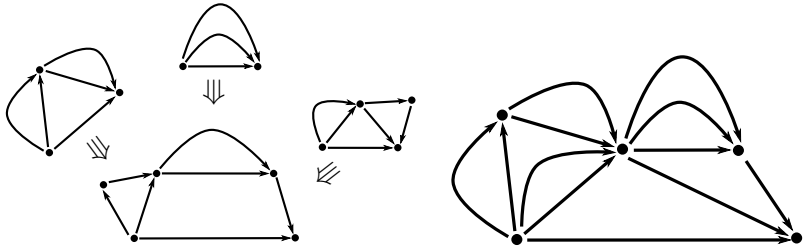
$$\begin{array}{c} \Gamma, x : A, y : A, f : Id_A(x, y) \vdash P(x, y, f) : Type \\ \Gamma, x : A \vdash p(x) : P(x, x, refl(x)) \\ \Gamma \vdash a : A \quad \Gamma \vdash b : A \quad \Gamma \vdash g : Fill(G) \\ \hline \Gamma \vdash J(a, b, g) : P(a, b, g) \end{array}$$

- An Opetopic  $J$ -Rule:

$$\begin{array}{c} \Gamma, \llbracket F : A \rrbracket_\pi, \alpha : Fill(F) \vdash P(F, \alpha) : Type \\ \Gamma, \llbracket N : A \rrbracket_\pi \vdash p(N) : P(N \triangleright comp(N), refl(N)) \\ \Gamma \vdash \llbracket G : A \rrbracket_\pi \quad \Gamma \vdash \beta : Fill(G) \\ \hline \Gamma \vdash J(G, \beta) : P(G, \beta) \end{array}$$

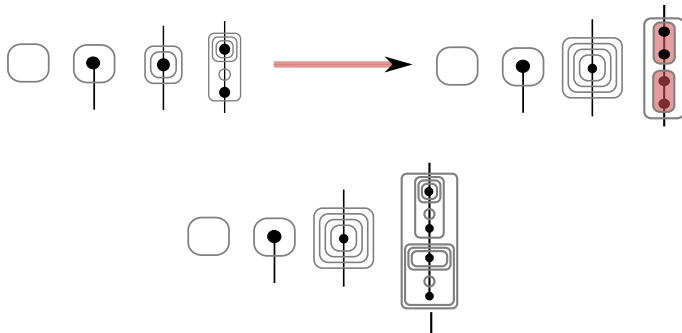
# The Opetopes as a Substitution Calculus

- The opetopes come equipped with a natural substitution operation arising from the fact that they are constructors in a polynomial monad



## Substitution (cont'd)

- By introducing binding, we can build a rewrite system reminiscent of  $\lambda$ -calculus:



# Opetopic Type Theory

The opetopes provide a natural framework for organizing higher dimensional type-theoretic concepts geometrically:

Dimension	Terms
0	Contexts
1	Types
2	Proofs
3	Proofs w/ Metavariables
...	...