



# Introduction to Topology -- 1

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This page is a detailed introduction to basic [topology](#). Starting from scratch (required background is just a basic concept of [sets](#)), and amplifying motivation from [analysis](#), it first develops standard [point-set topology](#) ([topological spaces](#)). In passing, some basics of [category theory](#) make an informal appearance, used to transparently summarize some conceptually important aspects of the theory, such as [initial](#) and [final topologies](#) and the [reflection](#) into [Hausdorff](#) and [sober topological spaces](#). The second part introduces some basics of [homotopy theory](#), mostly the [fundamental group](#), and ends with their first application to the classification of [covering spaces](#).

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**this chapter:** *Introduction to Topology 1 – Point-set topology*

next chapter: [Introduction to Topology 2 -- Basic Homotopy Theory](#)

For introduction to more general and abstract [homotopy theory](#) see instead at [Introduction to Homotopy Theory](#).

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## Point-set Topology

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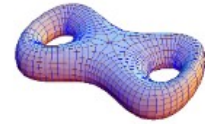
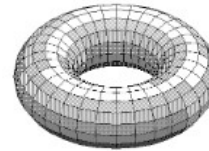
The idea of [topology](#) is to study “[spaces](#)” with “[continuous functions](#)” between them. Specifically one considers [functions](#) between [sets](#) (whence “[point-set topology](#)”, see [below](#)) such that there is a concept for what it means that these functions depend continuously on their arguments, in that that their values do not “jump”. Such a concept of [continuity](#) is familiar from [analysis](#) on [metric spaces](#), (recalled [below](#)) but the definition in topology generalizes this analytic concept and renders it more foundational, generalizing the concept of [metric spaces](#) to that of [topological spaces](#). (def. [2.3](#) below).

Hence [topology](#) is the study of the [category](#) whose [objects](#) are [topological spaces](#), and whose [morphisms](#) are [continuous functions](#) (see also remark [3.3](#) below). This category is much more flexible than that of [metric spaces](#), for example it admits the construction of arbitrary [quotients](#) and [intersections](#) of spaces. Accordingly, topology underlies or informs many and diverse areas of mathematics, such as [functional analysis](#), [operator algebra](#), [manifold/scheme](#) theory, hence [algebraic geometry](#) and [differential geometry](#), and the study of [topological groups](#), [topological vector spaces](#), [local rings](#), etc.. Not the least, it gives rise to the field of [homotopy theory](#), where one considers also continuous deformations of continuous functions themselves (“[homotopies](#)”). Topology itself has many branches, such as [low-dimensional topology](#) or [topological domain theory](#).

A popular imagery for the concept of a [continuous function](#) is provided by deformations of [elastic](#) physical bodies, which may be deformed by stretching them without tearing. The canonical illustration is a continous [bijective](#) function from the [torus](#) to the surface of a coffee mug, which maps half of the torus to the handle of the coffee mug, and continuously deforms parts of the other half in order to form the actual cup. Since the [inverse function](#) to this function is itself continuous, the torus and the coffee mug, both regarded as [topological spaces](#), are “[the same](#)” for the purposes of [topology](#), one says they are [homeomorphic](#).

On the other hand, there is *no* [homeomorphism](#) from the [torus](#) to, for instance, the [sphere](#), signifying that these represent two topologically distinct spaces. Part

of topology is concerned with studying [homeomorphism-invariants](#) of topological spaces ("[topological properties](#)") which allow to detect by means of [algebraic](#) manipulations whether two topological spaces are homeomorphic (or more generally [homotopy equivalent](#)) or not. This is called [algebraic topology](#). A basic algebraic invariant is the [fundamental group](#) of a topological space (discussed below), which measures how many ways there are to wind loops inside a topological space.



Beware that the popular imagery of "[rubber-sheet geometry](#)" only captures part of the full scope of topology, in that it invokes spaces that *locally* still look like [metric spaces](#). But the concept of topological spaces is a good bit more general. Notably [finite topological spaces](#) are either [discrete](#) or very much unlike [metric spaces](#) (example 4.7 below), they play a role in [categorical logic](#). Also in [geometry](#) exotic topological spaces frequently arise when forming non-free [quotients](#). In order to gauge just how many of such "exotic" examples of topological spaces beyond locally [metric spaces](#) one wishes to admit in the theory, extra "[separation axioms](#)" are imposed on topological spaces (see [below](#)), and the flavour of topology as a field depends on this choice.

Among the separation axioms, the [Hausdorff space](#) axiom is most popular (see [below](#)) the weaker axiom of [soberity](#) (see [below](#)) stands out, on the one hand because this is the weakest axiom that is still naturally satisfied in applications to [algebraic geometry](#) ([schemes are sober](#)) and [computer science](#) (Vickers 89) and on the other hand because it fully realizes the strong roots that topology has in [formal logic](#): [sober topological spaces](#) are entirely characterized by the union-, intersection- and inclusion-relations (logical [conjunction](#), [disjunction](#) and [implication](#)) among their [open subsets](#) ([propositions](#)). This leads to a natural and fruitful generalization of [topology](#) to more general "purely logic-determined spaces", called [locales](#) and in yet more generality [toposes](#) and [higher toposes](#). While the latter are beyond the scope of this introduction, their rich theory and relation to the [foundations](#) of mathematics and geometry provides an outlook on the relevance of the basic ideas of [topology](#).

In this first part we discuss the foundations of the concept of "sets equipped with topology" ([topological spaces](#)) and of [continuous functions](#) between them.

## 1. Metric spaces

The concept of continuity was first made precise in [analysis](#), in terms of [epsilon-delta analysis](#) on [metric spaces](#), recalled as def. 1.8 below. Then it was realized that this has a more elegant formulation in terms of the more general concept of [open sets](#), this is prop. 1.13 below. Adopting the latter as the definition leads to a more abstract concept of "continuous space", this is the concept of [topological spaces](#),

def. 2.3 below.

Here we briefly recall the relevant basic concepts from [analysis](#), as a motivation for various definitions in [topology](#). The reader who either already recalls these concepts in analysis or is content with ignoring the motivation coming from analysis should skip right away to the section [Topological spaces](#).

### Definition 1.1. (metric space)

A [metric space](#) is

1. a [set](#)  $X$  (the “underlying set”);
2. a [function](#)  $d : X \times X \rightarrow [0, \infty)$  (the “distance function”) from the [Cartesian product](#) of the set with itself to the [non-negative real numbers](#)

such that for all  $x, y, z \in X$ :

1. (symmetry)  $d(x, y) = d(y, x)$
2. ([triangle inequality](#))  $d(x, z) \leq d(x, y) + d(y, z)$ .
3. (non-degeneracy)  $d(x, y) = 0 \Leftrightarrow x = y$

**Definition 1.2.** Let  $(X, d)$ , be a [metric space](#). Then for every element  $x \in X$  and every  $\epsilon \in \mathbb{R}_+$  a [positive real number](#), we write

$$B_x^\circ(\epsilon) := \{y \in X \mid d(x, y) < \epsilon\}$$

for the [open ball](#) of [radius](#)  $\epsilon$  around  $x$ . Similarly we write

$$B_x(\epsilon) := \{y \in X \mid d(x, y) \leq \epsilon\}$$

for the *closed ball* of [radius](#)  $\epsilon$  around  $x$ . Finally we write

$$S_x(\epsilon) := \{y \in X \mid d(x, y) = \epsilon\}$$

for the [sphere](#) of [radius](#)  $\epsilon$  around  $x$ .

For  $\epsilon = 1$  we also speak of the *unit open/closed ball* and the *unit sphere*.

**Definition 1.3.** For  $(X, d)$  a [metric space](#) (def. 1.1) then a [subset](#)  $S \subset X$  is called a [bounded subset](#) if  $S$  is contained in some [open ball](#) (def. 1.2)

$$S \subset B_x^\circ(r)$$

around some  $x \in X$  of some [radius](#)  $r \in \mathbb{R}$ .

A key source of metric spaces are [normed vector spaces](#):

### Dedfinition 1.4. (normed vector space)

A [normed vector space](#) is

1. a [real vector space](#)  $V$ ;
2. a [function](#) (the [norm](#))

$$\|-\| : V \rightarrow \mathbb{R}_{\geq 0}$$

from the underlying [set](#) of  $V$  to the [non-negative real numbers](#),

such that for all  $c \in \mathbb{R}$  with [absolute value](#)  $|c|$  and all  $v, w \in V$  it holds true that

1. (linearity)  $\|cv\| = |c|\|v\|$ ;
2. ([triangle inequality](#))  $\|v + w\| \leq \|v\| + \|w\|$ ;
3. (non-degeneracy) if  $\|v\| = 0$  then  $v = 0$ .

**Proposition 1.5.** Every [normed vector space](#)  $(V, \|-\|)$  becomes a [metric space](#) according to def. 1.1 by setting

$$d(x, y) := \|x - y\|.$$

Examples of [normed vector spaces](#) (def. 1.4) and hence, via prop. 1.5, of [metric spaces](#) include the following:

**Example 1.6.** For  $n \in \mathbb{N}$ , the [Cartesian space](#)

$$\mathbb{R}^n = \{\vec{x} = (x_i)_{i=1}^n \mid x_i \in \mathbb{R}\}$$

carries a [norm](#) (the *Euclidean norm*) given by the [square root](#) of the [sum](#) of the [squares](#) of the components:

$$\|\vec{x}\| := \sqrt{\sum_{i=1}^n (x_i)^2}.$$

Via prop. 1.5 this gives  $\mathbb{R}^n$  the structure of a [metric space](#), and as such it is called the [Euclidean space](#) of [dimension](#)  $n$ .

**Example 1.7.** More generally, for  $n \in \mathbb{N}$ , and  $p \in \mathbb{R}$ ,  $p \geq 1$ , then the [Cartesian space](#)  $\mathbb{R}^n$  carries the [p-norm](#)

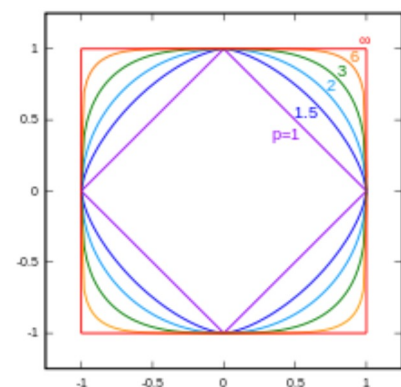
$$\|\vec{x}\|_p := \sqrt[p]{\sum_i |x_i|^p}$$

One also sets

$$\|\vec{x}\|_\infty := \max_{i \in I} |x_i|$$

and calls this the [supremum norm](#).

The graphics on the right (grabbed from Wikipedia) shows unit circles (def. 1.2)



in  $\mathbb{R}^2$  with respect to various [p-norms](#).

By the [Minkowski inequality](#), the [p-norm](#) generalizes to non-[finite dimensional vector spaces](#) such as [sequence spaces](#) and [Lebesgue spaces](#).

## Continuity

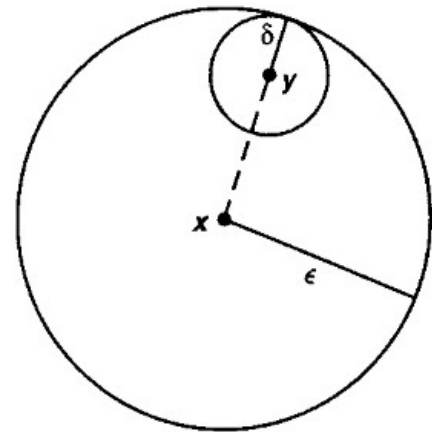
The following is now the fairly obvious definition of continuity for functions between metric spaces.

### Definition 1.8. (epsilon-delta definition of continuity)

For  $(X, d_X)$  and  $(Y, d_Y)$  two [metric spaces](#) (def. 1.1), then a [function](#)

$$f : X \rightarrow Y$$

is said to be *continuous at a point*  $x \in X$  if for every [positive real number](#)  $\epsilon$  there exists a [positive real number](#)  $\delta$  such that for all  $x' \in X$  that are a [distance](#) smaller than  $\delta$  from  $x$  then their image  $f(x')$  is a distance smaller than  $\epsilon$  from  $f(x)$ :



$$(f \text{ continuous at } x) := \bigvee_{\substack{\epsilon \in \mathbb{R} \\ \epsilon > 0}} \left( \bigwedge_{\substack{\delta \in \mathbb{R} \\ \delta > 0}} ((d_X(x, x') < \delta) \Rightarrow (d_Y(f(x), f(x')) < \epsilon)) \right).$$

The function  $f$  is said to be *continuous* if it is continuous at every point  $x \in X$ .

### Example 1.9. (polynomials are continuous functions)

Consider the [real line](#)  $\mathbb{R}$  regarded as the 1-dimensional [Euclidean space](#)  $\mathbb{R}$  from example 1.6.

For  $P \in \mathbb{R}[X]$  a [polynomial](#), then the function

$$\begin{aligned} f_P &: \mathbb{R} \rightarrow \mathbb{R} \\ x &\mapsto P(x) \end{aligned}$$

is a [continuous function](#) in the sense of def. 1.8.

Similarly for instance

- forming the [square root](#) is a continuous function  $\sqrt{\phantom{x}} : \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}_{\geq 0}$ ;
- forming the multiplicative inverse is a continuous function  $1/(\phantom{x}) : \mathbb{R}_{> 0} \rightarrow \mathbb{R}_{> 0}$ .

On the other hand, a [step function](#) is continuous everywhere except at the [finite number](#) of points at which it changes its value, see example [1.14](#) below.

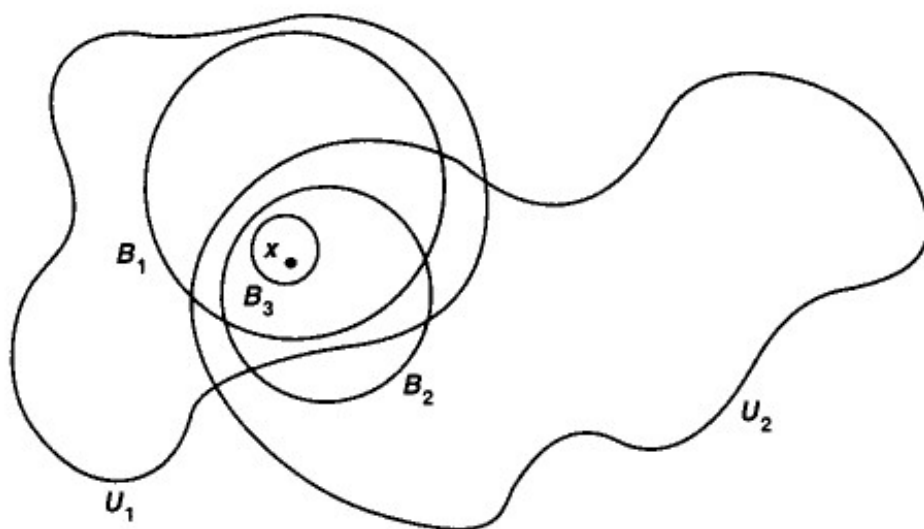
We now reformulate the analytic concept of continuity from def. [1.8](#) in terms of the simple but important concept of [open sets](#):

### Definition 1.10. (neighbourhood and open set)

Let  $(X, d)$  be a [metric space](#) (def. [1.1](#)). Say that:

1. A [neighbourhood](#) of a point  $x \in X$  is a [subset](#)  $U_x \subset X$  which contains some [open ball](#)  $B_x^\circ(\epsilon) \subset U_x$  around  $x$  (def. [1.2](#)).
2. An [open subset](#) of  $X$  is a [subset](#)  $U \subset X$  such that for every  $x \in U$  it also contains an [open ball](#)  $B_x^\circ(\epsilon)$  around  $x$  (def. [1.2](#)).
3. An [open neighbourhood](#) of a point  $x \in X$  is a [neighbourhood](#)  $U_x$  of  $x$  which is also an open subset, hence equivalently this is any open subset of  $X$  that contains  $x$ .

The following picture shows a point  $x$ , some [open balls](#)  $B_i$  containing it, and two of its [neighbourhoods](#)  $U_i$ :



*graphics grabbed from [Munkres 75](#)*

### Example 1.11. (the empty subset is open)

Notice that for  $(X, d)$  a [metric space](#), then the [empty subset](#)  $\emptyset \subset X$  is always an [open subset](#) of  $(X, d)$  according to def. [1.10](#). This is because the clause for open subsets  $U \subset X$  says that “for every point  $x \in U$  there exists...”, but since there is no  $x$  in  $U = \emptyset$ , this clause is always satisfied in this case.

Conversely, the entire set  $X$  is always an open subset of  $(X, d)$ .

### Example 1.12. (open/closed [intervals](#))



Regard the [real numbers](#)  $\mathbb{R}$  as the 1-dimensional [Euclidean space](#) (example [1.6](#)).

For  $a < b \in \mathbb{R}$  consider the following [subsets](#):

1.  $(a, b) := \{x \in \mathbb{R} \mid a < x < b\}$  (*open interval*)
2.  $(a, b] := \{x \in \mathbb{R} \mid a < x \leq b\}$  (*half-open interval*)
3.  $[a, b) := \{x \in \mathbb{R} \mid a \leq x < b\}$  (*half-open interval*)
4.  $[a, b] := \{x \in \mathbb{R} \mid a \leq x \leq b\}$  (*closed interval*)

The first of these is an open subset according to def. [1.10](#), the other three are not. The first one is called an [open interval](#), the last one a [closed interval](#) and the middle two are called [half-open intervals](#).

Similarly for  $a, b \in \mathbb{R}$  one considers

1.  $(-\infty, b) := \{x \in \mathbb{R} \mid x < b\}$  (*unbounded open interval*)
2.  $(a, \infty) := \{x \in \mathbb{R} \mid a < x\}$  (*unbounded open interval*)
3.  $(-\infty, b] := \{x \in \mathbb{R} \mid x \leq b\}$  (*unbounded half-open interval*)
4.  $[a, \infty) := \{x \in \mathbb{R} \mid a \leq x\}$  (*unbounded half-open interval*)

The first two of these are open subsets, the last two are not.

For completeness we may also consider

- $(-\infty, \infty) = \mathbb{R}$
- $(a, a) = \emptyset$

which are both open, according to def. [2.3](#).

We may now rephrase the analytic definition of continuity entirely in terms of open subsets (def. [1.10](#)):

**Proposition 1.13. (rephrasing continuity in terms of open sets)**

Let  $(X, d_X)$  and  $(Y, d_Y)$  be two [metric space](#) (def. [1.1](#)). Then a [function](#)  $f: X \rightarrow Y$  is [continuous](#) in the [epsilon-delta](#) sense of def. [1.8](#) precisely if it has the property that its [pre-images](#) of [open subsets](#) of  $Y$  (in the sense of def. [1.10](#)) are open subsets of  $X$ :

$$(f \text{ continuous}) \Leftrightarrow ((O_Y \subset Y \text{ open}) \Rightarrow (f^{-1}(O_Y) \subset X \text{ open})) .$$



## principle of continuity

*Continuous pre-Images of open subsets are open.*

**Proof.** Observe, by direct unwinding the definitions, that the epsilonic definition of continuity (def. 1.8) says equivalently in terms of [open balls](#) (def. 1.2) that  $f$  is continuous at  $x$  precisely if for every open ball  $B_{f(x)}^\circ(\epsilon)$  around an image point, there exists an open ball  $B_x^\circ(\delta)$  around the corresponding pre-image point which maps into it:

$$\begin{aligned} (f \text{ continuous at } x) &\Leftrightarrow \forall_{\epsilon > 0} \left( \exists_{\delta > 0} (f(B_x^\circ(\delta)) \subset B_{f(x)}^\circ(\epsilon)) \right) \\ &\Leftrightarrow \forall_{\epsilon > 0} \left( \exists_{\delta > 0} (B_x^\circ(\delta) \subset f^{-1}(B_{f(x)}^\circ(\epsilon))) \right) \end{aligned}$$

With this observation the proof immediate. For the record, we spell it out:

First assume that  $f$  is continuous in the epsilonic sense. Then for  $O_Y \subset Y$  any [open subset](#) and  $x \in f^{-1}(O_Y)$  any point in the pre-image, we need to show that there exists an [open neighbourhood](#) of  $x$  in  $f^{-1}(O_Y)$ .

That  $O_Y$  is open in  $Y$  means by definition that there exists an [open ball](#)  $B_{f(x)}^\circ(\epsilon)$  in  $O_Y$  around  $f(x)$  for some radius  $\epsilon$ . By the assumption that  $f$  is continuous and using the above observation, this implies that there exists an open ball  $B_x^\circ(\delta)$  in  $X$  such that  $f(B_x^\circ(\delta)) \subset B_{f(x)}^\circ(\epsilon) \subset O_Y$ , hence such that  $B_x^\circ(\delta) \subset f^{-1}(B_{f(x)}^\circ(\epsilon)) \subset f^{-1}(O_Y)$ . Hence this is an open ball of the required kind.

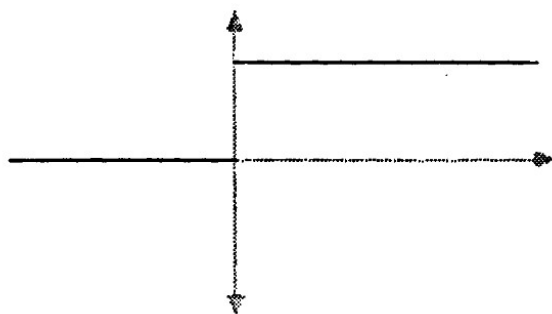
Conversely, assume that the pre-image function  $f^{-1}$  takes open subsets to open subsets. Then for every  $x \in X$  and  $B_{f(x)}^\circ(\epsilon) \subset Y$  an [open ball](#) around its image, we need to produce an open ball  $B_x^\circ(\delta) \subset X$  around  $x$  such that  $f(B_x^\circ(\delta)) \subset B_{f(x)}^\circ(\epsilon)$ .

But by definition of open subsets,  $B_{f(x)}^\circ(\epsilon) \subset Y$  is open, and therefore by assumption on  $f$  its pre-image  $f^{-1}(B_{f(x)}^\circ(\epsilon)) \subset X$  is also an open subset of  $X$ . Again by definition of open subsets, this implies that it contains an open ball as required. ■

### Example 1.14. ([step function](#))

Consider  $\mathbb{R}$  as the 1-dimensional [Euclidean space](#) (example 1.6) and consider the [step function](#)

$$\begin{aligned} \mathbb{R} &\xrightarrow{H} \mathbb{R} \\ x &\mapsto \begin{cases} 0 & | x \leq 0 \\ 1 & | x > 0 \end{cases} \end{aligned}$$



graphics grabbed from [Vickers 89](#)

Consider then for  $a < b \in \mathbb{R}$  the [open interval](#)  $(a, b) \subset \mathbb{R}$ , an [open subset](#) according to example [1.12](#). The [preimage](#)  $H^{-1}(a, b)$  of this open subset is

$$H^{-1} : (a, b) \mapsto \begin{cases} \emptyset & | a \geq 1 \text{ or } b \leq 0 \\ \mathbb{R} & | a < 0 \text{ and } b > 1 \\ \emptyset & | a \geq 0 \text{ and } b \leq 1 \\ (0, \infty) & | 0 \leq a < 1 \text{ and } b > 1 \\ (-\infty, 0] & | a < 0 \text{ and } b \leq 1 \end{cases}.$$

By example [1.12](#), all except the last of these pre-images listed are open subsets.

The failure of the last of the pre-images to be open witnesses that the step function is not continuous at  $x = 0$ .

## Compactness

A key application of [metric spaces](#) in [analysis](#) is that they allow a formalization of what it means for an infinite [sequence](#) of elements in the metric space (def. [1.15](#) below) to [converge](#) to a [limit of a sequence](#) (def. [1.16](#) below). Of particular interest are therefore those metric spaces for which each sequence has a converging subsequence: the [sequentially compact metric spaces](#) (def. [1.19](#)).

We now briefly recall these concepts from [analysis](#). Then, in the above spirit, we reformulate their epsilon-delta definition in terms of [open subsets](#). This gives a useful definition that generalizes to [topological spaces](#), the [compact topological spaces](#) discussed further [below](#).

### Definition 1.15. ([sequence](#))

Given a [set](#)  $X$ , then a [sequence](#) of elements in  $X$  is a [function](#)

$$x_{(-)} : \mathbb{N} \rightarrow X$$

from the [natural numbers](#) to  $X$ .

A [sub-sequence](#) of such a sequence is a sequence of the form

$$x_{\iota(-)} : \mathbb{N} \xrightarrow{\iota} \mathbb{N} \xrightarrow{x_{(-)}} X$$

for some [injection](#)  $\iota$ .

### Definition 1.16. ([convergence to limit of a sequence](#))

Let  $(X, d)$  be a [metric space](#) (def. [1.1](#)). Then a [sequence](#)

$$x_{(-)} : \mathbb{N} \rightarrow X$$

in the underlying set  $X$  (def. 1.15) is said to converge to a point  $x_\infty \in X$ , denoted

$$x_i \xrightarrow{i \rightarrow \infty} x_\infty$$

if for every positive real number  $\epsilon$ , there exists a natural number  $n$ , such that all elements in the sequence after the  $n$ th one have distance less than  $\epsilon$  from  $x_\infty$ .

$$(x_i \xrightarrow{i \rightarrow \infty} x_\infty) \Leftrightarrow \left( \bigvee_{\substack{\epsilon \in \mathbb{R} \\ \epsilon > 0}} \left( \bigexists_{n \in \mathbb{N}} \left( \bigvee_{\substack{i \in \mathbb{N} \\ i > n}} d(x_i, x_\infty) \leq \epsilon \right) \right) \right).$$

Here the point  $x_\infty$  is called the limit of the sequence. Often one writes  $\lim_{i \rightarrow \infty} x_i$  for this point.

### Definition 1.17. (Cauchy sequence)

Given a metric space  $(X, d)$  (def. 1.1), then a sequence of points in  $X$  (def. 1.15)

$$x_{(-)} : \mathbb{N} \rightarrow X$$

is called a Cauchy sequence if for every positive real number  $\epsilon$  there exists a natural number  $n \in \mathbb{N}$  such that the distance between any two elements of the sequence beyond the  $n$ th one is less than  $\epsilon$

$$(x_{(-)} \text{ Cauchy}) \Leftrightarrow \left( \bigvee_{\substack{\epsilon \in \mathbb{R} \\ \epsilon > 0}} \left( \bigexists_{N \in \mathbb{N}} \left( \bigvee_{\substack{i, j \in \mathbb{N} \\ i, j > N}} d(x_i, x_j) \leq \epsilon \right) \right) \right).$$

### Definition 1.18. (complete metric space)

A metric space  $(X, d)$  (def. 1.1), for which every Cauchy sequence (def. 1.17) converges (def. 1.16) is called a complete metric space.

A normed vector space, regarded as a metric space via prop. 1.5 that is complete in this sense is called a Banach space.

Finally recall the concept of compactness of metric spaces via epsilon-ontic analysis:

### Definition 1.19. (sequentially compact metric space)

A metric space  $(X, d)$  (def. 1.1) is called sequentially compact if every sequence in  $X$  has a subsequence (def. 1.15) which converges (def. 1.16).

The key fact to translate this epsilon-ontic definition of compactness to a concept that makes sense for general topological spaces (below) is the following:

### Proposition 1.20. (sequentially compact metric spaces are equivalently compact metric spaces)

For a metric space  $(X, d)$  (def. 1.1) the following are equivalent:

1.  $X$  is sequentially compact;
2. for every set  $\{U_i \subset X\}_{i \in I}$  of open subsets  $U_i$  of  $X$  (def. 1.10) which cover  $X$  in that  $X = \bigcup_{i \in I} U_i$ , then there exists a finite subset  $J \subset I$  of these open subsets which still covers  $X$  in that also  $X = \bigcup_{i \in J \subset I} U_i$ .

The **proof** of prop. 1.20 is most conveniently formulated with some of the terminology of topology in hand, which we introduce now. Therefore we postpone the proof to below.

In **summary** prop. 1.13 and prop. 1.20 show that the purely combinatorial and in particular non-epsilon concept of open subsets captures a substantial part of the nature of metric spaces in analysis. This motivates to reverse the logic and consider more general “spaces” which are *only* characterized by what counts as their open subsets. These are the topological spaces which we turn to now in def. 2.3 (or, more generally, these are the “locales”, which we briefly consider below in remark 5.6).

## 2. Topological spaces

Due to prop. 1.13 we should pay attention to open subsets in metric spaces. It turns out that the following closure property, which follow directly from the definitions, is at the heart of the concept:

### Proposition 2.1. (closure properties of open sets in a metric space)

The collection of open subsets of a metric space  $(X, d)$  as in def. 1.10 has the following properties:

1. The union of any set of open subsets is again an open subset.
2. The intersection of any finite number of open subsets is again an open subset.

### Remark 2.2. (empty union and empty intersection)

Notice the degenerate case of unions  $\bigcup_{i \in I} U_i$  and intersections  $\bigcap_{i \in I} U_i$  of subsets  $U_i \subset X$  for the case that they are indexed by the empty set  $I = \emptyset$ :

1. the *empty union* is the empty set itself;
2. the *empty intersection* is all of  $X$ .

(The second of these may seem less obvious than the first. We discuss the general logic behind these kinds of phenomena below.)

This way prop. 2.1 is indeed compatible with the degenerate cases of examples of open subsets in example 1.11.

Proposition 2.1 motivates the following generalized definition, which abstracts away from the concept of [metric space](#) just its system of [open subsets](#):

### Definition 2.3. ([topological spaces](#))

Given a [set](#)  $X$ , then a *topology* on  $X$  is a collection  $\tau$  of [subsets](#) of  $X$  called the [open subsets](#), hence a [subset](#) of the [power set](#)  $P(X)$

$$\tau \subset P(X)$$

such that this is closed under forming

1. finite [intersections](#);
2. arbitrary [unions](#).

In particular (by remark 2.2):

- the [empty set](#)  $\emptyset \subset X$  is in  $\tau$  (being the union of no subsets)

and

- the whole set  $X \subset X$  itself is in  $\tau$  (being the intersection of no subsets).

A set  $X$  equipped with such a [topology](#) is called a [topological space](#).

**Remark 2.4.** In the field of [topology](#) it is common to eventually simply say “[space](#)” as shorthand for “[topological space](#)”. This is especially so as further qualifiers are added, such as “Hausdorff space” (def. 4.4 below). But beware that there are other kinds of [spaces](#) in mathematics.

**Remark 2.5.** The simple definition of [open subsets](#) in def. 2.3 and the simple implementation of the *principle of continuity* below in def. 3.1 gives the field of [topology](#) its fundamental and universal flavor. The combinatorial nature of these definitions makes [topology](#) be closely related to [formal logic](#). This becomes more manifest still for the “[sober topological space](#)” discussed [below](#). For more on this perspective see the remark on [locales](#) below, remark 5.6. An introductory textbook amplifying this perspective is ([Vickers 89](#)).

Before we look at first examples [below](#), here is some common **further terminology** regarding topological spaces:

There is an evident [partial ordering](#) on the set of topologies that a given set may carry:

### Definition 2.6. ([finer/coarser topologies](#))

Let  $X$  be a [set](#), and let  $\tau_1, \tau_2 \in P(X)$  be two [topologies](#) on  $X$ , hence two choices of

open subsets for  $X$ , making it a topological space. If

$$\tau_1 \subset \tau_2$$

hence if every open subset of  $X$  with respect to  $\tau_1$  is also regarded as open by  $\tau_2$ , then one says that

- the topology  $\tau_2$  is finer than the topology  $\tau_1$
- the topology  $\tau_1$  is coarser than the topology  $\tau_2$ .

With any kind of structure on sets, it is of interest how to “generate” such structures from a small amount of data:

### Definition 2.7. (basis for the topology)

Let  $(X, \tau)$  be a topological space, def. 2.3, and let

$$\beta \subset \tau$$

be a subset of its set of open subsets. We say that

1.  $\beta$  is a basis for the topology  $\tau$  if every open subset  $O \in \tau$  is a union of elements of  $\beta$ ;
2.  $\beta$  is a sub-basis for the topology if every open subset  $O \in \tau$  is a union of finite intersections of elements of  $\beta$ .

Often it is convenient to *define* topologies by defining some (sub-)basis as in def. 2.7. Examples are the metric topology below, example 2.9, the binary product topology in def. 2.18 below, and the compact-open topology on mapping spaces below in def. 6.17. To make use of this, we need to recognize sets of open subsets that serve as the basis for some topology:

### Lemma 2.8. (recognition of topological bases)

Let  $X$  be a set.

1. A collection  $\beta \subset P(X)$  of subsets of  $X$  is a basis for some topology  $\tau \subset P(X)$  (def. 2.7) precisely if
  1. every point of  $X$  is contained in at least one element of  $\beta$ ;
  2. for every two subsets  $B_1, B_2 \in \beta$  and for every point  $x \in B_1 \cap B_2$  in their intersection, then there exists a  $B \in \beta$  that contains  $x$  and is contained in the intersection:  $x \in B \subset B_1 \cap B_2$ .
2. A subset  $B \subset \tau$  of opens is a sub-basis for a topology  $\tau$  on  $X$  precisely if  $\tau$  is the coarsest topology (def. 2.6) which contains  $B$ .

## Examples

We discuss here some basic examples of [topological spaces](#) (def. 2.3), to get a feeling for the scope of the concept. But topological spaces are ubiquitous in [mathematics](#), so that there are many more examples and many more classes of examples than could be listed. As we further develop the theory below, we encounter more examples, and more classes of examples. Below in [Universal constructions](#) we discuss a very general construction principle of new topological space from given ones.

First of all, our motivating example from [above](#) now reads as follows:

### Example 2.9. ([metric topology](#))

Let  $(X, d)$  be a [metric space](#) (def. 1.1). Then the collection of its [open subsets](#) in def. 1.10 constitutes a [topology](#) on the set  $X$ , making it a [topological space](#) in the sense of def. 2.3. This is called the [metric topology](#).

The [open balls](#) in a metric space constitute a [basis of a topology](#) (def. 2.7) for the [metric topology](#).

While the example of [metric space](#) topologies (example 2.9) is the motivating example for the concept of [topological spaces](#), it is important to notice that the concept of topological spaces is considerably more general, as some of the following examples show.

The following simplistic example of a (metric) topological space is important for the theory (for instance in prop. 2.35):

### Example 2.10. ([empty space](#) and [point space](#))

On the [empty set](#) there exists a unique topology. We write  $\emptyset$  also for the resulting [topological space](#), which we call the [empty topological space](#).

On a [singleton](#) set  $\{1\}$  there exists a unique topology  $\tau$  making it a [topological space](#) according to def. 2.3, namely

$$\tau := \{\emptyset, \{1\}\}.$$

We write

$$* := (\{1\}, \tau := \{\emptyset, \{1\}\})$$

for this topological space and call it *the [point topological space](#)*.

This is equivalently the [metric topology](#) (example 2.9) on  $\mathbb{R}^0$ , regarded as the 0-dimensional [Euclidean space](#) (example 1.6).

**Example 2.11.** On the 2-element set  $\{0, 1\}$  there are (up to [permutation](#) of elements) three distinct topologies:

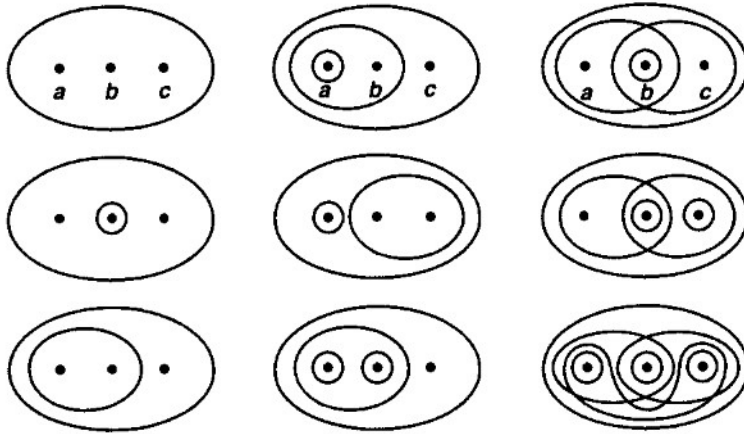
1. the [codiscrete topology](#) (def. 2.13)  $\tau = \{\emptyset, \{0, 1\}\};$



2. the [discrete topology](#) (def. 2.13),  $\tau = \{\emptyset, \{0\}, \{1\}, \{0, 1\}\}$ ;

3. the [Sierpinski space](#) topology  $\tau = \{\emptyset, \{1\}, \{0, 1\}\}$ .

**Example 2.12.** The following shows all the topologies on the 3-element set (up to [permutation](#) of elements)



graphics grabbed from [Munkres 75](#)

### Example 2.13. (discrete and co-discrete topology)

Let  $S$  be any [set](#). Then there are always the following two extreme possibilities of equipping  $X$  with a topology  $\tau \subset P(X)$  in the sense of def. 2.3, and hence making it a [topological space](#):

1.  $\tau := P(S)$  the set of *all* open subsets;

this is called the [discrete topology](#) on  $S$ , it is the [finest topology](#) (def. 2.6) on  $X$ ,

we write  $\text{Disc}(S)$  for the resulting topological space;

2.  $\tau := \{\emptyset, S\}$  the set containing only the [empty](#) subset of  $S$  and all of  $S$  itself;

this is called the [codiscrete topology](#) on  $S$ , it is the [coarsest topology](#) (def. 2.6) on  $X$ ,

we write  $\text{CoDisc}(S)$  for the resulting topological space.

The reason for this terminology is best seen when considering [continuous functions](#) into or out of these (co-)discrete topological spaces, we come to this in example 3.8 below.

### Example 2.14. (cofinite topology)

Given a [set](#)  $X$ , then the [cofinite topology](#) or *finite complement topology* on  $X$  is the [topology](#) (def. 2.3) whose [open subsets](#) are precisely

1. all [cofinite subsets](#)  $S \subset X$  (i.e. those such that the [complement](#)  $X \setminus S$  is a

[finite set](#));

2. the [empty set](#).

If  $X$  is itself a [finite set](#) (but not otherwise) then the cofinite topology on  $X$  coincides with the [discrete topology](#) on  $X$  (example [2.13](#)).

We now consider basic construction principles of new topological spaces from given ones:

1. [disjoint union spaces](#) (example [2.15](#))
2. [subspaces](#) (example [2.16](#)),
3. [quotient spaces](#) (example [2.17](#))
4. [product spaces](#) (example [2.18](#)).

Below in [Universal constructions](#) we will recognize these as simple special cases of a general construction principle.

### Example 2.15. ([disjoint union](#))

For  $\{(X_i, \tau_i)\}_{i \in I}$  a [set](#) of topological spaces, then their [disjoint union](#)

$$\bigsqcup_{i \in I} (X_i, \tau_i)$$

is the topological space whose underlying set is the [disjoint union](#) of the underlying sets of the summand spaces, and whose open subsets are precisely the disjoint unions of the open subsets of the summand spaces.

In particular, for  $I$  any index set, then the disjoint union of  $I$  copies of the [point space](#) (example [2.10](#)) is equivalently the [discrete topological space](#) (example [2.13](#)) on that index set:

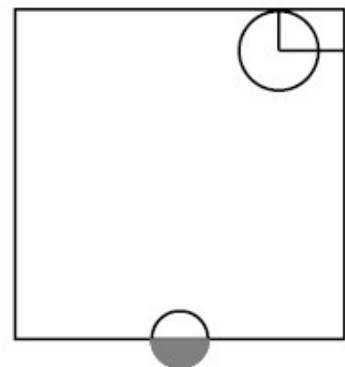
$$\bigsqcup_{i \in I} * = \text{Disc}(I) .$$

### Example 2.16. ([subspace topology](#))

Let  $(X, \tau_X)$  be a [topological space](#), and let  $S \subset X$  be a [subset](#) of the underlying set. Then the corresponding [topological subspace](#) has  $S$  as its underlying set, and its open subsets are those subsets of  $S$  which arise as restrictions of open subsets of  $X$ .

$$(U_S \subset S \text{ open}) \Leftrightarrow \left( \exists_{U_X \in \tau_X} (U_S = U_X \cap S) \right) .$$

(This is also called the [initial topology](#) of the inclusion map. We come back to this below in def. [8.5](#).)



The picture on the right shows two open subsets inside the square, regarded as a topological subspace of the plane  $\mathbb{R}^2$ :

*graphics grabbed from Munkres 75*

### Example 2.17. (quotient topological space)

Let  $(X, \tau_X)$  be a topological space (def. 2.3) and let

$$R_{\sim} \subset X \times X$$

be an equivalence relation on its underlying set. Then the quotient topological space has

- as underlying set the quotient set  $X / \sim$ , hence the set of equivalence classes,

and

- a subset  $O \subset X / \sim$  is declared to be an open subset precisely if its preimage  $\pi^{-1}(O)$  under the canonical projection map

$$\pi : X \rightarrow X / \sim$$

is open in  $X$ .

(This is also called the final topology of the projection  $\pi$ . We come back to this below in def. 8.5. )

Often one considers this with input datum not the equivalence relation, but any surjection

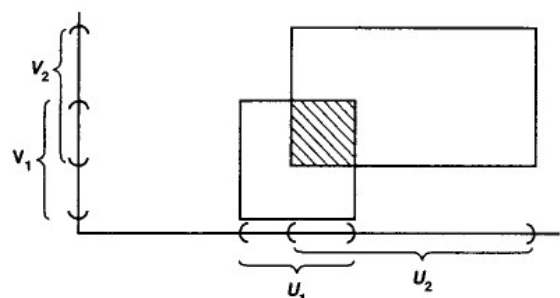
$$\pi : X \rightarrow Y$$

of sets. Of course this identifies  $Y = X / \sim$  with  $(x_1 \sim x_2) \Leftrightarrow (\pi(x_1) = \pi(x_2))$ . Hence the quotient topology on the codomain set of a function out of any topological space has as open subsets those whose pre-images are open.

To see that this indeed does define a topology on  $X / \sim$  it is sufficient to observe that taking pre-images commutes with taking unions and with taking intersections.

### Example 2.18. (binary product topological space)

For  $(X_1, \tau_{X_1})$  and  $(X_2, \tau_{X_2})$  two topological spaces, then their binary product topological space has as underlying set the Cartesian product  $X_1 \times X_2$  of the corresponding two underlying sets, and its topology is generated from the basis (def. 2.7) given by the Cartesian products



$U_1 \times U_2$  of the opens  $U_i \in \tau_i$ .

*graphics grabbed from Munkres 75*

Beware that for non-[finite](#) products, the descriptions of the product topology is not as simple. This we turn to below in [example 8.11](#), after introducing the general concept of [limits](#) in the [category of topological spaces](#).

The following examples illustrate how all these ingredients and construction principles may be combined.

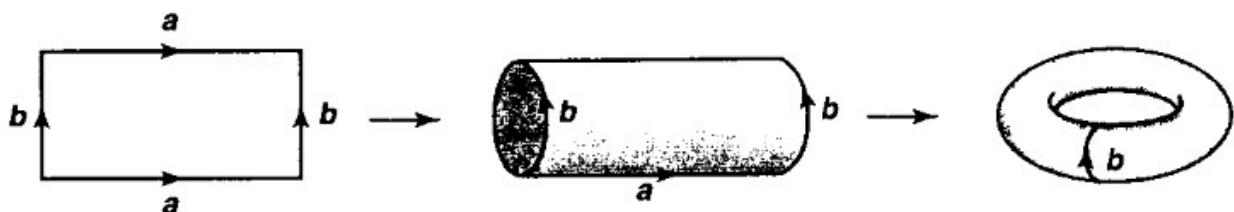
The following example we will examine in more detail below in [example 3.29](#), after we have introduced the concept of [homeomorphisms](#) below.

**Example 2.19.** Consider the [real numbers](#)  $\mathbb{R}$  as the 1-dimensional [Euclidean space](#) ([example 1.6](#)) and hence as a [topological space](#) via the corresponding [metric topology](#) ([example 2.9](#)). Moreover, consider the [closed interval](#)  $[0, 1] \subset \mathbb{R}$  from [example 1.12](#), regarded as a [subspace](#) (def. 2.16) of  $\mathbb{R}$ .

The [product space](#) ([example 2.18](#)) of this interval with itself

$$[0, 1] \times [0, 1]$$

is a topological space modelling the closed square. The [quotient space](#) ([example 2.17](#)) of that by the relation which identifies a pair of opposite sides is a model for the [cylinder](#). The further quotient by the relation that identifies the remaining pair of sides yields a model for the [torus](#).



*graphics grabbed from Munkres 75*

### Example 2.20. ([spheres](#) and disks)

For  $n \in \mathbb{N}$  write

- $D^n$  for the [n-disk](#), the [closed unit ball](#) (def. 1.2) in the  $n$ -dimensional [Euclidean space](#)  $\mathbb{R}^n$  ([example 1.6](#)) and equipped with the induced [subspace topology](#) ([example 2.16](#)) of the corresponding [metric topology](#) ([example 2.9](#));
- $S^{n-1}$  for the [\(n-1\)-sphere](#) (def. 1.2) also equipped with the corresponding [subspace topology](#);
- $i_n : S^{n-1} \hookrightarrow D^n$  for the [continuous function](#) that exhibits this [boundary](#) inclusion.

Notice that

- $S^{-1} = \emptyset$  is the [empty topological space](#) (example 2.10);
- $S^0 = * \sqcup *$  is the [disjoint union space](#) (example 2.15) of the [point topological space](#) (example 2.10) with itself, equivalently the [discrete topological space](#) on two elements (example 2.11).

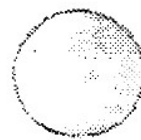
## Closed subsets

The [complements](#) of [open subsets](#) in a [topological space](#) are called [closed subsets](#) (def. 2.21 below). This simple definition indeed captures the concept of closure in the [analytic](#) sense of [convergence](#) of [sequences](#) (prop. 2.27 below). Of particular interest for the theory of topological spaces in the discussion of [separation axioms](#) below are those closed subsets which are “[irreducible](#)” (def. 2.28 below). These happen to be equivalently the “[frame](#) homomorphisms” (def. 2.32) to the [frame of opens](#) of the point (prop. 2.35 below).

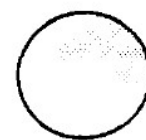
### Definition 2.21. ([closed subsets](#))

Let  $(X, \tau)$  be a [topological space](#) (def. 2.3).

1. A [subset](#)  $S \subset X$  is called a [closed subset](#) if its [complement](#)  $X \setminus S$  is an [open subset](#):



open



closed



neither

$$(S \subset X \text{ is closed}) \quad \Leftrightarrow \quad (X \setminus S \subset X \text{ is open}) .$$

*graphics grabbed from [Vickers 89](#)*

2. If a [singleton](#) subset  $\{x\} \subset X$  is closed, one says that  $x$  is a *closed point* of  $X$ .
3. Given any subset  $S \subset X$ , then its [topological closure](#)  $\text{Cl}(S)$  is the smallest closed subset containing  $S$ :

$$\text{Cl}(S) := \bigcap_{\substack{C \subset X \text{ closed} \\ S \subset C}} (C) .$$

4. A subset  $S \subset X$  such that  $\text{Cl}(S) = X$  is called a [dense subset](#) of  $(X, \tau)$ .

### Remark 2.22. ([de Morgan's law](#))

In reasoning about [closed subsets](#) in [topology](#) we are concerned with [complements](#) of [unions](#) and [intersections](#) as well as with [unions/intersections](#) of [complements](#). Recall therefore that taking [complements](#) of [subsets](#) exchanges [unions](#) with [intersections](#) ([de Morgan's law](#)):

Given a [set](#)  $X$  and a set of subsets

$$\{S_i \subset S\}_{i \in I}$$

then

$$X \setminus \left( \bigcup_{i \in I} S_i \right) = \bigcap_{i \in I} (X \setminus S_i)$$

and

$$X \setminus \left( \bigcap_{i \in I} S_i \right) = \bigcup_{i \in I} (X \setminus S_i) .$$

Also notice that taking complements reverses inclusion relations:

$$(S_1 \subset S_2) \Leftrightarrow (X \setminus S_2 \subset X \setminus S_1) .$$

Often it is useful to reformulate def. 2.21 of [closed subsets](#) as follows:

**Lemma 2.23.** *Let  $(X, \tau)$  be a [topological space](#) and let  $S \subset X$  be a [subset](#) of its underlying set. Then a point  $x \in X$  is contained in the [topological closure](#)  $\text{Cl}(S)$  (def. 2.21) precisely if every [open neighbourhood](#)  $U_x \subset X$  of  $x$  [intersects](#)  $S$ :*

$$(x \in \text{Cl}(S)) \Leftrightarrow \neg \left( \bigcap_{\substack{U \subset X \setminus S \\ U \subset X \text{ open}}} (x \in U) \right) .$$

**Proof.** In view of remark 2.22 we may rephrase the definition of the [topological closure](#) as follows:

$$\begin{aligned} \text{Cl}(S) &:= \bigcap_{\substack{C \subset X \text{ closed} \\ S \subset C}} (C) \\ &= \bigcap_{\substack{U \subset X \setminus S \\ U \subset X \text{ open}}} (X \setminus U) \\ &= X \setminus \left( \bigcup_{\substack{U \subset X \setminus S \\ U \subset X \text{ open}}} U \right) \end{aligned}$$

■

**Definition 2.24. ([topological interior](#) and [boundary](#))**

Let  $(X, \tau)$  be a [topological space](#) (def. 2.3) and let  $S \subset X$  be a [subset](#). Then the [topological interior](#) of  $S$  is the largest [open subset](#)  $\text{Int}(S) \in \tau$  still contained in  $S$ ,  $\text{Int}(S) \subset S \subset X$ :

$$\text{Int}(S) := \bigcup_{\substack{O \subset S \\ O \subset X \text{ open}}} (O) .$$

The [boundary](#)  $\partial S$  of  $S$  is the [complement](#) of its interior inside its [topological closure](#) (def. 2.21):

$$\partial S := \text{Cl}(S) \setminus \text{Int}(S) .$$

**Lemma 2.25. (duality between closure and interior)**

Let  $(X, \tau)$  be a [topological space](#) and let  $S \subset X$  be a [subset](#). Then the [topological interior](#) of  $S$  (def. 2.24) is the same as the [complement](#) of the [topological closure](#)  $\text{Cl}(X \setminus S)$  of the complement of  $S$ :

$$X \setminus \text{Int}(S) = \text{Cl}(X \setminus S)$$

and conversely

$$X \setminus \text{Cl}(S) = \text{Int}(X \setminus S) .$$

**Proof.** Using remark 2.22, we compute as follows:

$$\begin{aligned} X \setminus \text{Int}(S) &= X \setminus \left( \bigcup_{\substack{U \subset S \\ U \subset X \text{ open}}} U \right) \\ &= \bigcap_{\substack{U \subset S \\ U \subset X \text{ open}}} (X \setminus U) \\ &= \bigcap_{\substack{C \supset X \setminus S \\ C \text{ closed}}} (C) \\ &= \text{Cl}(X \setminus S) \end{aligned}$$

Similarly for the other case. ■

**Example 2.26. ([topological closure](#) and [interior](#) of [closed](#) and [open intervals](#))**

Regard the [real numbers](#) as the 1-dimensional [Euclidean space](#) (example 1.6) and equipped with the corresponding [metric topology](#) (example 2.9) . Let  $a < b \in \mathbb{R}$ . Then the [topological interior](#) (def. 2.24) of the [closed interval](#)  $[a, b] \subset \mathbb{R}$  (example 1.12) is the [open interval](#)  $(a, b) \subset \mathbb{R}$ , moreover the closed interval is its own [topological closure](#) (def. 2.21) and the converse holds (by lemma 2.25):

$$\begin{aligned} \text{Cl}((a, b)) &= [a, b] & \text{Int}((a, b)) &= (a, b) \\ \text{Cl}([a, b]) &= [a, b] & \text{Int}([a, b]) &= (a, b) \end{aligned}$$

Hence the [boundary](#) of the closed interval is its endpoints, while the boundary of the open interval is empty

$$\partial[a, b] = \{a\} \cup \{b\} \quad \partial(a, b) = \emptyset .$$

The terminology “closed” subspace for complements of opens is justified by the following statement, which is a further example of how the combinatorial concept of open subsets captures key phenomena in [analysis](#):

**Proposition 2.27. ([convergence in closed subspaces](#))**

Let  $(X, d)$  be a [metric space](#) (def. 1.1), regarded as a [topological space](#) via



example 2.9, and let  $V \subset X$  be a [subset](#). Then the following are equivalent:

1.  $V \subset X$  is a [closed subspace](#) according to def. 2.21.
2. For every [sequence](#)  $x_i \in V \subset X$  (def. 1.15) with elements in  $V$ , which [converges](#) as a sequence in  $X$  (def. 1.16) to some  $x_\infty \in X$ , then  $x_\infty \in V \subset X$ .

**Proof.** First assume that  $V \subset X$  is closed and that  $x_i \xrightarrow{i \rightarrow \infty} x_\infty$  for some  $x_\infty \in X$ . We need to show that then  $x_\infty \in V$ . Suppose it were not, hence that  $x_\infty \in X \setminus V$ . Since, by assumption on  $V$ , this [complement](#)  $X \setminus V \subset X$  is an [open subset](#), it would follow that there exists a [real number](#)  $\epsilon > 0$  such that the [open ball](#) around  $x$  of radius  $\epsilon$  were still contained in the complement:  $B_x^\circ(\epsilon) \subset X \setminus V$ . But since the sequence is assumed to converge in  $X$ , this would mean that there exists  $N_\epsilon$  such that all  $x_{i > N_\epsilon}$  are in  $B_x^\circ(\epsilon)$ , hence in  $X \setminus V$ . This contradicts the assumption that all  $x_i$  are in  $V$ , and hence we have [proved by contradiction](#) that  $x_\infty \in V$ .

Conversely, assume that for all sequences in  $V$  that converge to some  $x_\infty \in X$  then  $x_\infty \in V \subset X$ . We need to show that then  $V$  is closed, hence that  $X \setminus V \subset X$  is an open subset, hence that for every  $x \in X \setminus V$  we may find a real number  $\epsilon > 0$  such that the [open ball](#)  $B_x^\circ(\epsilon)$  around  $x$  of radius  $\epsilon$  is still contained in  $X \setminus V$ . Suppose on the contrary that such  $\epsilon$  did not exist. This would mean that for each  $k \in \mathbb{N}$  with  $k \geq 1$  then the [intersection](#)  $B_x^\circ(1/k) \cap V$  were [non-empty](#). Hence then we could choose points  $x_k \in B_x^\circ(1/k) \cap V$  in these intersections. These would form a sequence which clearly converges to the original  $x$ , and so by assumption we would conclude that  $x \in V$ , which violates the assumption that  $x \in X \setminus V$ . Hence we [proved by contradiction](#)  $X \setminus V$  is in fact open. ■

A special role in the theory is played by the “irreducible” closed subspaces:

### Definition 2.28. ([irreducible closed subspace](#))

A [closed subset](#)  $S \subset X$  (def. 2.21) of a [topological space](#)  $X$  is called [irreducible](#) if it is [non-empty](#) and not the [union](#) of two closed proper (i.e. smaller) subsets. In other words, a [non-empty](#) closed subset  $S \subset X$  is irreducible if whenever  $S_1, S_2 \subset X$  are two [closed subspace](#) such that

$$S = S_1 \cup S_2$$

then  $S_1 = S$  or  $S_2 = S$ .

### Example 2.29. (closures of points are irreducible)

For  $x \in X$  a [point](#) inside a [topological space](#), then the [closure](#)  $\text{Cl}(\{x\})$  of the [singleton subset](#)  $\{x\} \subset X$  is [irreducible](#) (def. 2.28).

### Example 2.30. (no nontrivial closed irreducibles in metric spaces)

Let  $(X, d)$  be a [metric space](#), regarded as a [topological space](#) via its [metric topology](#) (example 2.9). Then every point  $x \in X$  is closed (def 2.21), hence

every singleton subset  $\{x\} \subset X$  is irreducible according to def. 2.29.

Let  $\mathbb{R}$  be the 1-dimensional [Euclidean space](#) (example 1.6) with its [metric topology](#) (example 2.9). Then for  $a < c \in \mathbb{R}$  the closed interval  $[a, c] \subset \mathbb{R}$  (example 1.12) is *not* irreducible, since for any  $b \in \mathbb{R}$  with  $a < b < c$  it is the union of two smaller closed subintervals:

$$[a, c] = [a, b] \cup [b, c] .$$

In fact we will see below (prop. 5.3) that in a metric space the singleton subsets are precisely the only irreducible closed subsets.

Often it is useful to re-express the condition of irreducibility of closed subspaces in terms of complementary open subsets:

**Proposition 2.31. (*irreducible closed subsets in terms of prime open subsets*)**

Let  $(X, \tau)$  be a [topological space](#), and let  $P \in \tau$  be a proper [open subset](#) of  $X$ , hence so that the [complement](#)  $F := X \setminus P$  is a [non-empty closed subspace](#). Then  $F$  is [irreducible](#) in the sense of def. 2.28 precisely if whenever  $U_1, U_2 \in \tau$  are open subsets with  $U_1 \cup U_2 \subset P$  then  $U_1 \subset P$  or  $U_2 \subset P$ :

$$(X \setminus P \text{ irreducible}) \Leftrightarrow \left( \bigvee_{U_1, U_2 \in \tau} ((U_1 \cup U_2 \subset P) \Rightarrow (U_1 \subset P \text{ or } U_2 \subset P)) \right) .$$

The open subset  $P \subset X$  with this property are also called the *prime open subsets* in  $\tau_X$ .

**Proof.** Observe that every [closed subset](#)  $F_i \subset F$  may be exhibited as the [complement](#)

$$F_i = F \setminus U_i$$

of some open subset  $U_i \in \tau$  with respect to  $F$ . Observe that under this identification the condition that  $U_1 \cup U_2 \subset P$  is equivalent to the condition that  $F_1 \cup F_2 = F$ , because it is equivalent to the equation labeled  $(\star)$  in the following sequence of equations:

$$\begin{aligned} F_1 \cup F_2 &= (F \setminus U_1) \cup (F \setminus U_2) \\ &= (X \setminus (P \cup U_1)) \cup (X \setminus (P \cup U_2)) \\ &= X \setminus ((P \cup U_1) \cap (P \cup U_2)) \\ &= X \setminus (P \cup (U_1 \cap U_2)) \\ &\stackrel{(\star)}{=} X \setminus P \\ &= F . \end{aligned}$$

Similarly, the condition that  $U_i \subset P$  is equivalent to the condition that  $F_i = F$ , because it is equivalent to the equality  $(\star)$  in the following sequence of equalities:

$$\begin{aligned}
 F_i &= F \setminus U_i \\
 &= X \setminus (P \cup U_i) \\
 &\stackrel{(*)}{=} X \setminus P \\
 &= F
 \end{aligned}$$

Under these identifications, the two conditions are manifestly the same. ■

We consider yet another equivalent characterization of irreducible closed subsets, prop. 2.35 below, which will be needed in the discussion of the *separation axioms?* further below. Stating this requires the following concept of “[frame homomorphism](#)”, the natural kind of [homomorphisms](#) between [topological spaces](#) if we were to forget the underlying set of points of a topological space, and only remember the set  $\tau_X$  with its operations induced by taking finite intersections and arbitrary unions:

**Definition 2.32. ([frame homomorphisms](#))**

Let  $(X, \tau_X)$  and  $(Y, \tau_Y)$  be [topological spaces](#) (def. 2.3). Then a function

$$\tau_X \leftarrow \tau_Y : \phi$$

between their [sets of open subsets](#) is called a [frame homomorphism](#) if it preserves

1. arbitrary [unions](#);
2. [finite intersections](#).

In other words,  $\phi$  is a frame homomorphism precisely if

1. for every [set](#)  $I$  and every  $I$ -indexed set  $\{U_i \in \tau_Y\}_{i \in I}$  of elements of  $\tau_Y$ , then

$$\phi\left(\bigcup_{i \in I} U_i\right) = \bigcup_{i \in I} \phi(U_i) \in \tau_X,$$

2. for every [finite set](#)  $J$  and every  $J$ -indexed set  $\{U_j \in \tau_Y\}_{j \in J}$  of elements in  $\tau_Y$ , then

$$\phi\left(\bigcap_{j \in J} U_j\right) = \bigcap_{j \in J} \phi(U_j) \in \tau_X.$$

**Remark 2.33. ([frame homomorphisms preserve inclusions](#))**

A [frame homomorphism](#)  $\phi$  as in def. 2.32 necessarily also preserves inclusions in that

- for every inclusion  $U_1 \subset U_2$  with  $U_1, U_2 \in \tau_Y \subset P(Y)$  then

$$\phi(U_1) \subset \phi(U_2) \in \tau_X.$$

This is because inclusions are witnessed by unions

$$(U_1 \subset U_2) \Leftrightarrow (U_1 \cup U_2 = U_2)$$

or alternatively because inclusions are witnessed by finite intersections:

$$(U_1 \subset U_2) \Leftrightarrow (U_1 \cap U_2 = U_1) .$$

**Example 2.34. (pre-images of continuous functions are frame homomorphisms)**

Let  $(X, \tau_X)$  and  $(Y, \tau_Y)$  be two [topological spaces](#). One way to obtain a function between their sets of open subsets

$$\tau_X \leftarrow \tau_Y : \phi$$

is to specify a function

$$f : X \rightarrow Y$$

of their underlying sets, and take  $\phi := f^{-1}$  to be the [pre-image](#) operation. A priori this is a function of the form

$$P(Y) \leftarrow P(X) : f^{-1}$$

and hence in order for this to co-restrict to  $\tau_X \subset P(X)$  when restricted to  $\tau_Y \subset P(Y)$  we need to demand that, under  $f$ , pre-images of open subsets of  $Y$  are open subsets of  $Z$ . Below in def. [3.1](#) we highlight these as the [continuous functions](#) between topological spaces.

$$f : (X, \tau_X) \rightarrow (Y, \tau_Y)$$

In this case then

$$\tau_X \leftarrow \tau_Y : f^{-1}$$

is a frame homomorphism in the sense of def. [2.32](#).

For the following recall from example [2.10](#) the [point topological space](#)

$$* = (\{1\}, \tau_* = \{\emptyset, \{1\}\}).$$

**Proposition 2.35. (irreducible closed subsets are equivalently frame homomorphisms to opens of the point)**

For  $(X, \tau)$  a [topological space](#), then there is a [natural bijection](#) between the [irreducible closed subspaces](#) of  $(X, \tau)$  (def. [2.28](#)) and the [frame homomorphisms](#) from  $\tau_X$  to  $\tau_*$ , and this bijection is given by

$$\begin{aligned} \text{FrameHom}(\tau_X, \tau_*) &\xrightarrow{\cong} \text{IrrClSub}(X) \\ \phi &\mapsto X \setminus (U_\emptyset(\phi)) \end{aligned}$$

where  $U_\emptyset(\phi)$  is the [union](#) of all elements  $U \in \tau_x$  such that  $\phi(U) = \emptyset$ :

$$U_\emptyset(\phi) := \bigcup_{\substack{U \in \tau_X \\ \phi(U) = \emptyset}} (U) .$$

See also ([Johnstone 82, II 1.3](#)).

**Proof.** First we need to show that the function is well defined in that given a frame homomorphism  $\phi: \tau_X \rightarrow \tau_*$  then  $X \setminus U_\emptyset(\phi)$  is indeed an irreducible closed subspace.

To that end observe that:

(\*) *If there are two elements  $U_1, U_2 \in \tau_X$  with  $U_1 \cap U_2 \subset U_\emptyset(\phi)$  then  $U_1 \subset U_\emptyset(\phi)$  or  $U_2 \subset U_\emptyset(\phi)$ .*

This is because

$$\begin{aligned} \phi(U_1) \cap \phi(U_2) &= \phi(U_1 \cap U_2) \\ &\subset \phi(U_\emptyset(\phi)) \quad , \\ &= \emptyset \end{aligned}$$

where the first equality holds because  $\phi$  preserves finite intersections by def. [2.32](#), the inclusion holds because  $\phi$  respects inclusions by remark [2.33](#), and the second equality holds because  $\phi$  preserves arbitrary unions by def. [2.32](#). But in  $\tau_* = \{\emptyset, \{1\}\}$  the intersection of two open subsets is empty precisely if at least one of them is empty, hence  $\phi(U_1) = \emptyset$  or  $\phi(U_2) = \emptyset$ . But this means that  $U_1 \subset U_\emptyset(\phi)$  or  $U_2 \subset U_\emptyset(\phi)$ , as claimed.

Now according to prop. [2.31](#) the condition (\*) identifies the [complement](#)  $X \setminus U_\emptyset(\phi)$  as an [irreducible closed subspace](#) of  $(X, \tau)$ .

Conversely, given an irreducible closed subset  $X \setminus U_0$ , define  $\phi$  by

$$\phi : U \mapsto \begin{cases} \emptyset & \text{if } U \subset U_0 \\ \{1\} & \text{otherwise} \end{cases} .$$

This does preserve

### 1. arbitrary unions

because  $\phi(\bigcup_i U_i) = \{\emptyset\}$  precisely if  $\bigcup_i U_i \subset U_0$  which is the case precisely if all  $U_i \subset U_0$ , which means that all  $\phi(U_i) = \emptyset$  and because  $\bigcup_i \emptyset = \emptyset$ ;

while  $\phi(\bigcup_i U_i) = \{1\}$  as soon as one of the  $U_i$  is not contained in  $U_0$ , which means that one of the  $\phi(U_i) = \{1\}$  which means that  $\bigcup_i \phi(U_i) = \{1\}$ ;

### 2. finite intersections

because if  $U_1 \cap U_2 \subset U_0$ , then by (\*)  $U_1 \subset U_0$  or  $U_2 \subset U_0$ , whence  $\phi(U_1) = \emptyset$  or

$\phi(U_2) = \emptyset$ , whence with  $\phi(U_1 \cap U_2) = \emptyset$  also  $\phi(U_1) \cap \phi(U_2) = \emptyset$ ;

while if  $U_1 \cap U_2$  is not contained in  $U_0$  then neither  $U_1$  nor  $U_2$  is contained in  $U_0$  and hence with  $\phi(U_1 \cap U_2) = \{1\}$  also  $\phi(U_1) \cap \phi(U_2) = \{1\} \cap \{1\} = \{1\}$ .

Hence this is indeed a frame homomorphism  $\tau_X \rightarrow \tau_*$ .

Finally, it is clear that these two operations are inverse to each other. ■

### 3. Continuous functions

With the concept of [topological spaces](#) in hand (def. 2.3) it is now immediate to formally implement in abstract generality the statement of prop. 1.13:

#### principle of continuity

*Continuous pre-Images of open subsets are open.*

#### Definition 3.1. (continuous function)

A [continuous function](#) between [topological spaces](#) (def. 2.3)

$$f: (X, \tau_X) \rightarrow (Y, \tau_Y)$$

is a [function](#) between the underlying sets,

$$f: X \rightarrow Y$$

such that [pre-images](#) under  $f$  of open subsets of  $Y$  are open subsets of  $X$ .

We may equivalently state this in terms of [closed subsets](#):

**Proposition 3.2.** *Let  $(X_1, \tau_X)$  and  $(Y, \tau_Y)$  be two [topological spaces](#) (def. 2.3). Then a [function](#)*

$$f: X \rightarrow Y$$

*between the underlying [sets](#) is [continuous](#) in the sense of def. 3.1 precisely if [pre-images](#) under  $f$  of [closed subsets](#) of  $Y$  (def. 2.21) are closed subsets of  $X$ .*

**Proof.** This follows since taking [pre-images](#) commutes with taking [complements](#). ■

Before looking at first examples of continuous functions [below](#) we consider now an informal remark on the resulting global structure, the “[category of topological spaces](#)”, remark 3.3 below. This is a language that serves to make transparent key phenomena in [topology](#) which we encounter further below, such as the

Tn-reflection (remark 4.23 below), and the universal constructions.

**Remark 3.3. (concrete category of topological spaces)**

For  $X_1, X_2, X_3$  three topological spaces and for

$$X_1 \xrightarrow{f} X_2 \quad \text{and} \quad X_2 \xrightarrow{g} X_3$$

two continuous functions (def. 3.1) then their composition

$$f_2 \circ f_1 : X_1 \xrightarrow{f} X_2 \xrightarrow{f_2} X_3$$

is clearly itself again a continuous function from  $X_1$  to  $X_3$ . Moreover, this composition operation is clearly associative, in that for

$$X_1 \xrightarrow{f} X_2 \quad \text{and} \quad X_2 \xrightarrow{g} X_3 \quad \text{and} \quad X_3 \xrightarrow{h} X_4$$

three continuous functions, then

$$f_3 \circ (f_2 \circ f_1) = (f_3 \circ f_2) \circ f_1 : X_1 \rightarrow X_3 .$$

Finally, the composition operation is also clearly unital, in that for each topological space  $X$  there exists the identity function  $\text{id}_X : X \rightarrow X$  and for  $f : X_1 \rightarrow X_2$  any continuous function then

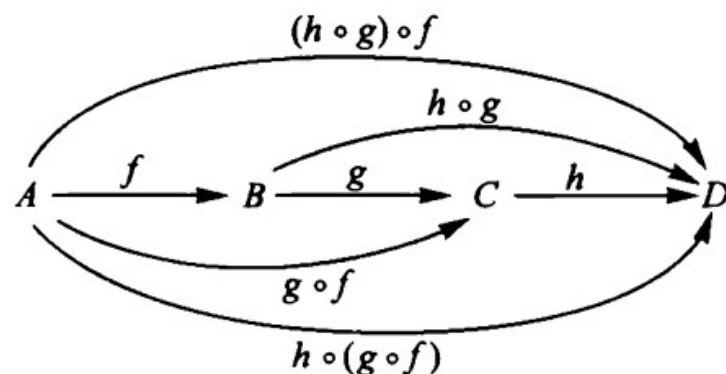
$$\text{id}_{X_2} \circ f = f = f \circ \text{id}_{X_1} .$$

One summarizes this situation by saying that:

1. topological spaces constitute the objects,
2. continuous functions constitute the morphisms (homomorphisms)

of a category, called the category of topological spaces (“Top” for short).

It is useful to depict collections of objects with morphisms between them by diagrams, like this one:



graphics grabbed from Lawvere-Schanuel 09.

There are other categories. For instance there is the category of sets (“Set” for short) whose



1. objects are sets,
2. morphisms are plain functions between these.

The two categories Top and Set are different, but related. After all,

1. an object of Top (hence a topological space) is an object of Set (hence a set) equipped with extra structure (namely with a topology);
2. a morphism in Top (hence a continuous function) is a morphism in Set (hence a plain function) with the extra property that it preserves this extra structure.

Hence we have the *underlying set assigning function*

$$\begin{array}{ccc} \text{Top} & \xrightarrow{U} & \text{Set} \\ (X, \tau) & \longmapsto & X \end{array}$$

from the class of topological spaces to the class of sets. But more is true: every continuous function between topological spaces is, by definition, in particular a function on underlying sets:

$$\begin{array}{ccccc} \text{Top} & \xrightarrow{U} & \text{Set} & & \\ (X, \tau_X) & \longmapsto & X & & \\ f \downarrow & \mapsto & \downarrow f & & \\ (Y, \tau_Y) & \longmapsto & Y & & \end{array}$$

and this assignment (trivially) respects the composition of morphisms and the identity morphisms.

Such a function between classes of objects of categories, which is extended to a function on the sets of homomorphisms between these objects in a way that respects composition and identity morphisms is called a functor. If we write an arrow between categories

$$U : \text{Top} \longrightarrow \text{Set}$$

then it is understood that we mean not just a function between their classes of objects, but a functor.

The functor  $U$  at hand has the special property that it does not do much except forgetting extra structure, namely the extra structure on a set  $X$  given by a choice of topology  $\tau_X$ . One also speaks of a forgetful functor.

This is intuitively clear, and we may easily formalize it: The functor  $U$  has the special property that as a function between sets of homomorphisms ("hom sets", for short) it is injective. More in detail, given topological spaces  $(X, \tau_X)$  and  $(Y, \tau_Y)$  then the component function of  $U$  from the set of continuous function

between these spaces to the set of plain functions between their underlying sets

$$\left\{ (X, \tau_X) \xrightarrow[\text{function}]{\text{continuous}} (Y, \tau_Y) \right\} \xrightarrow{U} \left\{ X \xrightarrow{\text{function}} Y \right\}$$

is an [injective function](#), including the continuous functions among all functions of underlying sets.

A [functor](#) with this property, that its component functions between all [hom-sets](#) are injective, is called a [faithful functor](#).

A [category](#) equipped with a [faithful functor](#) to [Set](#) is called a [concrete category](#).

Hence [Top](#) is canonically a [concrete category](#).

### Example 3.4. ([product topological space construction is functorial](#))

For  $\mathcal{C}$  and  $\mathcal{D}$  two [categories](#) as in remark 3.3 (for instance [Top](#) or [Set](#)) then we obtain a new category denoted  $\mathcal{C} \times \mathcal{D}$  and called their [product category](#) whose

1. [objects](#) are [pairs](#)  $(c, d)$  with  $c$  an object of  $\mathcal{C}$  and  $d$  an object of  $\mathcal{D}$ ;
- [morphisms](#) are [pairs](#)  $(f, g): (c, d) \rightarrow (c', d')$  with  $f: c \rightarrow c'$  a morphism of  $\mathcal{C}$  and  $g: d \rightarrow d'$  a morphisms of  $\mathcal{D}$ ,
- [composition](#) of morphisms is defined pairwise  $(f', g') \circ (f, g) := (f' \circ f, g' \circ g)$ .

This concept secretly underlies the construction of [product topological spaces](#):

Let  $(X_1, \tau_{X_1})$ ,  $(X_2, \tau_{X_2})$ ,  $(Y_1, \tau_{Y_1})$  and  $(Y_2, \tau_{Y_2})$  be [topological spaces](#). Then for all [pairs](#) of [continuous functions](#)

$$f_1 : (X_1, \tau_{X_1}) \rightarrow (Y_1, \tau_{Y_1})$$

and

$$f_2 : (X_2, \tau_{X_2}) \rightarrow (Y_2, \tau_{Y_2})$$

the canonically induced function on [Cartesian products](#) of sets

$$\begin{array}{ccc} X_1 \times X_2 & \xrightarrow{f_1 \times f_2} & Y_1 \times Y_2 \\ (x_1, x_2) & \mapsto & (f_1(x_1), f_2(x_2)) \end{array}$$

is a [continuous function](#) with respect to the [binary product space topologies](#) (def. 2.18)

$$f_1 \times f_2 : (X_1 \times X_2, \tau_{X_1 \times X_2}) \rightarrow (Y_1 \times Y_2, \tau_{Y_1 \times Y_2}) .$$

Moreover, this construction respects [identity functions](#) and [composition](#) of functions in both arguments.

In the language of [category theory](#) (remark 3.3), this is summarized by saying

that the [product topological space](#) construction  $(-) \times (-)$  extends to a [functor](#) from the [product category](#) of the [category Top](#) with itself to itself:

$$(-) \times (-) : \mathbf{Top} \times \mathbf{Top} \rightarrow \mathbf{Top} .$$

## Examples

We discuss here some basic examples of [continuous functions](#) (def. 3.1) between [topological spaces](#) (def. 2.3) to get a feeling for the nature of the concept. But as with topological spaces themselves, continuous functions between them are ubiquitous in mathematics, and no list will exhaust all classes of examples. Below in the section [Universal constructions](#) we discuss a general principle that serves to produce examples of continuous functions with prescribed “[universal properties](#)”.

### Example 3.5. (point space is [terminal](#))

For  $(X, \tau)$  any [topological space](#), then there is a unique continuous function

$$X \rightarrow *$$

from  $X$  to the [point topological space](#) (def. 2.10).

In the language of [category theory](#) (remark 3.3), this says that the point  $*$  is the [terminal object](#) in the [category Top](#) of topological spaces.

### Example 3.6. ([constant continuous functions](#))

For  $(X, \tau)$  a [topological space](#) then for  $x \in X$  any element of the underlying set, there is a unique continuous function (which we denote by the same symbol)

$$x : * \rightarrow X$$

from the [point topological space](#) (def. 2.10), whose image in  $X$  is that element. Hence there is a [natural bijection](#)

$$\left\{ * \xrightarrow{f} X \mid f \text{ continuous} \right\} \simeq X$$

between the continuous functions from the point to any topological space, and the underlying set of that topological space.

More generally, for  $(X, \tau_X)$  and  $(Y, \tau_Y)$  two topological spaces, then a continuous function  $X \rightarrow Y$  between them is called a [constant function](#) with value some point  $y \in Y$  if it factors through the point spaces as

$$\text{const}_y : X \xrightarrow{\exists!} * \xrightarrow{y} Y .$$

### Definition 3.7. ([locally constant function](#))

For  $(X, \tau_X), (Y, \tau_Y)$  two [topological spaces](#), then a [continuous function](#)  $f: (X, \tau_X) \rightarrow (Y, \tau_Y)$  (def. 3.1) is called [locally constant](#) if every point  $x \in X$  has a [neighbourhood](#) on which the function is constant.

### Example 3.8. ([continuous functions](#) into and out of [discrete](#) and [codiscrete spaces](#))

Let  $S$  be a [set](#) and let  $(X, \tau)$  be a [topological space](#). Recall from example 2.13

1. the [discrete topological space](#)  $\text{Disc}(S)$ ;
2. the [co-discrete topological space](#)  $\text{CoDisc}(S)$

on the underlying set  $S$ . Then [continuous functions](#) (def. 3.1) into/out of these satisfy:

1. every [function](#) (of sets)  $\text{Disc}(S) \rightarrow X$  out of a discrete space is [continuous](#);
2. every [function](#) (of sets)  $X \rightarrow \text{CoDisc}(S)$  into a codiscrete space is [continuous](#).

Also:

- every [continuous function](#)  $(X, \tau) \rightarrow \text{Disc}(S)$  into a discrete space is [locally constant](#) (def. 3.7).

### Example 3.9. ([diagonal](#))

For  $X$  a [set](#), its [diagonal](#)  $\Delta_X$  is the [function](#) from  $X$  to the [Cartesian product](#) of  $X$  with itself, given by

$$\begin{aligned} X &\xrightarrow{\Delta_X} X \times X \\ x &\mapsto (x, x) \end{aligned}$$

For  $(X, \tau)$  a [topological space](#), then the diagonal is a [continuous function](#) to the [product topological space](#) (def. 2.18) of  $X$  with itself.

$$\Delta_X : (X, \tau) \rightarrow (X \times X, \tau_{X \times X}) .$$

To see this, it is sufficient to see that the [preimages](#) of [basic opens](#)  $U_1 \times U_2$  in  $\tau_{X \times X}$  are in  $\tau_X$ . But these pre-images are the [intersections](#)  $U_1 \cap U_2 \subset X$ , which are open by the axioms on the topology  $\tau_X$ .

### Example 3.10. ([image factorization](#))

Let  $f : (X, \tau_X) \rightarrow (Y, \tau_Y)$  be a [continuous function](#).

Write  $f(X) \subset Y$  for the [image](#) of  $f$  on underlying sets, and consider the resulting factorization of  $f$  through  $f(X)$  on underlying sets:

$$f : X \xrightarrow{\text{surjective}} f(X) \xrightarrow{\text{injective}} Y .$$

There are the following two ways to topologize the [image](#)  $f(X)$  such as to make this a sequence of two continuous functions:

1. By example [2.16](#)  $f(X)$  inherits a [subspace topology](#) from  $(Y, \tau_Y)$  which evidently makes the inclusion  $f(X) \rightarrow Y$  a [continuous function](#).

Observe that this also makes  $X \rightarrow f(X)$  a continuous function: An open subset of  $f(X)$  in this case is of the form  $U_Y \cap f(X)$  for  $U_Y \in \tau_Y$ , and  $f^{-1}(U_Y \cap f(X)) = f^{-1}(U_Y)$ , which is open in  $X$  since  $f$  is continuous.

2. By example [2.17](#)  $f(X)$  inherits a [quotient topology](#) from  $(X, \tau_X)$  which evidently makes the surjection  $X \rightarrow f(X)$  a [continuous function](#).

Observe that this also makes  $f(X) \rightarrow Y$  a continuous function: The preimage under this map of an open subset  $U_Y \in \tau_Y$  is the restriction  $U_Y \cap f(X)$ , and the pre-image of that under  $X \rightarrow f(X)$  is  $f^{-1}(U_Y)$ , as before, which is open since  $f$  is continuous, and therefore  $U_Y \cap f(X)$  is open in the quotient topology.

Beware that in general a continuous function itself (as opposed to its [pre-image](#) function) neither preserves [open subsets](#), nor [closed subsets](#), as the following examples show:

**Example 3.11.** Regard the [real numbers](#)  $\mathbb{R}$  as the 1-dimensional [Euclidean space](#) (example [1.6](#)) equipped with the [metric topology](#) (example [2.9](#)). For  $a \in \mathbb{R}$  the [constant function](#) (example [3.6](#))

$$\begin{array}{ccc} \mathbb{R} & \xrightarrow{\text{const}_a} & \mathbb{R} \\ x & \mapsto & a \end{array}$$

maps every [open subset](#)  $U \subset \mathbb{R}$  to the [singleton set](#)  $\{a\} \subset \mathbb{R}$ , which is not open.

**Example 3.12.** Write  $\text{Disc}(\mathbb{R})$  for the set of [real numbers](#) equipped with its [discrete topology](#) (def. [2.13](#)) and  $\mathbb{R}$  for the set of [real numbers](#) equipped with its [Euclidean metric topology](#) (example [1.6](#), example [2.9](#)). Then the [identity function](#) on the underlying sets

$$\text{id}_{\mathbb{R}} : \text{Disc}(\mathbb{R}) \rightarrow \mathbb{R}$$

is a [continuous function](#) (a special case of example [3.8](#)). A [singleton subset](#)  $\{a\} \in \text{Disc}(\mathbb{R})$  is open, but regarded as a subset  $\{a\} \in \mathbb{R}$  it is not open.

**Example 3.13.** Consider the set of [real numbers](#)  $\mathbb{R}$  equipped with its [Euclidean metric topology](#) (example [1.6](#), example [2.9](#)). The [exponential function](#)

$$\exp(-) : \mathbb{R} \rightarrow \mathbb{R}$$

maps all of  $\mathbb{R}$  (which is a closed subset, since  $\mathbb{R} = \mathbb{R} \setminus \emptyset$ ) to the [open interval](#)

$(0, \infty) \subset \mathbb{R}$ , which is not closed.

Those continuous functions that do happen to preserve open or closed subsets get a special name:

**Definition 3.14. (open maps and closed maps)**

A continuous function  $f: (X, \tau_X) \rightarrow (Y, \tau_Y)$  (def. 3.1) is called

- an open map if the image under  $f$  of an open subset of  $X$  is an open subset of  $Y$ ;
- a closed map if the image under  $f$  of a closed subset of  $X$  (def. 2.21) is a closed subset of  $Y$ .

**Example 3.15. (projections are open)**

For  $(X_1, \tau_{X_1})$  and  $(X_2, \tau_{X_2})$  two topological spaces, then the projection maps

$$\pi_i : (X_1 \times X_2, \tau_{X_1 \times X_2}) \rightarrow (X_i, \tau_{X_i})$$

out of their product topological space (def. 2.18)

$$X_1 \times X_2 \xrightarrow{\pi_1} X_1$$

$$(x_1, x_2) \mapsto x_1$$

$$X_1 \times X_2 \xrightarrow{\pi_2} X_2$$

$$(x_1, x_2) \mapsto x_2$$

are open maps (def. 3.14).

Below in prop. 6.24 we find a large supply of closed maps.

Sometimes it is useful to recognize quotient topological space projections via saturated subsets (essentially another term for pre-images of underlying sets):

**Definition 3.16. (saturated subset)**

Let  $f : X \rightarrow Y$  be a function of sets. Then a subset  $S \subset X$  is called an  $f$ -saturated subset (or just *saturated subset*, if  $f$  is understood) if  $S$  is the pre-image of its image:

$$(S \subset X \text{ } f\text{-saturated}) \Leftrightarrow (S = f^{-1}(f(S))) .$$

Here  $f^{-1}(f(S))$  is also called the  *$f$ -saturation* of  $S$ .

**Example 3.17. (pre-images are saturated subsets)**

For  $f : X \rightarrow Y$  any function of sets, and  $S_Y \subset Y$  any subset of  $Y$ , then the

**pre-image**  $f^{-1}(S_Y) \subset X$  is an  **$f$ -saturated subset** of  $X$  (def. 3.16).

Observe that:

**Lemma 3.18.** *Let  $f: X \rightarrow Y$  be a **function**. Then a **subset**  $S \subset X$  is  **$f$ -saturated** (def. 3.16) precisely if its **complement**  $X \setminus S$  is saturated.*

**Proposition 3.19. (recognition of quotient topologies)**

A **continuous function** (def. 3.1)

$$f : (X, \tau_X) \rightarrow (Y, \tau_Y)$$

whose underlying function  $f: X \rightarrow Y$  is **surjective** exhibits  $\tau_Y$  as the corresponding **quotient topology** (def. 2.17) precisely if  $f$  sends open and  **$f$ -saturated subsets** in  $X$  (def. 3.16) to open subsets of  $Y$ . By lemma 3.18 this is the case precisely if it sends closed and  **$f$ -saturated subsets** to closed subsets.

We record the following technical lemma about saturated subspaces, which we will need below to prove prop. 6.28.

**Lemma 3.20. (saturated open neighbourhoods of saturated closed subsets under closed maps)**

Let

1.  $f : (X, \tau_X) \rightarrow (Y, \tau_Y)$  be a **closed map** (def. 3.14);
2.  $C \subset X$  be a **closed subset** of  $X$  (def. 2.21) which is  **$f$ -saturated** (def. 3.16);
3.  $U \supset C$  be an **open subset** containing  $C$ ;

then there exists a smaller open subset  $V$  still containing  $C$

$$U \supset V \supset C$$

and such that  $V$  is still  **$f$ -saturated**.

**Proof.** We claim that the **complement** of  $X$  by the  $f$ -saturation (def. 3.16) of the complement of  $X$  by  $U$

$$V := X \setminus (f^{-1}(f(X \setminus U)))$$

has the desired properties. To see this, observe first that

1. the **complement**  $X \setminus U$  is closed, since  $U$  is assumed to be open;
2. hence the image  $f(X \setminus U)$  is closed, since  $f$  is assumed to be a closed map;
3. hence the pre-image  $f^{-1}(f(X \setminus U))$  is closed, since  $f$  is continuous (using prop. 3.2), therefore its complement  $V$  is indeed open;



4. this pre-image  $f^{-1}(f(X \setminus U))$  is saturated (by example 3.17) and hence also its complement  $V$  is saturated (by lemma 3.18).

Therefore it now only remains to see that  $U \supset V \supset C$ .

By [de Morgan's law](#) (remark 2.22) the inclusion  $U \supset V$  is equivalent to the inclusion  $f^{-1}(f(X \setminus U)) \supset X \setminus U$ , which is clearly the case.

The inclusion  $V \supset C$  is equivalent to  $f^{-1}(f(X \setminus U)) \cap C = \emptyset$ . Since  $C$  is saturated by assumption, this is equivalent to  $f^{-1}(f(X \setminus U)) \cap f^{-1}(f(C)) = \emptyset$ . This in turn holds precisely if  $f(X \setminus U) \cap f(C) = \emptyset$ . Since  $C$  is saturated, this holds precisely if  $X \setminus U \cap C = \emptyset$ , and this is true by the assumption that  $U \supset C$ . ■

## Homeomorphisms

With the [objects](#) ([topological spaces](#)) and the [morphisms](#) ([continuous functions](#)) of the [category Top](#) thus defined (remark 3.3), we obtain the concept of “sameness” in topology. To make this precise, one says that a [morphism](#)

$$X \xrightarrow{f} Y$$

in a [category](#) is an [isomorphism](#) if there exists a morphism going the other way around

$$X \xleftarrow{g} Y$$

which is an [inverse](#) in the sense that both its [compositions](#) with  $f$  yield an [identity morphism](#):

$$f \circ g = \text{id}_Y \quad \text{and} \quad g \circ f = \text{id}_X .$$

Since such  $g$  is unique if it exists, one often writes “ $f^{-1}$ ” for this [inverse morphism](#). However, in the context of [topology](#) then  $f^{-1}$  usually refers to the [pre-image](#) function of a given [function](#)  $f$ , and in these notes we will stick to this usage and never use “ $(-)^{-1}$ ” to denote [inverses](#).

### Definition 3.21. ([homeomorphisms](#))

An [isomorphism](#) in the [category Top](#) (remark 3.3) of [topological spaces](#) (def. 2.3) with [continuous functions](#) between them (def. 3.1) is called a [homeomorphism](#).

Hence a [homeomorphism](#) is a [continuous function](#)

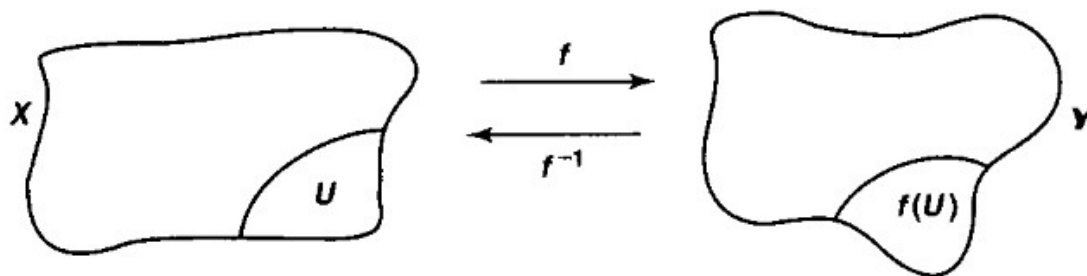
$$f : (X, \tau_X) \rightarrow (Y, \tau_Y)$$

between two [topological spaces](#)  $(X, \tau_X)$ ,  $(Y, \tau_Y)$  such that there exists another continuous function the other way around

$$(X, \tau_X) \leftarrow (Y, \tau_Y) : g$$

such that their [composites](#) are the [identity functions](#) on  $X$  and  $Y$ , respectively:

$$f \circ g = \text{id}_Y \quad \text{and} \quad g \circ f = \text{id}_X .$$



graphics grabbed from [Munkres 75](#)

We notationally indicate that a continuous function is a homeomorphism by the symbol " $\simeq$ ".

$$f : (X, \tau_X) \xrightarrow{\simeq} (Y, \tau_Y) .$$

If there is *some*, possibly unspecified, homeomorphism between topological spaces  $(X, \tau_X)$  and  $(Y, \tau_Y)$ , then we also write

$$(X, \tau_X) \simeq (Y, \tau_Y)$$

and say that the two topological spaces *are homeomorphic*.

A [property/predicate](#)  $P$  of [topological spaces](#) which is [invariant](#) under homeomorphism in that

$$((X, \tau_X) \simeq (Y, \tau_Y)) \Rightarrow (P(X, \tau_X) \Leftrightarrow P(Y, \tau_Y))$$

is called a [topological property](#) or *topological invariant*.

**Remark 3.22.** If  $f : (X, \tau_X) \rightarrow (Y, \tau_Y)$  is a [homeomorphism](#) (def. 3.21) with inverse continuous function  $g$ , then

1. also  $g$  is a homeomorphism, with inverse continuous function  $f$ ;
2. the underlying function of sets  $f : X \rightarrow Y$  of a homeomorphism  $f$  is necessarily a [bijection](#), with inverse bijection  $g$ .

But beware that not every [continuous function](#) which is [bijective](#) on underlying sets is a homeomorphism. While an [inverse function](#)  $g$  will exist on the level of functions of sets, this inverse may fail to be continuous:

**Counter Example 3.23.** Consider the [continuous function](#)

$$\begin{aligned} [0, 2\pi) &\longrightarrow S^1 \subset \mathbb{R}^2 \\ t &\longmapsto (\cos(t), \sin(t)) \end{aligned}$$

from the [half-open interval](#) (def. 1.12) to the unit circle  $S^1 := S_0(1) \subset \mathbb{R}^2$  (def. 1.2), regarded as a [topological subspace](#) (example 2.16) of the [Euclidean plane](#) (example 1.6).

The underlying function of sets of  $f$  is a [bijection](#). The [inverse function](#) of sets however fails to be continuous at  $(1, 0) \in S^1 \subset \mathbb{R}^2$ . Hence this  $f$  is *not* a [homeomorphism](#).

Indeed, below we see that the two topological spaces  $[0, 2\pi)$  and  $S^1$  are distinguished by [topological invariants](#), meaning that they cannot be homeomorphic via *any* (other) choice of homeomorphism. For example  $S^1$  is a [compact topological space](#) (def. 6.4) while  $[0, 2\pi)$  is not, and  $S^1$  has a non-trivial [fundamental group](#), while that of  $[0, 2\pi)$  is trivial ([this prop.](#)).

Below in example 6.29 we discuss a practical criterion under which continuous bijections are homeomorphisms after all. But immediate from the definitions is the following characterization:

**Proposition 3.24. ([homeomorphisms are the continuous and open bijections](#))**

*Let  $f : (X, \tau_X) \rightarrow (Y, \tau_Y)$  be a [continuous function](#) between [topological spaces](#) (def. 3.1). Then the following are equivalence:*

1.  $f$  is a [homeomorphism](#);
2.  $f$  is a [bijection](#) and an [open map](#) (def. 3.14);
3.  $f$  is a [bijection](#) and a [closed map](#) (def. 3.14).

**Proof.** It is clear from the definition that a homeomorphism in particular has to be a bijection. The condition that the [inverse function](#)  $Y \leftarrow X : g$  be continuous means that the [pre-image](#) function of  $g$  sends open subsets to open subsets. But by  $g$  being the inverse to  $f$ , that pre-image function is equal to  $f$ , regarded as a function on subsets:

$$g^{-1} = f : P(X) \rightarrow P(Y) .$$

Hence  $g^{-1}$  sends opens to opens precisely if  $f$  does, which is the case precisely if  $f$  is an open map, by definition. This shows the equivalence of the first two items. The equivalence between the first and the third follows similarly via prop. 3.2. ■

Now we consider some actual **examples** of [homeomorphisms](#):

**Example 3.25. (concrete point homeomorphic to abstract point space)**

Let  $(X, \tau_X)$  be a [non-empty topological space](#), and let  $x \in X$  be any point. Regard the corresponding [singleton subset](#)  $\{x\} \subset X$  as equipped with its [subspace](#)

[topology](#)  $\tau_{\{x\}}$  (example 2.16). Then this is [homeomorphic](#) (def. 3.21) to the abstract [point space](#) from example 2.10:

$$(\{x\}, \tau_{\{x\}}) \simeq * .$$

### Example 3.26. (open interval homeomorphic to the real line)

Regard the [real line](#) as the 1-dimensional [Euclidean space](#) (example 1.6) with its [metric topology](#) (example 2.9).

Then the open [interval](#)  $(-1, 1) \subset \mathbb{R}$  (def. 1.12) regarded with its [subspace topology](#) (example 2.16) is [homeomorphic](#) (def. 3.21) to all of the [real line](#)

$$(-1, 1) \simeq \mathbb{R}^1 .$$

An [inverse](#) pair of [continuous functions](#) is for instance given (via example 1.9) by

$$\begin{aligned} f &: \mathbb{R}^1 \rightarrow (-1, +1) \\ x &\mapsto \frac{x}{\sqrt{1+x^2}} \end{aligned}$$

and

$$\begin{aligned} g &: (-1, +1) \rightarrow \mathbb{R}^1 \\ x &\mapsto \frac{x}{\sqrt{1-x^2}} . \end{aligned}$$

But there are many other choices for  $f$  and  $g$  that yield a homeomorphism.

Similarly, for all  $a < b \in \mathbb{R}$

1. the [open intervals](#)  $(a, b) \subset \mathbb{R}$  (example 1.12) equipped with their [subspace topology](#) are all homeomorphic to each other,
2. the closed intervals  $[a, b]$  are all homeomorphic to each other,
3. the half-open intervals of the form  $[a, b)$  are all homeomorphic to each other;
4. the half-open intervals of the form  $(a, b]$  are all homeomorphic to each other.

Generally, every [open ball](#) in  $\mathbb{R}^n$  (def. 1.2) is [homeomorphic](#) to all of  $\mathbb{R}^n$ :

$$(B_0^\circ(\epsilon) \subset \mathbb{R}^n) \simeq \mathbb{R}^n .$$

While mostly the interest in a given homeomorphism is in it being non-obvious from the definitions, many homeomorphisms that appear in practice exhibit “obvious re-identifications” for which it is of interest to leave them *consistently implicit*:

### Example 3.27. (homeomorphisms between iterated product spaces)

Let  $(X, \tau_X)$ ,  $(Y, \tau_Y)$  and  $(Z, \tau_Z)$  be [topological spaces](#).

Then:

1. There is an evident [homeomorphism](#) between the two ways of bracketing the three factors when forming their [product topological space](#) (def. 2.18), called the [associator](#):

$$\alpha_{X,Y,Z} : ((X, \tau_X) \times (Y, \tau_Y)) \times (Z, \tau_Z) \xrightarrow{\cong} (X, \tau_X) \times ((Y, \tau_Y) \times (Z, \tau_Z)) .$$

2. There are evident [homeomorphism](#) between  $(X, \tau)$  and its [product topological space](#) (def. 2.18) with the [point space](#)  $*$  (example 2.10), called the left and right [unitors](#):

$$\lambda_X : * \times (X, \tau_X) \xrightarrow{\cong} (X, \tau_X)$$

and

$$\rho_X : (X, \tau_X) \times * \xrightarrow{\cong} (X, \tau_X) .$$

3. There is an evident [homeomorphism](#) between the results of the two orders in which to form their [product topological spaces](#) (def. 2.18), called the [braiding](#):

$$\beta_{X,Y} : (X, \tau_X) \times (Y, \tau_Y) \xrightarrow{\cong} (Y, \tau_Y) \times (X, \tau_X) .$$

Moreover, all these homeomorphisms are compatible with each other, in that they make the following [diagrams commute](#) (recall remark 3.3):

1. (triangle identity)

$$\begin{array}{ccc} (X \times *) \times Y & \xrightarrow{\alpha_{X,*,Y}} & X \times (* \times Y) \\ \rho_X \times \text{id}_Y \searrow & & \swarrow \text{id}_X \times \lambda_Y \\ & X \times Y & \end{array}$$

2. ([pentagon identity](#))

$$\begin{array}{ccc} & (W \times X) \times (Y \times Z) & \\ \alpha_{W \times X, Y, Z} \nearrow & & \searrow \alpha_{W, X, Y \times Z} \\ ((W \times X) \times Y) \times Z & & (W \times (X \times (Y \times Z))) \\ \alpha_{W, X, Y} \times \text{id}_Z \downarrow & & \uparrow \text{id}_W \times \alpha_{X, Y, Z} \\ (W \times (X \times Y)) \times Z & \xrightarrow{\alpha_{W, X \times Y, Z}} & W \times ((X \times Y) \times Z) \end{array}$$

3. (hexagon identities)

$$\begin{array}{ccccc}
(X \times Y) \times Z & \xrightarrow{\alpha_{X,Y,Z}} & X \times (Y \times Z) & \xrightarrow{\beta_{X,Y \times Z}} & (Y \times Z) \times X \\
\downarrow \beta_{X,Y} \times \text{id}_Z & & & & \downarrow \alpha_{Y,Z,X} \\
(Y \times X) \times Z & \xrightarrow{\alpha_{Y,X,Z}} & Y \times (X \times Z) & \xrightarrow{\text{id}_Y \times \beta_{X,Z}} & Y \times (Z \times X)
\end{array}$$

and

$$\begin{array}{ccccc}
X \times (Y \times Z) & \xrightarrow{\alpha_{X,Y,Z}^{\text{inv}}} & (X \times Y) \times Z & \xrightarrow{\beta_{X \times Y,Z}} & Z \times (X \times Y) \\
\downarrow \text{id}_X \times \beta_{Y,Z} & & & & \downarrow \alpha_{Z,X,Y}^{\text{inv}} \\
X \times (Z \times Y) & \xrightarrow{\alpha_{X,Z,Y}^{\text{inv}}} & (X \times Z) \times Y & \xrightarrow{\beta_{X,Z} \times \text{id}} & (Z \times X) \times Y
\end{array}$$

#### 4. (symmetry)

$$\beta_{Y,X} \circ \beta_{X,Y} = \text{id} : (X_1 \times X_2 \tau_{X_1 \times X_2}) \rightarrow (X_1 \times X_2 \tau_{X_1 \times X_2}) .$$

In the language of [category theory](#) (remark 3.3), all this is summarized by saying that the the [functorial](#) construction  $(-) \times (-)$  of [product topological spaces](#) (example 3.4) gives the [category Top](#) of [topological spaces](#) the [structure](#) of a [monoidal category](#) which moreover is [symmetrically braided](#).

From this, a basic result of [category theory](#), the [MacLane coherence theorem](#), guarantees that there is no essential ambiguity re-bracketing arbitrary iterations of the binary product topological space construction, as long as the above homeomorphisms are understood.

Accordingly, we may write

$$(X_1, \tau_1) \times (X_2, \tau_2) \times \cdots \times (X_n, \tau_n)$$

for iterated [product topological spaces](#) without putting parenthesis.

The following are a sequence of examples all of the form that an abstractly constructed topological space is homeomorphic to a certain subspace of a Euclidean space. These examples are going to be useful in further developments below, for example in the [proof below](#) of the [Heine-Borel theorem](#) (prop. 6.23).

- [Products](#) of [intervals](#) are homeomorphic to [hypercubes](#) (example 3.28).
- The [closed interval](#) glued at its endpoints is homeomorphic to the [circle](#) (example 3.29).
- The [cylinder](#), the [Möbius strip](#) and the [torus](#) are all homeomorphic to [quotients](#) of the square (example 3.30).

#### Example 3.28. (product of closed intervals homeomorphic to hypercubes)

Let  $n \in \mathbb{N}$ , and let  $[a_i, b_i] \subset \mathbb{R}$  for  $i \in \{1, \dots, n\}$  be  $n$  [closed intervals](#) in the [real line](#)

(example 1.12), regarded as [topological subspaces](#) of the 1-dimensional [Euclidean space](#) (example 1.6) with its [metric topology](#) (example 2.9). Then the [product topological space](#) (def. 2.18, example 3.27) of all these intervals is [homeomorphic](#) (def. 3.21) to the corresponding [topological subspace](#) of the  $n$ -dimensional [Euclidean space](#) (example 1.6):

$$[a_1, b_1] \times [a_2, b_2] \times \cdots \times [a_n, b_n] \simeq \left\{ \vec{x} \in \mathbb{R}^n \mid \forall_i (a_i \leq x_i \leq b_i) \right\} \subset \mathbb{R}^n .$$

**Proof.** There is a canonical [bijection](#) between the underlying sets. It remains to see that this, as well and its inverse, are [continuous functions](#). For this it is sufficient to see that under this bijection the defining [basis](#) (def. 2.7) for the [product topology](#) is also a basis for the [subspace topology](#). But this is immediate from lemma 2.8. ■

### Example 3.29. (closed interval glued at endpoints homeomorphic circle)

As topological spaces, the [closed interval](#)  $[0, 1]$  (def. 1.12) with its two endpoints identified is [homeomorphic](#) (def. 3.21) to the standard [circle](#):

$$[0, 1]_{/(0 \sim 1)} \simeq S^1 .$$

More in detail: let

$$S^1 \hookrightarrow \mathbb{R}^2$$

be the unit [circle](#) in the [plane](#)

$$S^1 = \{(x, y) \in \mathbb{R}^2, x^2 + y^2 = 1\}$$

equipped with the [subspace topology](#) (example 2.16) of the plane  $\mathbb{R}^2$ , which is itself equipped with its standard [metric topology](#) (example 2.9).

Moreover, let

$$[0, 1]_{/(0 \sim 1)}$$

be the [quotient topological space](#) (example 2.17) obtained from the [interval](#)  $[0, 1] \subset \mathbb{R}^1$  with its [subspace topology](#) by applying the [equivalence relation](#) which identifies the two endpoints (and nothing else).

Consider then the function

$$f : [0, 1] \rightarrow S^1$$

given by

$$t \mapsto (\cos(t), \sin(t)) .$$

This has the property that  $f(0) = f(1)$ , so that it descends to the [quotient topological space](#)



$$\begin{array}{ccc}
 [0,1] & \longrightarrow & [0,1]_{/(0 \sim 1)} \\
 f \searrow & & \downarrow \tilde{f} \\
 & & S^1
 \end{array}
 .$$

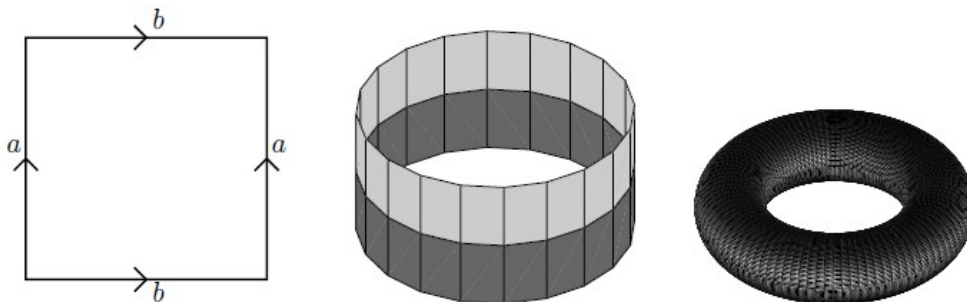
We claim that  $\tilde{f}$  is a [homeomorphism](#) (definition 3.21).

First of all it is immediate that  $\tilde{f}$  is a [continuous function](#). This follows immediately from the fact that  $f$  is a [continuous function](#) and by definition of the [quotient topology](#) (example 2.17).

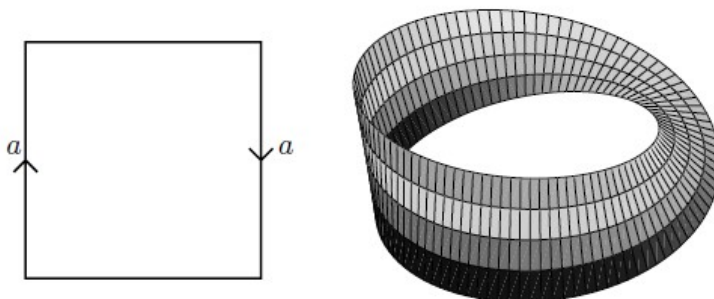
So we need to check that  $\tilde{f}$  has a continuous inverse function. Clearly the restriction of  $f$  itself to the open interval  $(0,1)$  has a continuous inverse. It fails to have a continuous inverse on  $[0,1)$  and on  $(0,1]$  and fails to have an inverse at all on  $[0,1]$ , due to the fact that  $f(0) = f(1)$ . But the relation quotiented out in  $[0,1]_{/(0 \sim 1)}$  is exactly such as to fix this failure.

### Example 3.30. (cylinder, Möbius strip and torus homeomorphic to quotients of the square)

The [square](#)  $[0,1]^2$  with two of its sides identified is the [cylinder](#), and with also the other two sides identified is the [torus](#):



If the sides are identified with opposite orientation, the result is the [Möbius strip](#):



*graphics grabbed from [Lawson 03](#)*

Important examples of pairs of spaces that are *not* homeomorphic include the

following:

**Theorem 3.31. ([topological invariance of dimension](#))**

For  $n_1, n_2 \in \mathbb{N}$  but  $n_1 \neq n_2$ , then the [Euclidean spaces](#)  $\mathbb{R}^{n_1}$  and  $\mathbb{R}^{n_2}$  (example 1.6, example 2.9) are not [homeomorphic](#).

More generally, an [open subset](#) in  $\mathbb{R}^{n_1}$  is never homeomorphic to an open subset in  $\mathbb{R}^{n_2}$  if  $n_1 \neq n_2$ .

The proofs of theorem 3.31 are not elementary, in contrast to how obvious the statement seems to be intuitively. One approach is to use tools from [algebraic topology](#): One assigns [topological invariants](#) to topological spaces, notably classes in [ordinary cohomology](#) or in [topological K-theory](#)), quantities that are [invariant](#) under [homeomorphism](#), and then shows that these classes coincide for  $\mathbb{R}^{n_1} - \{0\}$  and for  $\mathbb{R}^{n_2} - \{0\}$  precisely only if  $n_1 = n_2$ .

One indication that [topological invariance of dimension](#) is not an *elementary* consequence of the axioms of topological spaces is that a related “intuitively obvious” statement is in fact false: One might think that there is no [surjective continuous function](#)  $\mathbb{R}^{n_1} \rightarrow \mathbb{R}^{n_2}$  if  $n_1 < n_2$ . But there are: these are called the [Peano curves](#).

## 4. Separation axioms

The plain definition of [topological space](#) (above) happens to admit examples where distinct points or distinct subsets of the underlying set appear as more-or-less unseparable as seen by the topology on that set.

The extreme class of examples of topological spaces in which the open subsets do not distinguish distinct underlying points, or in fact any distinct subsets, are the [codiscrete spaces](#) (example 2.13). This does occur in practice:

**Example 4.1. ([real numbers](#) quotiented by [rational numbers](#))**

Consider the [real line](#)  $\mathbb{R}$  regarded as the 1-dimensional [Euclidean space](#) (example 1.6) with its [metric topology](#) (example 2.9) and consider the [equivalence relation](#)  $\sim$  on  $\mathbb{R}$  which identifies two [real numbers](#) if they differ by a [rational number](#):

$$(x \sim y) \Leftrightarrow \left( \exists_{p/q \in \mathbb{Q} \subset \mathbb{R}} (x = y + p/q) \right).$$

Then the [quotient topological space](#) (def. 2.17)

$$\mathbb{R}/\mathbb{Q} := \mathbb{R}/\sim$$

is a [codiscrete topological space](#) (def. 2.13), hence its topology does not distinguish any distinct proper subsets.

Here are some less extreme examples:

### Example 4.2. (open neighbourhoods in the Sierpinski space)

Consider the [Sierpinski space](#) from example 2.11, whose underlying set consists of two points  $\{0, 1\}$ , and whose open subsets form the set  $\tau = \{\emptyset, \{1\}, \{0, 1\}\}$ . This means that the only (open) neighbourhood of the point  $\{0\}$  is the entire space. Incidentally, also the [topological closure](#) of  $\{0\}$  (def. 2.21) is the entire space.

### Example 4.3. ([line with two origins](#))

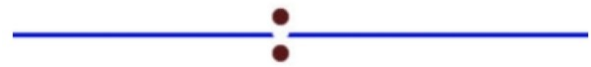
Consider the [disjoint union space](#)  $\mathbb{R} \sqcup \mathbb{R}$  (example 2.15) of two copies of the [real line](#)  $\mathbb{R}$  regarded as the 1-dimensional [Euclidean space](#) (example 1.6) with its [metric topology](#) (example 2.9), which is equivalently the [product topological space](#) (example 2.18) of  $\mathbb{R}$  with the [discrete topological space](#) on the 2-element set (example 2.13):

$$\mathbb{R} \sqcup \mathbb{R} \simeq \mathbb{R} \times \text{Disc}(\{0, 1\})$$

Moreover, consider the [equivalence relation](#) on the underlying set which identifies every point  $x_i$  in the  $i$ th copy of  $\mathbb{R}$  with the corresponding point in the other, the  $(1 - i)$ th copy, except when  $x = 0$ :

$$(x_i \sim y_j) \Leftrightarrow ((x = y) \text{ and } ((x \neq 0) \text{ or } (i = j))) .$$

The [quotient topological space](#) by this equivalence relation (def. 2.17)



$$(\mathbb{R} \sqcup \mathbb{R}) / \sim$$

is called the **line with two origins**. These “two origins” are the points  $0_0$  and  $0_1$ .

We claim that in this space *every neighbourhood of  $0_0$  intersects every neighbourhood of  $0_1$* .

Because, by definition of the [quotient space topology](#), the [open neighbourhoods](#) of  $0_i \in (\mathbb{R} \sqcup \mathbb{R}) / \sim$  are precisely those that contain subsets of the form

$$(-\epsilon, \epsilon)_i := (-\epsilon, 0) \cup \{0_i\} \cup (0, \epsilon) .$$

But this means that the “two origins”  $0_0$  and  $0_1$  may not be [separated by neighbourhoods](#), since the intersection of  $(-\epsilon, \epsilon)_0$  with  $(-\epsilon, \epsilon)_1$  is always non-empty:

$$(-\epsilon, \epsilon)_0 \cap (-\epsilon, \epsilon)_1 = (-\epsilon, 0) \cup (0, \epsilon) .$$

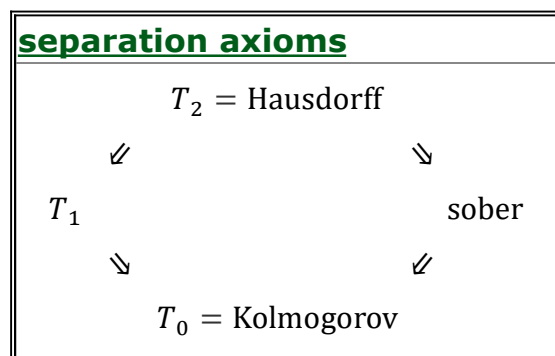
In many applications one wants to exclude at least some such exotic examples of topological spaces from the discussion and instead concentrate on those examples for which the topology recognizes the separation of distinct points, or of more

general disjoint subsets. The relevant conditions to be imposed on top of the plain [axioms](#) of a [topological space](#) are hence known as [separation axioms](#) which we discuss in the following.

These axioms are all of the form of saying that two subsets (of certain kinds) in the topological space are ‘separated’ from each other in one sense if they are ‘separated’ in a (generally) weaker sense. For example the weakest axiom (called  $T_0$ ) demands that if two points are distinct as elements of the underlying set of points, then there exists at least one [open subset](#) that contains one but not the other.

In this fashion one may impose a hierarchy of stronger axioms. For example demanding that given two distinct points, then each of them is contained in some open subset not containing the other ( $T_1$ ) or that such a pair of open subsets around two distinct points may in addition be chosen to be disjoint ( $T_2$ ). This last condition,  $T_2$ , also called the [Hausdorff condition](#) is the most common among all separation axioms. Historically this axiom was originally taken as part of the definition of topological spaces, and it is still often (but by no means always) considered by default.

However, there are respectable areas of mathematics that involve topological spaces where the Hausdorff axiom fails, but a weaker axiom is still satisfied, called [soberity](#). This is the case notably in [algebraic geometry](#) ([schemes are sober](#)) and in [computer science](#) (Vickers 89). These [sober topological spaces](#) are singled out by the fact that they are entirely characterized by their [sets of open subsets](#) with their union and intersection structure (as in def. 2.32) and may hence be understood independently from their underlying sets of points.



All separation axioms are satisfied by [metric spaces](#) (def. 1.1), from whom the concept of topological space was originally abstracted [above](#). Hence imposing some of them may also be understood as gauging just how far one allows topological spaces to generalize away from metric spaces

## $T_n$ spaces

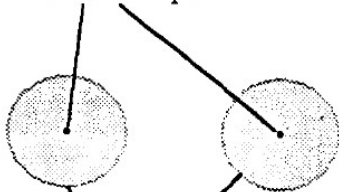
There are many variants of separation axioms. The classical ones are labeled  $T_n$  (for German “Trennungsaxiom”). These we now introduce in def. 4.4 and def. 4.13:

**Definition 4.4. (the first three [separation axioms](#))**

Let  $(X, \tau)$  be a [topological space](#) (def. 2.3).

For  $x \neq y \in X$  any two points in the underlying set of  $X$  which are not [equal](#) as elements of this set, consider the following [propositions](#):

two distinct points



disjoint open sets

- **(T0)** There exists a [neighbourhood](#) of one of the two points which does not contain the other point.
- **(T1)** There exist [neighbourhoods](#) of both points which do not contain the other point.
- **(T2)** There exists [neighbourhoods](#) of both points which do not intersect each other.

graphics grabbed from [Vickers 89](#)

The topological space  $X$  is called a  $T_n$ -topological space or just  $T_n$ -space, for short, if it satisfies condition  $T_n$  above for all pairs of distinct points.

A  $T_0$ -topological space is also called a [Kolmogorov space](#).

A  $T_2$ -topological space is also called a [Hausdorff topological space](#).

For definiteness, we re-state these conditions formally. Write  $x, y \in X$  for points in  $X$ , write  $U_x, U_y \in \tau$  for open [neighbourhoods](#) of these points. Then:

- **(T0)**  $\forall_{x \neq y} \left( \left( \exists_{U_y} (\{x\} \cap U_y = \emptyset) \right) \text{ or } \left( \exists_{U_x} (U_x \cap \{y\} = \emptyset) \right) \right)$
- **((T1))**  $\forall_{x \neq y} \left( \exists_{U_x, U_y} ((\{x\} \cap U_y = \emptyset) \text{ and } (U_x \cap \{y\} = \emptyset)) \right)$
- **(T2)**  $\forall_{x \neq y} \left( \exists_{U_x, U_y} (U_x \cap U_y = \emptyset) \right)$

The following is evident but important:

**Proposition 4.5.** ( $T_n$  are topological properties of increasing strength)

The separation properties  $T_n$  from def. 4.4 are [topological properties](#) in that if two topological spaces are [homeomorphic](#) (def. 3.21) then one of them satisfies  $T_n$  precisely if the other does.

Moreover, these properties imply each other as

$$T2 \Rightarrow T1 \Rightarrow T0 .$$

**Example 4.6.** Examples of topological spaces that are not [Hausdorff](#) (def. 4.4) include

1. the [Sierpinski space](#) (example 4.2),

2. the [line with two origins](#) (example 4.3),
3. the [quotient topological space](#)  $\mathbb{R}/\mathbb{Q}$  (example 4.1).

#### Example 4.7. (finite $T_1$ -spaces are discrete)

For a [finite topological space](#)  $(X, \tau)$ , hence one for which the underlying set  $X$  is a [finite set](#), the following are equivalent:

1.  $(X, \tau)$  is  $T_1$  (def. 4.4);
2.  $(X, \tau)$  is a [discrete topological space](#) (def. 2.13).

#### Example 4.8. (metric spaces are Hausdorff)

Every [metric space](#) (def 1.1), regarded as a [topological space](#) via its [metric topology](#) (example 2.9) is a [Hausdorff topological space](#) (def. 4.4).

#### Example 4.9. (subspace of $T_n$ -space is $T_n$ )

Let  $(X, \tau)$  be a [topological space](#) satisfying the  $T_n$  [separation axiom](#) for some  $n \in \{0, 1, 2\}$  according to def. 4.4. Then also every [topological subspace](#)  $S \subset X$  (example 2.16) satisfies  $T_n$ .

### Separation in terms of topological closures

The conditions  $T_0$ ,  $T_1$  and  $T_2$  have the following equivalent formulation in terms of [topological closures](#) (def. 2.21).

#### Proposition 4.10. ( $T_0$ in terms of topological closures)

A [topological space](#)  $(X, \tau)$  is  $T_0$  (def. 4.4) precisely if the function  $\text{Cl}(\{-\})$  that forms [topological closures](#) (def. 2.21) of [singleton subsets](#) from the underlying set of  $X$  to the set of [irreducible closed subsets](#) of  $X$  (def. 2.28, which is well defined according to example 2.29), is [injective](#):

$$\text{Cl}(\{-\}) : X \hookrightarrow \text{IrrClSub}(X)$$

**Proof.** Assume first that  $X$  is  $T_0$ . Then we need to show that if  $x, y \in X$  are such that  $\text{Cl}(\{x\}) = \text{Cl}(\{y\})$  then  $x = y$ . Hence assume that  $\text{Cl}(\{x\}) = \text{Cl}(\{y\})$ . Since the closure of a point is the [complement](#) of the union of the open subsets not containing the point (lemma 2.23), this means that the union of open subsets that do not contain  $x$  is the same as the union of open subsets that do not contain  $y$ :

$$\bigcup_{\substack{U \subset X \text{ open} \\ U \subset X \setminus \{x\}}} (U) = \bigcup_{\substack{U \subset X \text{ open} \\ U \subset X \setminus \{y\}}} (U)$$

But if the two points were distinct,  $x \neq y$ , then by  $T_0$  one of the above unions

would contain  $x$  or  $y$ , while the other would not, in contradiction to the above equality. Hence we have a [proof by contradiction](#).

Conversely, assume that if  $x, y \in X$  are such that  $\text{Cl}\{x\} = \text{Cl}\{y\}$  then  $x = y$ . We need to show that if  $x \neq y$  then there exists an open neighbourhood around one of the two points not containing the other.

Hence assume that  $x \neq y$ . By assumption it follows that  $\text{Cl}\{x\} \neq \text{Cl}\{y\}$ , hence that now

$$\bigcup_{\substack{U \subset X \text{ open} \\ U \subset X \setminus \{x\}}} (U) \neq \bigcup_{\substack{U \subset X \text{ open} \\ U \subset X \setminus \{y\}}} (U) .$$

This means that there must be at least one open subset which contains  $x$  but not  $y$ , or vice versa. ■

### Proposition 4.11. ( $T_1$ in terms of topological closures)

A [topological space](#)  $(X, \tau)$  is  $T_1$  (def. 4.4) precisely if all its points are [closed points](#) (def. 2.21).

**Proof.** Assume first that  $(X, \tau)$  is  $T_1$ . We need to show that for every point  $x \in X$  we have  $\text{Cl}\{x\} = \{x\}$ . Since the closure of a point is the [complement](#) of the union of all open subsets not containing this point, this is the case precisely if the union of all open subsets not containing  $x$  is  $X \setminus \{x\}$ , hence if every point  $y \neq x$  is member of at least one open subset not containing  $x$ . This is true by  $T_1$ .

Conversely, assume that for all  $x \in X$  then  $\text{Cl}\{x\} = \{x\}$ . Then for  $x \neq y \in X$  two distinct points we need to produce an open subset of  $y$  that does not contain  $x$ . But as before, since  $\text{Cl}\{x\}$  is the complement of the union of all open subsets that do not contain  $x$ , the assumption  $\text{Cl}\{x\} = \{x\}$  means that  $y$  is member of one of these open subsets that do not contain  $x$ . ■

### Proposition 4.12. ( $T_2$ in terms of topological closures)

A [topological space](#)  $(X, \tau_X)$  is  $T_2$  = [Hausdorff](#) (def. 4.4) precisely if the [diagonal function](#)  $\Delta_X: (X, \tau_X) \rightarrow (X \times X, \tau_{X \times X})$  (example 3.9) is a [closed map](#) (def. 3.14).

**Proof.** If  $(X, \tau_X)$  is Hausdorff, then by definition for every pair of distinct points  $x \neq y \in X$  there exists open neighbourhoods  $U_x, U_y \in \tau_X$  such that  $U_x \cap U_y = \emptyset$ . In terms of the [product topology](#) (example 2.18) this means that every point  $(x, y) \in X \times X$  which is not on the diagonal has an open neighbourhood  $U_x \times U_y$  which still does not contain the diagonal. By definition this means that in fact every [subset](#) of the diagonal is a [closed subset](#) of  $X \times X$ , hence in particular those that are in the image under  $\Delta_X$  of closed subsets of  $X$ . Hence  $\Delta_X$  is a closed map.

Conversely, if  $\Delta_X$  is a closed map, then the full diagonal (i.e. the image of  $X$  under  $\Delta_X$ ) is closed in  $X \times X$ , and hence this means that every points  $(x, y) \in X \times X$  not on the diagonal has an open neighbourhood  $U_x \times U_y$  not containing the diagonal, i.e.



such that  $U_x \cap U_y = \emptyset$ . Hence  $X$  is Hausdorff. ■

## Further separation axioms

Clearly one may and does consider further variants of the separation axioms  $T_0$ ,  $T_1$  and  $T_2$  from def. 4.4. We consider two more:

**Definition 4.13.** Let  $(X, \tau)$  be [topological space](#) (def. 4.4).

Consider the following conditions

- **(T3)** The space  $(X, \tau)$  is  $T_1$  (def. 4.4) and for  $x \in X$  a point and  $C \subset X$  a [closed subset](#) (def. 2.21) not containing  $x$ , then there exist disjoint [open neighbourhoods](#)  $U_x \supset \{x\}$  and  $U_C \supset C$ .
- **(T4)** The space  $(X, \tau)$  is  $T_1$  (def. 4.4) and for  $C_1, C_2 \subset X$  disjoint [closed subsets](#) (def. 2.21) then there exist disjoint [open neighbourhoods](#)  $U_{C_i} \supset C_i$ .

If  $(X, \tau)$  satisfies  $T_3$  it is said to be a  $T_3$ -space also called a [regular Hausdorff topological space](#).

If  $(X, \tau)$  satisfies  $T_4$  it is to be a  $T_4$ -space also called a [normal Hausdorff topological space](#).

Observe that:

**Proposition 4.14.** *The separation axioms from def. 4.4, def. 4.13 imply each other as*

$$T_4 \Rightarrow T_3 \Rightarrow T_2 \Rightarrow T_1 \Rightarrow T_0 .$$

**Proof.** The implications

$$T_2 \Rightarrow T_1 \Rightarrow T_0$$

and

$$T_4 \Rightarrow T_3$$

are immediate from the definitions. The remaining implication  $T_3 \Rightarrow T_2$  follows with prop. 4.11: This says that by assumption of  $T_1$  then all points in  $(X, \tau)$  are closed, and with this the condition  $T_2$  is manifestly a special case of the condition for  $T_3$ . ■

Hence instead of saying “ $X$  is  $T_1$  and ...” one could just as well phrase the conditions  $T_3$  and  $T_4$  as “ $X$  is  $T_2$  and ...”, which would render the proof of prop. 4.14 even more trivial.

As before we have equivalent reformulations of the further separation axioms.

## Further separation axioms in terms of topological closures

### Proposition 4.15. ( $T_3$ in terms of topological closures)

A [topological space](#)  $(X, \tau)$  is [regular Hausdorff space](#) (def. 4.13), precisely if all points are closed and for all [closed subsets](#)  $x \in X$  with [open neighbourhood](#)  $U \supset \{x\}$  there exists a smaller open neighbourhood  $V \supset \{x\}$  whose [topological closure](#)  $\text{Cl}(V)$  is still contained in  $U$ :

$$\{x\} \subset V \subset \text{Cl}(V) \subset U .$$

The **proof** of prop. 4.15 is the direct specialization of the following proof for prop. 4.16 to the case that  $C = \{x\}$  (using that by  $T_1$ , which is part of the definition of  $T_3$ , the singleton subset is indeed closed by prop. 4.11).

### Proposition 4.16. ( $T_4$ in terms of topological closures)

A [topological space](#)  $(X, \tau)$  is [normal Hausdorff space](#) (def. 4.13), precisely if all points are closed and for all [closed subsets](#)  $C \subset X$  with [open neighbourhood](#)  $U \supset C$  there exists a smaller open neighbourhood  $V \supset C$  whose [topological closure](#)  $\text{Cl}(V)$  is still contained in  $U$ :

$$C \subset V \subset \text{Cl}(V) \subset U .$$

**Proof.** In one direction, assume that  $(X, \tau)$  is normal, and consider  $C \subset U$ . It follows that the [complement](#) of the open subset  $U$  is closed and disjoint from  $C$ :

$$C \cap X \setminus U = \emptyset .$$

Therefore by assumption of normality of  $(X, \tau)$ , there exists open neighbourhoods  $V \supset C$  and  $W \supset X \setminus U$  with

$$V \cap W = \emptyset .$$

But this means that

$$V \subset X \setminus W$$

and since the [complement](#)  $X \setminus W$  of the open set  $W$  is closed, it still contains the closure of  $V$ , so that we have

$$C \subset V \subset \text{Cl}(V) \subset X \setminus W \subset U .$$

In the other direction, assume that for every open neighbourhood  $U \supset C$  of a closed subset  $C$  there exists a smaller open neighbourhood  $V$  with  $C \subset V \subset \text{Cl}(V) \subset U$ . Consider disjoint closed subsets  $C_1, C_2 \subset X$ . We need to produce disjoint open neighbourhoods for them.

From their disjointness it follows that  $X \setminus C_2 \supset C_1$  is an open neighbourhood. Hence

by assumption there is an open neighbourhood  $V$  with

$$C_1 \subset V \subset \text{Cl}(V) \subset X \setminus C_2 .$$

Thus  $V \supset C_1$  and  $X \setminus \text{Cl}(X) \supset C_2$  are two disjoint open neighbourhoods, as required. ■

In summary, **the main separation axioms** and their reformulation are the following:

number	name	statement	reformulation
$T_0$	<a href="#">Kolmogorov</a>	given two distinct points, at least one of them has an open neighbourhood not containing the other point	every irreducible closed subset is the closure of at most one point
$T_1$		given two distinct points, both have an open neighbourhood not containing the other point	all points are closed
$T_2$	<a href="#">Hausdorff</a>	given two distinct points, they have disjoint open neighbourhoods	the diagonal is a closed map
$T_{>2}$		$T_1$ and...	all points are closed and...
$T_3$	<a href="#">regular Hausdorff</a>	...given a point and a closed subset not containing it, they have disjoint open neighbourhoods	...every neighbourhood of a point contains the closure of an open neighbourhood
$T_4$	<a href="#">normal Hausdorff</a>	...given two disjoint closed subsets, they have disjoint open neighbourhoods	...every neighbourhood of a closed set also contains the closure of an open neighbourhood

Notice that there is a whole zoo of further variants of [separation axioms](#) that are considered in the literature. But the above are the main ones. Specifically  $T_2 = \text{Hausdorff}$  is the most popular one, often considered by default in the literature, when topological spaces are considered.

We discuss a few more properties related to the separation axioms that we will need further below.

1. the [shrinking lemma](#), lemma [4.17](#) below;
2. [Urysohn's lemma](#), prop. [4.19](#) below.

**Lemma 4.17. ([shrinking lemma](#))**

Let  $X$  be a [topological space](#) which is [normal](#) (def. 4.13) and let  $\{U_i \subset X\}_{i \in I}$  be an [open cover](#).

Then there exists another open cover  $\{V_i \subset X\}_{i \in I}$  such that the [topological closure](#)  $\text{Cl}(V_i)$  of its elements (def. 2.21) is contained in the original patches:

$$\forall_{i \in I} (V_i \subset \text{Cl}(V_i) \subset U_i) .$$

The following concept if [Urysohn functions](#) is another approach of thinking about separation of subsets in a topological space, not in terms of their neighbourhoods, but in terms of continuous real-valued “indicator functions” that take different values on the subsets. But the [Urysohn lemma](#) (prop. 4.19 below) implies that this concept of separation is in fact equivalent to that of normality of Hausdorff spaces.

### Definition 4.18. ([Urysohn function](#))

Let  $X$  be a [topological space](#), and let  $A, B \subset X$  be disjoint [closed subsets](#). Then an *Urysohn function separating  $A$  from  $B$*  is

- a [continuous function](#)  $f: X \rightarrow [0, 1]$

to the [closed interval](#) equipped with its [Euclidean metric topology](#), that takes the value 0 on  $A$  and the value 1 on  $B$ :

$$f(A) = \{0\} \quad \text{and} \quad f(B) = \{1\} .$$

### Proposition 4.19. ([Urysohn's lemma](#))

Let  $X$  be a [normal](#) (or  $T_4$ ) [topological space](#), and let  $A, B \subset X$  be two disjoint [closed subsets](#) of  $X$ . Then there exists an Urysohn function separating  $A$  from  $B$  (def. 4.18).

**Remark 4.20.** Beware that the function in prop. 4.19 may take the values 0 or 1 even outside of the two subsets. The condition that the function takes value 0 or 1, respectively, *precisely* on the two subsets corresponds to “[perfectly normal spaces](#)”.

**Proof.** of [Urysohn's lemma](#), prop. 4.19

Set

$$C_0 := A \quad U_1 := X \setminus B .$$

Since by assumption

$$A \cap B = \emptyset .$$

we have

$$C_0 \subset U_1 .$$

Notice that (by [this lemma](#)) if a space is normal then every open neighbourhood  $U \supset C$  of closed subset  $C$  contains a smaller neighbourhood  $V$  together with its closure  $\text{Cl}(V)$

$$U \subset V \subset \text{Cl}(V) \subset C .$$

Apply this fact successively to the above situation to obtain the following infinite sequence of nested open subsets  $U_r$  and closed subsets  $C_r$

$$\begin{array}{ccccccc} C_0 & & & & & & U_1 \\ C_0 & & \subset & & U_{1/2} \subset C_{1/2} & & \subset U_1 \\ C_0 \subset U_{1/4} \subset C_{1/4} \subset U_{1/2} \subset C_{1/2} \subset U_{3/4} \subset C_{3/4} \subset U_1 \end{array}$$

and so on, labeled by the [dyadic rational numbers](#)

$$\{U_r \subset X\}_{r \in \mathbb{Q}_{\text{dy}}}$$

with the property that

$$\forall_{r \in \mathbb{Q}_{\text{dy}}} (A \subset U_r \subset X \setminus B)$$

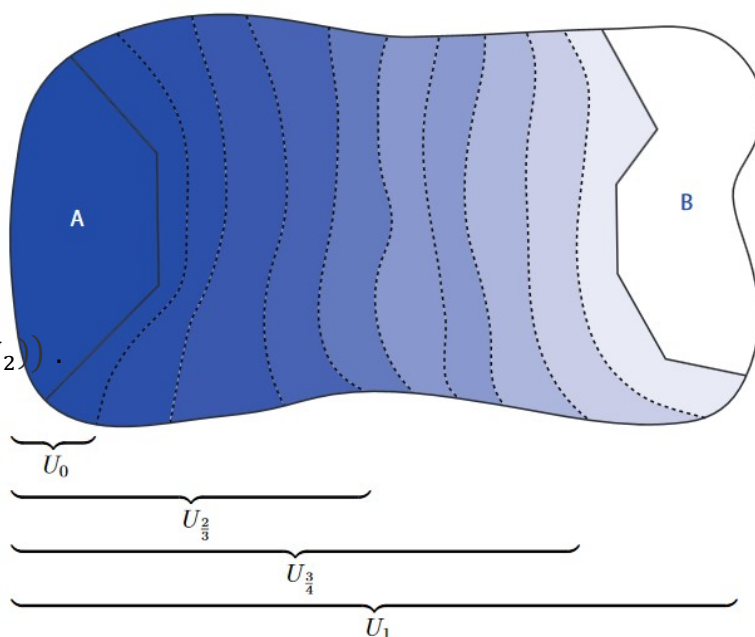
and

$$(r_1 < r_2) \Rightarrow ((U_{r_1} \subset U_{r_2}) \text{ and } (U_{r_1} \neq U_{r_2})) .$$

Define then the function

$$f : X \rightarrow [0, 1]$$

to assign to a point  $x \in X$  the [infimum](#) of the labels of those open subsets in this sequence that contain  $x$ :



$$f(x) := \lim_{U_r \supset \{x\}} r$$

Here the [limit](#) is over the [directed set](#) of those  $U_r$  that contain  $x$ , ordered by reverse inclusion.

This function clearly has the property that  $f(A) = \{0\}$  and  $f(B) = \{1\}$ . It only remains to see that it is continuous.

To this end, first observe that

$$(*) \quad (x \in \text{Cl}(U_r)) \Leftrightarrow (f(x) \leq r) .$$

To see this, observe that it is immediate from the definition that  $(x \in U_r) \Rightarrow (f(x) \leq r)$  and that  $(f(x) < r) \Rightarrow (x \in U_r \subset \text{Cl}(U_r))$ . For the remaining implications, it is sufficient to observe the case that

$$(x \in \partial U_r) \Rightarrow (f(x) = r),$$

where  $\partial U_r := \text{Cl}(U_r) \setminus U_r$  is the [boundary](#) of  $U_r$ .

This holds because the [dyadic numbers](#) are [dense](#) in  $\mathbb{R}$ . (And this would fail if we stopped the above decomposition into  $U_{a/2^n}$ -s at some finite  $n$ .) Namely if  $x \in \partial U_r$  then for every small positive real number  $\epsilon$  there exists a dyadic rational number  $r'$  with  $r < r' < r + \epsilon$ , and since  $x \in U_{r'}$  it follows that  $\lim_{U_r \ni \{x\}} = r$ .

Now we claim that for all  $\alpha \in [0, 1]$  then

1.  $f^{-1}((\alpha, 1])$  is open.
2.  $f^{-1}([0, \alpha))$  is open;

Regarding the first point: By  $(\star)$  we have

$$f^{-1}((\alpha, 1]) = \bigcup_{r \leq \alpha} X \setminus \text{Cl}(U_r).$$

Since the closures  $\text{Cl}(U_r)$  are closed, the complements  $X \setminus \text{Cl}(U_r)$  are open, and hence this is a union of open subsets, hence open.

Regarding the second point: By  $(\star)$  we have

$$f^{-1}([0, \alpha)) = \bigcup_{r < \alpha} \text{Cl}(U_r).$$

To see why this is open, observe that if  $r < \alpha$  then, again because the [dyadic numbers](#) within 0 and 1 are [dense](#) in  $[0, 1]$ , there exists  $r'$  with  $r < r' < \alpha$ , and hence by construction of the  $U_r$  we then have  $\text{Cl}(U_r) \subset U_{r'} \subset \text{Cl}(U_{r'})$ . This means that in the above union we may omit the closures, to obtain

$$f^{-1}([0, \alpha)) = \bigcup_{r < \alpha} U_r.$$

This now is open because unions of open subsets are open.

Now since the subsets  $\{[0, \alpha), (\alpha, 1]\}_{\alpha \in [0, 1]}$  form a [sub-base](#) for the Euclidean metric topology on  $[0, 1]$ , it follows that all pre-images of  $f$  are open, hence that  $f$  is continuous. ■

As a corollary we obtain:

**Proposition 4.21. (normality equivalent to existence of Urysohn functions)**

A  $T_1$ -space/Hausdorff space (def. 4.4) is [normal](#) (def. 4.13) precisely if it admits [Urysohn functions](#) (def 4.18) separating every pair of disjoint closed subsets.

**Proof.** In one direction this is the statement of the [Urysohn lemma](#), prop. 4.19.

In the other direction, assume the existence of [Urysohn functions](#) (def. 4.18)

separating all disjoint closed subsets. Let  $A, B \subset X$  be disjoint closed subsets, then we need to show that these have disjoint open neighbourhoods.

But for  $f: X \rightarrow [0, 1]$  by an Urysohn function with  $f(A) = \{0\}$  and  $f(B) = \{1\}$  then the [pre-images](#)

$$U_A := f^{-1}([0, 1/3]) \quad U_B := f^{-1}((2/3, 1])$$

are disjoint open neighbourhoods as required. ■

## $T_n$ reflection

Not every [universal construction](#) of [topological spaces](#) applied to  $T_n$ -spaces results again in a  $T_n$  topological space, notably [quotient space](#) constructions need not (as in example 4.3).

But at least for  $T_0$ ,  $T_1$  and  $T_2$  there is a universal way, called [reflection](#) (prop. 4.22 below), to approximate any topological space “from the left” by a  $T_n$  topological spaces.

Hence if one wishes to work within the [full subcategory](#) of the  $T_n$  among all [topological space](#), then the correct way to construct quotients and other [colimits](#) (see below) is to first construct them as usual [quotient topological spaces](#) (example 2.17), and then apply the  $T_n$ -reflection to the result.

### Proposition 4.22. ( $T_n$ -reflection)

*Let  $n \in \{0, 1, 2\}$ . Then for every [topological space](#)  $X$  there exists a  $T_n$ -topological space  $T_n X$  and a [continuous function](#)*

$$t_n(X) : X \longrightarrow T_n X$$

*which is the “closest approximation from the left” to  $X$  by a  $T_n$ -topological space, in that for  $Y$  any  $T_n$ -space, then [continuous functions](#) of the form*

$$f : X \longrightarrow Y$$

*are in [bijection](#) with [continuous function](#) of the form*

$$\tilde{f} : T_n X \longrightarrow Y$$

*and such that the bijection is constituted by*

$$f = \tilde{f} \circ t_n(X) : X \xrightarrow{t_n(X)} T_n X \xrightarrow{\tilde{f}} Y .$$

*Here  $X \xrightarrow{t_n(X)} T_n X$  is called the  $T_n$ -reflection of  $X$ .*

- For  $n = 0$  this is known as the [Kolmogorov quotient](#) construction (see prop.



4.25 below).

- For  $n = 2$  this is known as Hausdorff reflection or Hausdorffication or similar.

Moreover, the operation  $T_n(-)$  extends to continuous functions  $f: X \rightarrow Y$

$$(X \xrightarrow{f} Y) \mapsto (T_n X \xrightarrow{T_n f} T_n Y)$$

such as to preserve composition of functions as well as identity functions:

$$T_n g \circ T_n f = T_n (g \circ f) \quad , \quad T_n \text{id}_X = \text{id}_{T_n X}$$

Finally, the comparison map is compatible with this in that the following squares commute:

$$\begin{array}{ccc} X & \xrightarrow{f} & Y \\ h_X \downarrow & & \downarrow h_Y \\ T_n X & \xrightarrow{T_n f} & T_n Y \end{array}$$

#### Remark 4.23. (reflective subcategories)

In the language of category theory (remark 3.3) the  $T_n$ -reflection of prop. 4.22 says that

1.  $T_n(-)$  is a functor  $T_n : \text{Top} \rightarrow \text{Top}_{T_n}$  from the category Top of topological spaces to the full subcategory  $\text{Top}_{T_n} \xhookrightarrow{\iota} \text{Top}$  of Hausdorff topological spaces;
2.  $t_n(X): X \rightarrow T_n X$  is a natural transformation from the identity functor on Top to the functor  $\iota \circ T_n$
3.  $T_n$ -topological spaces form a reflective subcategory of all topological spaces in that  $T_n$  is left adjoint to the inclusion functor  $\iota$ ; this situation is denoted as follows:

$$\text{Top}_{T_n} \begin{array}{c} \xleftarrow{H} \\ \perp \\ \xrightarrow{\iota} \end{array} \text{Top} .$$

Generally, an adjunction between two functors

$$L : \mathcal{C} \leftrightarrow \mathcal{D} : R$$

is for all pairs of objects  $c \in \mathcal{C}$ ,  $d \in \mathcal{D}$  a bijection between sets of morphisms of the form

$$\{L(c) \rightarrow d\} \simeq \{c \rightarrow R(d)\} .$$

i.e.

$$\mathrm{Hom}_{\mathcal{D}}(L(c), d) \xrightarrow[\simeq]{\phi_{c,d}} \mathrm{Hom}_{\mathcal{C}}(c, R(d))$$

and such that these bijections are “[natural](#)” in that they for all pairs of morphisms  $f: c' \rightarrow c$  and  $g: d \rightarrow d'$  then the following [diagram commutes](#):

$$\begin{array}{ccc} \mathrm{Hom}_{\mathcal{D}}(L(c), d) & \xrightarrow[\simeq]{\phi_{c,d}} & \mathrm{Hom}_{\mathcal{C}}(c, R(d)) \\ g \circ (-) \circ L(f) \downarrow & & \downarrow R(g) \circ (-) \circ f \\ \mathrm{Hom}_{\mathcal{C}}(L(c'), d') & \xrightarrow[\simeq]{\phi_{c',d'}} & \mathrm{Hom}_{\mathcal{D}}(c', R(d')) \end{array}$$

There are various ways to see the existence and to construct the  $T_n$ -reflections. The following is the quickest way to see the existence, even though it leaves the actual construction rather implicit.

**Proposition 4.24.** *Let  $n \in \{0, 1, 2\}$ . Let  $(X, \tau)$  be a [topological space](#) and consider the [equivalence relation](#)  $\sim$  on the underlying set  $X$  for which  $x \sim y$  precisely if for every [surjective continuous function](#)  $f: X \rightarrow Y$  into any  $T_n$ -topological space  $Y$  we have  $f(x) = f(y)$ .*

*Then the set of [equivalence classes](#)*

$$T_n X := X / \sim$$

*equipped with the [quotient topology](#) is a  $T_n$ -topological space, and the quotient map  $t_n(X) : X \rightarrow X / \sim$  exhibits the  $T_n$ -reflection of  $X$ , according to prop. [4.22](#).*

**Proof.** First we observe that every continuous function  $f: X \rightarrow Y$  into a  $T_n$ -topological space  $Y$  factors uniquely via  $t_n(X)$  through a continuous function  $\tilde{f}$

$$f = \tilde{f} \circ h_X$$

where

$$\tilde{f}: [x] \mapsto f(x) .$$

To see this, first factor  $f$  through its [image](#)  $f(X)$

$$f : X \rightarrow f(X) \hookrightarrow Y$$

equipped with its [subspace topology](#) as a subspace of  $Y$  (example [3.10](#)). By prop. [4.9](#) also  $f(X)$  is a  $T_n$ -topological space if  $Y$  is.

It follows by definition of  $t_n(X)$  that the factorization exists at the level of sets as stated, since if  $x_1, x_2 \in X$  have the same [equivalence class](#)  $[x_1] = [x_2]$  in  $T_n X$ , then by definition they have the same image under all continuous surjective functions to a  $T_n$ -space, hence in particular under  $X \rightarrow f(X)$ . This means that  $\tilde{f}$  as above is well defined. Moreover, it is clear that this is the unique factorization.

To see that  $\tilde{f}$  is continuous, consider  $U \in Y$  an open subset. We need to show that

$\tilde{f}^{-1}(U)$  is open in  $X/\sim$ . But by definition of the [quotient topology](#), this is open precisely if its pre-image under the quotient projection  $t_n(X)$  is open, hence precisely if

$$(t_n(X))^{-1}(\tilde{f}^{-1}(U)) = (\tilde{f} \circ t_n(X))^{-1}(U) = f(U)$$

is open in  $X$ . But this is the case by the assumption that  $f$  is continuous.

What remains to be seen is that  $T_n X$  as constructed is indeed a  $T_n$ -topological space. Hence assume that  $[x] \neq [y] \in T_n X$  are two distinct points. We need to produce open neighbourhoods around one or both of these point not containing the other point and possibly disjoint to each other.

Now by definition of  $T_n X$  the assumption  $[x] \neq [y]$  means that there exists a  $T_n$ -topological space  $Y$  and a surjective continuous function  $f: X \rightarrow Y$  such that  $f(x) \neq f(y) \in Y$ . Accordingly, since  $Y$  is  $T_n$ , there exist the respective kinds of neighbourhoods around these image points in  $Y$ . Moreover, by the previous statement there exists the continuous function  $\tilde{f}: T_n X \rightarrow Y$  with  $\tilde{f}([x]) = f(x)$  and  $\tilde{f}([y]) = f(y)$ . By the nature of continuous functions, the pre-images of these open neighbourhoods in  $Y$  are still open in  $X$  and still satisfy the required disjunction properties. Therefore  $T_n X$  is a  $T_n$ -space. ■

Here are alternative constructions of the reflections:

**Proposition 4.25. ([Kolmogorov quotient](#))**

Let  $(X, \tau)$  be a [topological space](#). Consider the [relation](#) on the underlying set by which  $x_1 \sim x_2$  precisely if neither  $x_i$  has an [open neighbourhood](#) not containing the other. This is an [equivalence relation](#). The [quotient topological space](#)  $X \rightarrow X/\sim$  by this equivalence relation (def. [2.17](#)) exhibits the  $T_0$ -reflection of  $X$  according to prop. [4.22](#).

**Example 4.26.** The [Hausdorff reflection](#) ( $T_2$ -reflection, prop. [4.22](#))

$$T_2 : \mathbf{Top} \rightarrow \mathbf{Top}_{\text{Haus}}$$

of the [line with two origins](#) from example [4.3](#) is the [real line](#) itself:

$$T_2((\mathbb{R} \sqcup \mathbb{R})/\sim) \simeq \mathbb{R}.$$

## 5. Sober spaces

The alternative characterization of the  $T_0$ -condition in prop. [4.10](#) immediately suggests the following strengthening, different from the  $T_1$ -condition:

**Definition 5.1. ([sober topological space](#))**

A [topological space](#)  $(X, \tau)$  is called a [sober topological space](#) precisely if every [irreducible closed subspace](#) (def. [2.29](#)) is the [topological closure](#) (def. [2.21](#)) of a

unique point, hence precisely if the function

$$\text{Cl}(\{-\}) : X \rightarrow \text{IrrClSub}(X)$$

from the underlying set of  $X$  to the set of [irreducible closed subsets](#) of  $X$  (def. 2.28, well defined according to example 2.29) is [bijective](#).

**Proposition 5.2. (*sober implies  $T_0$* )**

Every [sober topological space](#) (def. 5.1) is  $T_0$  (def. 4.4).

**Proof.** By prop. 4.10. ■

**Proposition 5.3. (*Hausdorff spaces are sober*)**

Every [Hausdorff topological space](#) (def. 4.4) is a [sober topological space](#) (def. 5.1).

More specifically, in a Hausdorff topological space the [irreducible closed subspaces](#) (def. 2.28) are precisely the [singleton subspaces](#) (def. 8.6).

Hence, by example 4.8, in particular every [metric space](#) with its [metric topology](#) (example 2.9) is sober.

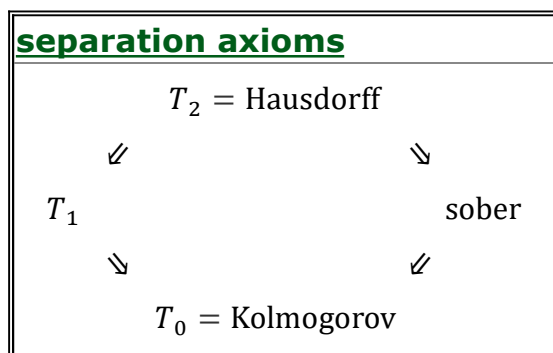
**Proof.** The second statement clearly implies the first. To see the second statement, suppose that  $F$  is an irreducible closed subspace which contained two distinct points  $x \neq y$ . Then by the Hausdorff property there are disjoint neighbourhoods  $U_x, U_y$ , and hence it would follow that the relative [complements](#)  $F \setminus U_x$  and  $F \setminus U_y$  were distinct proper closed subsets of  $F$  with

$$F = (F \setminus U_x) \cup (F \setminus U_y)$$

in contradiction to the assumption that  $F$  is irreducible.

This [proves by contradiction](#) that every irreducible closed subset is a singleton. Conversely, generally the [topological closure](#) of every singleton is irreducible closed, by example 2.29. ■

By prop. 5.2 and prop. 5.3 we have the implications on the right of the following diagram:



But there there is no implication between  $T_1$  and sobriety:

**Proposition 5.4.** The [intersection](#) of the [classes](#) of [sober topological spaces](#) (def. 5.1) and  $T_1$ -topological spaces (def. 4.4) is not [empty](#), but neither class is contained within the other.

That the intersection is not empty follows from prop. 5.3. That neither class is contained in the other is shown by the following counter-examples:

**Example.**

- The [Sierpinski space](#) (def. 2.11) is sober, but not  $T_1$ .
- The [cofinite topology](#) (example 2.14) on a non-[finite set](#) is  $T_1$  but not sober.

## Frames of opens

What makes the concept of [sober topological spaces](#) special is that for them the concept of [continuous functions](#) may be expressed entirely in terms of the relations between their [open subsets](#), disregarding the underlying set of points of which these open are in fact subsets.

Recall from example 2.34 that for every [continuous function](#)  $f: (X, \tau_X) \rightarrow (Y, \tau_Y)$  the [pre-image](#) function  $f^{-1}: \tau_Y \rightarrow \tau_X$  is a [frame homomorphism](#) (def. 2.32).

For sober topological spaces the converse holds:

**Proposition 5.5.** *If  $(X, \tau_X)$  and  $(Y, \tau_Y)$  are [sober topological spaces](#) (def. 5.1), then for every [frame homomorphism](#) (def. 2.32)*

$$\tau_X \leftarrow \tau_Y : \phi$$

*there is a unique [continuous function](#)  $f: X \rightarrow Y$  such that  $\phi$  is the function of forming [pre-images](#) under  $f$ :*

$$\phi = f^{-1}.$$

**Proof.** We first consider the special case of frame homomorphisms of the form

$$\tau_* \leftarrow \tau_X : \phi$$

and show that these are in bijection to the underlying set  $X$ , identified with the continuous functions  $* \rightarrow (X, \tau)$  via example 3.6.

By prop. 2.35, the frame homomorphisms  $\phi: \tau_X \rightarrow \tau_*$  are identified with the irreducible closed subspaces  $X \setminus U_\emptyset(\phi)$  of  $(X, \tau_X)$ . Therefore by assumption of [sobriety](#) of  $(X, \tau)$  there is a unique point  $x \in X$  with  $X \setminus U_\emptyset = \text{Cl}(\{x\})$ . In particular this means that for  $U_x$  an open neighbourhood of  $x$ , then  $U_x$  is not a subset of  $U_\emptyset(\phi)$ , and so it follows that  $\phi(U_x) = \{1\}$ . In conclusion we have found a unique  $x \in X$  such that

$$\phi : U \mapsto \begin{cases} \{1\} & | \text{ if } x \in U \\ \emptyset & | \text{ otherwise } \end{cases}.$$

This is precisely the [inverse image](#) function of the continuous function  $* \rightarrow X$  which sends  $1 \mapsto x$ .

Hence this establishes the bijection between frame homomorphisms of the form  $\tau_* \leftarrow \tau_X$  and continuous functions of the form  $* \rightarrow (X, \tau)$ .

With this it follows that a general frame homomorphism of the form  $\tau_X \xleftarrow{\phi} \tau_Y$  defines a function of sets  $X \xrightarrow{f} Y$  by [composition](#):

$$\begin{array}{ccc} X & \xrightarrow{f} & Y \\ (\tau_* \leftarrow \tau_X) & \mapsto & (\tau_* \leftarrow \tau_X \xleftarrow{\phi} \tau_Y) \end{array}.$$

By the previous analysis, an element  $U_Y \in \tau_Y$  is sent to  $\{1\}$  under this composite precisely if the corresponding point  $* \rightarrow X \xrightarrow{f} Y$  is in  $U_Y$ , and similarly for an element  $U_X \in \tau_X$ . It follows that  $\phi(U_Y) \in \tau_X$  is precisely that subset of points in  $X$  which are sent by  $f$  to elements of  $U_Y$ , hence that  $\phi = f^{-1}$  is the [pre-image](#) function of  $f$ . Since  $\phi$  by definition sends open subsets of  $Y$  to open subsets of  $X$ , it follows that  $f$  is indeed a continuous function. This proves the claim in generality. ■

### Remark 5.6. ([locales](#))

Proposition 5.5 is often stated as saying that sober topological spaces are [equivalently](#) the “[locales with enough points](#)” (Johnstone 82, II 1.). Here “[locale](#)” refers to a concept akin to topological spaces where one considers *just* a “[frame of open subsets](#)”  $\tau_X$ , without requiring that its elements be actual [subsets](#) of some ambient set. The natural notion of [homomorphism](#) between such generalized topological spaces are clearly the [frame](#) homomorphisms  $\tau_X \leftarrow \tau_Y$  as above. From this perspective, prop. 5.5 says that sober topological spaces  $(X, \tau_X)$  are entirely characterized by their [frames of opens](#)  $\tau_X$  and just so happen to “have enough points” such that these are actual open subsets of some ambient set, namely of  $X$ .

## Sober reflection

We saw above in prop. 4.22 that every topological space has a “best approximation from the left” by a [Hausdorff topological space](#). We now discuss the analogous statement for [sober topological spaces](#).

Recall again the [point topological space](#)  $* := (\{1\}, \tau_* = \{\emptyset, \{1\}\})$  (example 2.10).

**Definition 5.7.** Let  $(X, \tau)$  be a [topological space](#).

Define  $SX$  to be the set

$$SX := \mathrm{Hom}_{\mathrm{Frame}}(\tau_X, \tau_*)$$

of [frame homomorphisms](#) from the [frame of opens](#) of  $X$  to that of the point.

Define a [topology](#)  $\tau_{SX} \subset P(SX)$  on this set by declaring it to have one element  $\tilde{U}$  for each element  $U \in \tau_X$  and given by

$$\tilde{U} := \{\phi \in SX \mid \phi(U) = \{1\}\}.$$

Consider the function

$$\begin{aligned} X &\xrightarrow{s_X} SX \\ x &\mapsto (\mathrm{const}_x)^{-1} \end{aligned}$$

which sends an element  $x \in X$  to the function which assigns [inverse images](#) of the [constant function](#)  $\mathrm{const}_x : \{1\} \rightarrow X$  on that element.

**Lemma 5.8.** *The construction  $(SX, \tau_{SX})$  in [def. 5.7](#) is a [topological space](#), and the function  $s_X : X \rightarrow SX$  is a [continuous function](#)*

$$s_X : (X, \tau_X) \rightarrow (SX, \tau_{SX})$$

**Proof.** To see that  $\tau_{SX} \subset P(SX)$  is closed under arbitrary unions and finite intersections, observe that the function

$$\begin{aligned} \tau_X &\xrightarrow{\widetilde{(-)}} \tau_{SX} \\ U &\mapsto \tilde{U} \end{aligned}$$

in fact preserves arbitrary unions and finite intersections. Whith this the statement follows by the fact that  $\tau_X$  is closed under these operations.

To see that  $\widetilde{(-)}$  indeed preserves unions, observe that (e.g. [Johnstone 82, II 1.3 Lemma](#))

$$\begin{aligned} p \in \bigcup_{i \in I} \tilde{U}_i &\Leftrightarrow \exists_{i \in I} p(U_i) = \{1\} \\ &\Leftrightarrow \bigcup_{i \in I} p(U_i) = \{1\} \\ &\Leftrightarrow p\left(\bigcup_{i \in I} U_i\right) = \{1\} \\ &\Leftrightarrow p \in \widetilde{\bigcup_{i \in I} U_i} \end{aligned}$$

where we used that the frame homomorphism  $p : \tau_X \rightarrow \tau_*$  preserves unions. Similarly for intersections, now with  $I$  a [finite set](#):



$$\begin{aligned}
p \in \bigcap_{i \in I} \widetilde{U}_i &\Leftrightarrow \forall_{i \in I} p(U_i) = \{1\} \\
&\Leftrightarrow \bigcap_{i \in I} p(U_i) = \{1\} \\
&\Leftrightarrow p\left(\bigcap_{i \in I} U_i\right) = \{1\}' \\
&\Leftrightarrow p \in \overline{\bigcap_{i \in I} U_i}
\end{aligned}$$

where now we used that the frame homomorphism  $p$  preserves finite intersections.

To see that  $s_X$  is continuous, observe that  $s_X^{-1}(\tilde{U}) = U$ , by construction. ■

**Lemma 5.9.** *For  $(X, \tau_X)$  a [topological space](#), the function  $s_X: X \rightarrow SX$  from [def. 5.7](#) is*

1. an [injection](#) precisely if  $X$  is  $T_0$  ([def. 4.4](#));
2. a [bijection](#) precisely if  $X$  is [sober](#) ([def. 5.1](#)).

*In this case  $s_X$  is in fact a [homeomorphism](#).*

**Proof.** By [lemma 2.35](#) there is an identification  $SX \simeq \text{IrrClSub}(X)$  and via this  $s_X$  is identified with the map  $x \mapsto \text{Cl}(\{x\})$ .

Hence the second statement follows by definition, and the first statement by [this prop.](#).

That in the second case  $s_X$  is in fact a homeomorphism follows from the definition of the opens  $\tilde{U}$ : they are identified with the opens  $U$  in this case (...expand...). ■

**Lemma 5.10.** *For  $(X, \tau)$  a [topological space](#), then the topological space  $(SX, \tau_{SX})$  from [def. 5.7](#), [lemma 5.8](#) is sober.*

(e.g. [Johnstone 82](#), lemma II 1.7)

**Proof.** Let  $SX \setminus \tilde{U}$  be an [irreducible closed subspace](#) of  $(SX, \tau_{SX})$ . We need to show that it is the [topological closure](#) of a unique element  $\phi \in SX$ .

Observe first that also  $X \setminus U$  is irreducible.

To see this use [this prop.](#), saying that irreducibility of  $X \setminus U$  is equivalent to  $U_1 \cap U_2 \subset U \Rightarrow (U_1 \subset U) \text{ or } (U_2 \subset U)$ . But if  $U_1 \cap U_2 \subset U$  then also  $\tilde{U}_1 \cap \tilde{U}_2 \subset \tilde{U}$  (as in the [proof of lemma 5.8](#)) and hence by assumption on  $\tilde{U}$  it follows that  $\tilde{U}_1 \subset \tilde{U}$  or  $\tilde{U}_2 \subset \tilde{U}$ . By [lemma 2.35](#) this in turn implies  $U_1 \subset U$  or  $U_2 \subset U$ . In conclusion, this shows that also  $X \setminus U$  is irreducible .

By [lemma 2.35](#) this irreducible closed subspace corresponds to a point  $p \in SX$ . By that same lemma, this frame homomorphism  $p: \tau_X \rightarrow \tau_*$  takes the value  $\emptyset$  on all those opens which are inside  $U$ . This means that the [topological closure](#) of this point is just  $SX \setminus \tilde{U}$ .

This shows that there exists at least one point of which  $X \setminus \tilde{U}$  is the topological closure. It remains to see that there is no other such point.

So let  $p_1 \neq p_2 \in SX$  be two distinct points. This means that there exists  $U \in \tau_X$  with  $p_1(U) \neq p_2(U)$ . Equivalently this says that  $\tilde{U}$  contains one of the two points, but not the other. This means that  $(SX, \tau_{SX})$  is **T0**. By [this prop.](#) this is equivalent to there being no two points with the same topological closure. ■

**Proposition 5.11.** *For  $(X, \tau_X)$  any [topological space](#), for  $(Y, \tau_Y^{\text{sob}})$  a sober topological space, and for  $f: (X, \tau_X) \rightarrow (Y, \tau_Y)$  a [continuous function](#), then it factors uniquely through the soberification  $s_X: (X, \tau_X) \rightarrow (SX, \tau_{SX})$  from [def. 5.7](#), [lemma 5.8](#)*

$$\begin{array}{ccc} (X, \tau_X) & \xrightarrow{f} & (Y, \tau_Y^{\text{sob}}) \\ s_X \downarrow & \nearrow_{\exists!} & \\ (SX, \tau_{SX}) & & \end{array} .$$

**Proof.** By the construction in [def. 5.7](#), we the outer part of the following square [commutes](#):

$$\begin{array}{ccc} (X, \tau_X) & \xrightarrow{f} & (Y, \tau_Y^{\text{sob}}) \\ s_X \downarrow & \nearrow & \downarrow s_{SX} \\ (SX, \tau_{SX}) & \xrightarrow{s_f} & (SSX, \tau_{SSX}) \end{array} .$$

By [lemma 5.10](#) and [lemma 5.9](#), the right vertical morphism  $s_{SX}$  is an isomorphism (a [homeomorphism](#)), hence has an [inverse morphism](#). This defines the diagonal morphism, which is the desired factorization.

To see that this factorization is unique, consider two factorizations  $\tilde{f}, \bar{f}: (SX, \tau_{SX}) \rightarrow (Y, \tau_Y^{\text{sob}})$  and apply the soberification construction once more to the triangles

$$\begin{array}{ccc} (X, \tau_X) & \xrightarrow{f} & (Y, \tau_Y^{\text{sob}}) \\ s_X \downarrow & \nearrow_{\tilde{f}, \bar{f}} & \\ (SX, \tau_{SX}) & & \end{array} \quad \mapsto \quad \begin{array}{ccc} (SX, \tau_{SX}) & \xrightarrow{s_f} & (Y, \tau_Y^{\text{sob}}) \\ \simeq \downarrow & \nearrow_{\tilde{f}, \bar{f}} & \\ (SX, \tau_{SX}) & & \end{array} .$$

Here on the right we used again [lemma 5.9](#) to find that the vertical morphism is an isomorphism, and that  $\tilde{f}$  and  $\bar{f}$  do not change under soberification, as they already map between sober spaces. But now that the left vertical morphism is an isomorphism, the commutativity of this triangle for both  $\tilde{f}$  and  $\bar{f}$  implies that  $\tilde{f} = \bar{f}$ . ■

## 6. Compact spaces

From the discussion of [compact metric spaces](#) in [def. 1.19](#) and [prop. 1.20](#) it is now immediate how to generalize the concept to [topological spaces](#) to obtain a

notion of [compact topological spaces](#) (def. 6.2 and def. 6.4 below). These compact spaces play a special role in [topology](#), much like [finite dimensional vector spaces](#) do in [linear algebra](#).

The most naive version of the definition directly generalizes the concept via converging sequences from def. 1.19:

### Definition 6.1. (converging sequence in a topological space)

Let  $(X, \tau)$  be a [topological space](#) (def. 2.3) and let  $(x_n)_{n \in \mathbb{N}}$  be a [sequence](#) of points  $(x_n)$  in  $X$  (def. 1.15). We say that this sequence [converges](#) in  $(X, \tau)$  to a point  $x_\infty \in X$ , denoted

$$x_n \xrightarrow{n \rightarrow \infty} x_\infty$$

if for each open [neighbourhood](#)  $U_{x_\infty}$  of  $x_\infty$  there exists a  $k \in \mathbb{N}$  such that for all  $n \geq k$  then  $x_n \in U_{x_\infty}$ :

$$\left( x_n \xrightarrow{n \rightarrow \infty} x_\infty \right) \Leftrightarrow \bigvee_{\substack{U_{x_\infty} \in \tau_X \\ x_\infty \in U_{x_\infty}}} \left( \exists_{k \in \mathbb{N}} \left( \forall_{n \geq k} x_n \in U_{x_\infty} \right) \right).$$

### Definition 6.2. ([sequentially compact topological space](#))

Let  $(X, \tau)$  be a [topological space](#) (def. 2.3). It is called [sequentially compact](#) if for every [sequence](#) of points  $(x_n)$  in  $X$  (def. 1.15) there exists a sub-sequence  $(x_{n_k})_{k \in \mathbb{N}}$  which [converges](#) according to def. 6.1.

But prop. 1.20 suggests to consider also another definition of compactness for topological spaces:

### Definition 6.3. ([open cover](#))

An [open cover](#) of a [topological space](#)  $X$  (def. 2.3) is a [set](#)  $\{U_i \subset X\}_{i \in I}$  of [open subsets](#)  $U_i$  of  $X$ , indexed by some [set](#)  $I$ , such that their [union](#) is all of  $X$ :

$$\bigcup_{i \in I} U_i = X.$$

### Definition 6.4. ([compact topological space](#))

A [topological space](#)  $X$  (def. 2.3) is called a [compact topological space](#) if every [open cover](#)  $\{U_i \subset X\}_{i \in I}$  (def. 6.3) has a *finite subcover* in that there is a [finite subset](#)  $J \subset I$  such that  $\{U_i \subset X\}_{i \in J}$  is still a cover of  $X$  in that  $\bigcup_{i \in J} U_i = X$ .

### Remark 6.5. (terminology issue regarding “compact”)

Beware that the following terminology issue persists in the literature:

Some authors use “compact” to mean “[Hausdorff and compact](#)”. To disambiguate this, some authors (mostly in [algebraic geometry](#), but also for

instance Waldhausen) say “quasi-compact” for what we call “compact” in prop. 6.4.

There are several equivalent reformulation of the compactness condition:

**Proposition 6.6. (compactness in terms of closed subsets)**

Let  $(X, \tau)$  be a topological space. Then the following are equivalent:

1.  $(X, \tau)$  is compact in the sense of def. 6.4.
2. Let  $\{C_i \subset X\}_{i \in I}$  be a set of closed subsets (def. 2.21) such that their intersection is empty  $\bigcap_{i \in I} C_i = \emptyset$ , then there is a finite subset  $J \subset I$  such that the corresponding finite intersection is still empty  $\bigcap_{i \in J \subset I} C_i = \emptyset$ .
3. Let  $\{C_i \subset X\}_{i \in I}$  be a set of closed subsets (def. 2.21) such that it enjoys the finite intersection property, meaning that for every finite subset  $J \subset I$  then the corresponding finite intersection is non-empty  $\bigcap_{i \in J \subset I} C_i \neq \emptyset$ . Then also the total intersection is non-empty,  $\bigcap_{i \in I} C_i \neq \emptyset$ .

**Proof.** The equivalence between the first and the second statement is immediate by de Morgan's law (remark 2.22). The equivalence between the first and the third proceeds similarly, via a proof by contradiction. ■

**Example 6.7. (finite discrete spaces are compact)**

A discrete topological space (def. 2.13) is compact (def. 6.4) precisely if its underlying set is finite.

**Example 6.8. (closed intervals are compact)**

For any  $a < b \in \mathbb{R}$  the closed interval (example 1.12)

$$[a, b] \subset \mathbb{R}$$

regarded with its subspace topology is a compact topological space (def. 6.4).

**Proof.** Since all the closed intervals are homeomorphic (by example 3.26) it is sufficient to show the statement for  $[0, 1]$ . Hence let  $\{U_i \subset [0, 1]\}_{i \in I}$  be an open cover. We need to show that it has an open subcover.

Say that an element  $x \in [0, 1]$  is *admissible* if the closed sub-interval  $[0, x]$  is covered by finitely many of the  $U_i$ . In this terminology, what we need to show is that 1 is admissible.

Observe from the definition that

1. 0 is admissible,
2. if  $y < x \in [0, 1]$  and  $x$  is admissible, then also  $y$  is admissible.

This means that the set of admissible  $x$  forms either an [open interval](#)  $[0, g)$  or a [closed interval](#)  $[0, g]$ , for some  $g \in [0, 1]$ . We need to show that the latter is true, and for  $g = 1$ . We do so by observing that the alternatives lead to contradictions:

1. Assume that the set of admissible values were an open interval  $[0, g)$ . By assumption there would be a finite subset  $J \subset I$  such that  $\{U_i \subset [0, 1]\}_{i \in J \subset I}$  were a finite open cover of  $[0, g)$ . Accordingly, since there is some  $i_g \in I$  such that  $g \in U_{i_g}$ , the union  $\{U_i\}_{i \in J} \sqcup \{U_{i_g}\}$  were a finite cover of the closed interval  $[0, g]$ , contradicting the assumption that  $g$  itself is not admissible (since it is not contained in  $[0, g)$ ).
2. Assume that the set of admissible values were a closed interval  $[0, g]$  for  $g < 1$ . By assumption there would then be a finite set  $J \subset I$  such that  $\{U_i \subset [0, 1]\}_{i \in J \subset I}$  were a finite cover of  $[0, g]$ . Hence there would be an index  $i_g \in J$  such that  $g \in U_{i_g}$ . But then by the nature of open subsets in the Euclidean space  $\mathbb{R}$ , this  $U_{i_g}$  would also contain an open ball  $B_g^\circ(\epsilon) = (g - \epsilon, g + \epsilon)$ . This would mean that the set of admissible values includes the open interval  $[0, g + \epsilon)$ , contradicting the assumption.

This gives a [proof by contradiction](#). ■

### Proposition 6.9. (binary [Tychonoff theorem](#))

Let  $(X, \tau_X)$  and  $(Y, \tau_Y)$  be two [compact topological spaces](#) (def. 6.4). Then also their [product topological space](#) (def. 2.18)  $(X \times Y, \tau_{X \times Y})$  is compact.

**Proof.** Let  $\{U_i \subset X \times Y\}_{i \in I}$  be an [open cover](#) of the product space. We need to show that this has a finite subcover.

By definition of the product space topology, each  $U_i$  is the union, indexed by some set  $K_i$ , of [Cartesian products](#) of open subsets of  $X$  and  $Y$ :

$$U_i = \bigcup_{k_i \in K_i} (V_{k_i} \times W_{k_i}) \quad V_{k_i} \in \tau_X \quad \text{and} \quad W_{k_i} \in \tau_Y .$$

Consider then the [disjoint union](#) of all these index sets

$$K := \bigsqcup_{i \in I} K_i .$$

This is such that

$$(\star) \quad \{V_{k_i} \times W_{k_i} \subset X \times Y\}_{k_i \in K}$$

is again an open cover of  $X \times Y$ .

But by construction, each element  $V_{k_i} \times W_{k_i}$  of this new cover is contained in at least one  $U_{j(k_i)}$  of the original cover. Therefore it is now sufficient to show that there is a finite subcover of  $(\star)$ , consisting of elements indexed by  $k_i \in K_{\text{fin}} \subset K$  for

some [finite set](#)  $K_{\text{fin}}$ . Because then the corresponding  $U_{j(k_i)}$  for  $k_i \in K_{\text{fin}}$  form a finite subcover of the original cover.

In order to see that  $(\star)$  has a finite subcover, first fix a point  $x \in X$  and write  $\{x\} \subset X$  for the corresponding [singleton topological subspace](#). By [example 3.25](#) this is [homeomorphic](#) to the abstract [point space](#)  $*$ . By [example 3.27](#) there is thus a [homeomorphism](#) of the form

$$\{x\} \times Y \simeq Y .$$

Therefore, since  $(Y, \tau_Y)$  is assumed to be [compact](#), the open cover

$$\{(V_{k_1} \times W_{k_1}) \cap (\{x\} \times Y)\} \subset \{x\} \times Y\}_{k_i \in K}$$

has a finite subcover, indexed by a [finite subset](#)  $J_x \subset K$ .

Here we may assume without restriction of generality that  $x \in V_{k_i}$  for all  $k_i \in J_x \subset K$ , because if not then we may simply remove that index and still have a (finite) subcover.

By finiteness of  $J_x$  it now follows that the intersection

$$V_x := \bigcap_{k_i \in J_x} V_{k_i}$$

is still an open subset, and by the previous remark we may assume without restriction that

$$x \in V_x .$$

Now observe that by the nature of the above cover of  $\{x\} \times Y$  we have

$$\{x\} \times Y \subset \bigcup_{k_i \in J_x \subset K} V_{k_i} \times W_{k_i}$$

and hence

$$\{x\} \times Y \subset \{x\} \times \bigcup_{k_i \in J_x \subset K} W_{k_i} .$$

Since by construction  $V_x \subset V_{k_i}$  for all  $k_i \in J_x \subset K$ , it follows that we have found a finite cover not just of  $\{x\} \times Y$  but of  $V_x \times Y$

$$V_x \times Y \subset \bigcup_{k_i \in J_x \subset K} (V_{k_i} \times W_{k_i}) .$$

To conclude, observe that  $\{V_x \subset X\}_{x \in X}$  is clearly an open cover of  $X$ , so that by the assumption that also  $X$  is compact there is a finite set of points  $S \subset X$  so that  $\{V_x \subset X\}_{x \in S \subset X}$  is still a cover. In summary then

$$\{V_{k_i} \times W_{k_i} \subset X \times Y\}_{\substack{x \in S \subset X \\ k_i \in J_x \subset K}}$$

is a finite subcover as required. ■

In terms of the topological incarnation of the definitions of compactness, the familiar statement about metric spaces from prop. 1.20 now equivalently says the following:

**Proposition 6.10. (sequentially compact metric spaces are equivalently compact metric spaces)**

If  $(X, d)$  is a metric space, regarded as a topological space via its metric topology (example 2.9), then the following are equivalent:

1.  $(X, d)$  is a compact topological space (def. 6.4).
2.  $(X, d)$  is a sequentially compact topological space (def. 6.2).

**Proof.** of prop. 1.20 and prop. 6.10

Assume first that  $(X, d)$  is a compact topological space. Let  $(x_k)_{k \in \mathbb{N}}$  be a sequence in  $X$ . We need to show that it has a sub-sequence which converges.

Consider the topological closures of the sub-sequences that omit the first  $n$  elements of the sequence

$$F_n := \text{Cl}(\{x_k \mid k \geq n\})$$

and write

$$U_n := X \setminus F_n$$

for their open complements.

Assume now that the intersection of all the  $F_n$  were empty

$$(\star) \quad \bigcap_{n \in \mathbb{N}} F_n = \emptyset$$

or equivalently that the union of all the  $U_n$  were all of  $X$

$$\bigcup_{n \in \mathbb{N}} U_n = X,$$

hence that  $\{U_n \rightarrow X\}_{n \in \mathbb{N}}$  were an open cover. By the assumption that  $X$  is compact, this would imply that there is a finite subset  $\{i_1 < i_2 < \dots < i_k\} \subset \mathbb{N}$  with

$$\begin{aligned} X &= U_{i_1} \cup U_{i_2} \cup \dots \cup U_{i_k} \\ &= U_{i_k} \end{aligned}$$

This in turn would mean that  $F_{i_k} = \emptyset$ , which contradicts the construction of  $F_{i_k}$ . Hence we have a proof by contradiction that assumption  $(\star)$  is wrong, and hence that there must exist an element

$$x \in \bigcap_{n \in \mathbb{N}} F_n.$$

By definition of [topological closure](#) this means that for all  $n$  the [open ball](#)  $B_x^\circ(1/(n+1))$  around  $x$  of [radius](#)  $1/(n+1)$  must intersect the  $n$ th of the above subsequence:

$$B_x^\circ(1/(n+1)) \cap \{x_k \mid k \geq n\} \neq \emptyset.$$

Picking one point  $(x'_n)$  in the  $n$ th such intersection for all  $n$  hence defines a sub-sequence, which converges to  $x$ .

This proves that compact implies sequentially compact for metric spaces.

For the converse, assume now that  $(X, d)$  is sequentially compact. Let  $\{U_i \rightarrow X\}_{i \in I}$  be an [open cover](#) of  $X$ . We need to show that there exists a finite sub-cover.

Now by the [Lebesgue number lemma](#), there exists a positive real number  $\delta > 0$  such that for each  $x \in X$  there is  $i_x \in I$  such that  $B_x^\circ(\delta) \subset U_{i_x}$ . Moreover, since [sequentially compact metric spaces are totally bounded](#), there exists then a [finite set](#)  $S \subset X$  such that

$$X = \bigcup_{s \in S} B_s^\circ(\delta).$$

Therefore  $\{U_{i_s} \rightarrow X\}_{s \in S}$  is a finite sub-cover as required. ■

**Remark 6.11. (neither compactness nor sequential compactness implies the other)**

Beware that, in contrast to prop. 6.10, for general topological spaces being [sequentially compact](#) neither implies nor is implied by being [compact](#). The corresponding counter-examples are maybe beyond the scope of this note, but see for instance [Vermeeren 10](#), prop. 17 and prop. 18.

In [analysis](#), the [extreme value theorem](#) asserts that a [real](#)-valued [continuous function](#) on the [bounded closed interval](#) (def. 1.12) attains its [maximum](#) and [minimum](#). The following is the generalization of this statement to general topological spaces:

**Lemma 6.12. ([continuous surjections out of compact spaces have compact codomain](#))**

Let  $f: (X, \tau_X) \rightarrow (Y, \tau_Y)$  be a [continuous function](#) between [topological spaces](#) such that

1.  $(X, \tau_X)$  is a [compact topological space](#);
2.  $f: X \rightarrow Y$  is a [surjective function](#).

Then also  $(Y, \tau_Y)$  is [compact](#).



**Proof.** Let  $\{U_i \subset Y\}_{i \in I}$  be an [open cover](#) of  $Y$ . We need show that this has a finite sub-cover.

By the continuity of  $f$  the [pre-images](#)  $f^{-1}(U_i)$  are [open subsets](#) of  $X$ , and by the surjectivity of  $f$  they form an [open cover](#)  $\{f^{-1}(U_i) \subset X\}_{i \in I}$  of  $X$ . Hence by compactness of  $X$ , there exists a [finite subset](#)  $J \subset I$  such that  $\{f^{-1}(U_i) \subset X\}_{i \in J \subset I}$  is still an open cover of  $X$ . Finally, using again that  $f$  is assumed to be surjective, it follows that

$$\begin{aligned} Y &= f(X) \\ &= f\left(\bigcup_{i \in J} f^{-1}(U_i)\right) \\ &= \bigcup_{i \in J} U_i \end{aligned}$$

which means that also  $\{U_i \subset Y\}_{i \in J \subset I}$  is still an open cover of  $Y$ , and in particular a finite subcover of the original cover. ■

**Corollary 6.13. ([continuous images of compact spaces are compact](#))**

*If  $f: X \rightarrow Y$  is a [continuous function](#) out of a [compact topological space](#)  $X$  which is not necessarily [surjective](#), then we may consider its [image factorization](#)*

$$f : X \rightarrow f(X) \hookrightarrow Y$$

*as in example 3.10. Now by construction  $X \rightarrow f(X)$  is surjective, and so lemma 6.12 implies that  $f(X)$  is compact.*

The converse to cor. 6.13 does not hold in general: the pre-image of a compact subset under a continuous function need not be compact again. If this is the case, then we speak of [proper maps](#):

**Definition 6.14. ([proper maps](#))**

A [continuous function](#)  $f: (X, \tau_X) \rightarrow (Y, \tau_Y)$  is called [proper](#) if for  $C \in Y$  a [compact topological subspace](#) of  $Y$ , then also its [pre-image](#)  $f^{-1}(C)$  is [compact](#) in  $X$ .

There are various variants of the concept of compact spaces.

**Definition 6.15. ([locally compact topological space](#))**

A [topological space](#) is called [locally compact](#) if every point has a [neighbourhood](#) which is [compact](#) (def. 6.4).

**Remark 6.16. (terminology issue regarding “locally compact”)**

On top of the terminology issue inherited from that of “compact” (remark 6.5), the definition of “locally compact” is subject to further ambiguity in the literature. There are various definitions of locally compact spaces alternative to def. 6.15. For [Hausdorff topological spaces](#) all these definitions used happen to be equivalent, but in general they are not. The version we state in def. 6.15 is

the one that makes prop. 6.18 below work *without* requiring the Hausdorff property.

**Definition 6.17. (mapping space with compact-open topology)**

For  $X$  a topological space and  $Y$  a locally compact topological space (def. 6.15) then the mapping space

$$(X^Y, \tau_{(X^Y)})$$

is the topological space

- whose underlying set  $X^Y$  is the set of continuous functions  $Y \rightarrow X$ ,
- whose topology  $\tau_{(X^Y)}$  is generated from the sub-basis for the topology (def. 2.7) which is given by subsets denoted

$$U^K \subset \text{Hom}_{\text{Top}}(Y, X) \text{ for}$$

- $K \hookrightarrow Y$  a compact subset
- $U \hookrightarrow X$  an open subset

and defined to be those subsets of all those continuous functions  $f$  that fit into a commuting diagram of the form

$$\begin{array}{ccc} K & \hookrightarrow & Y \\ \downarrow & & \downarrow f \\ U & \hookrightarrow & X \end{array}$$

Accordingly this  $\tau_{(X^Y)}$  is called the compact-open topology on the set of functions.

The construction extends to a functor

$$(-)^{(-)} : \text{Top}_{\text{lcomp}}^{\text{op}} \times \text{Top} \rightarrow \text{Top} .$$

**Proposition 6.18.** *For  $X$  a topological space and  $Y$  a locally compact topological space, then then mapping space  $X^Y$  with its compact-open topology from def. 6.17 is an exponential object in Top.*

## Relation to Hausdorff spaces

We discuss some important relations between the concepts of compact spaces and of Hausdorff topological spaces.

**Proposition 6.19. (closed subspaces of compact Hausdorff spaces are equivalently compact subspaces)**

Let  $(X, \tau)$  be a [compact Hausdorff topological space](#) (def. 4.4, def. 6.4) and let  $Y \subset X$  be a [topological subspace](#). Then the following are equivalent:

1.  $Y \subset X$  is a [closed subspace](#) (def. 2.21);
2.  $Y$  is a [compact topological space](#).

**Proof.** By lemma 6.20 and lemma 6.22 below. ■

**Lemma 6.20. ([closed subspaces of compact spaces are compact](#))**

Let  $(X, \tau)$  be a [compact topological space](#) (def. 6.4), and let  $Y \subset X$  be a [closed topological subspace](#). Then also  $Y$  is [compact](#).

**Proof.** Let  $\{V_i \subset Y\}_{i \in I}$  be an [open cover](#) of  $Y$ . We need to show that this has a finite sub-cover.

By definition of the [subspace topology](#), there exist open subsets  $U_i$  of  $X$  with

$$V_i = U_i \cap Y.$$

By the assumption that  $Y$  is closed, the [complement](#)  $X \setminus Y$  is an open subset of  $X$ , and therefore

$$\{X \setminus Y \subset X\} \cup \{U_i \subset X\}_{i \in I}$$

is an [open cover](#) of  $X$ . Now by the assumption that  $X$  is compact, this latter cover has a finite subcover, hence there exists a [finite subset](#)  $J \subset I$  such that

$$\{X \setminus Y \subset X\} \cup \{U_i \subset X\}_{i \in J \subset I}$$

is still an open cover of  $X$ , hence in particular intersects to a finite open cover of  $Y$ . But since  $Y \cap (X \setminus Y) = \emptyset$ , it follows that indeed

$$\{V_i \subset Y\}_{i \in J \subset I}$$

is a cover of  $Y$ , and in indeed a finite subcover of the original one. ■

**Lemma 6.21. ([separation by neighbourhoods of points from compact subspaces in Hausdorff spaces](#))**

Let

1.  $(X, \tau)$  be a [Hausdorff topological space](#);
2.  $Y \subset X$  a [compact subspace](#).

Then for every  $x \in X \setminus Y$  there exists

1. an [open neighbourhood](#)  $U_x \supset \{x\}$ ;
2. an open neighbourhood  $U_Y \supset Y$

such that

- they are still disjoint:  $U_x \cap U_Y = \emptyset$ .

**Proof.** By the assumption that  $(X, \tau)$  is Hausdorff, we find for every point  $y \in Y$  disjoint open neighbourhoods  $U_{x,y} \supset \{x\}$  and  $U_y \supset \{y\}$ . By the nature of the [subspace topology](#) of  $Y$ , the restriction of all the  $U_y$  to  $Y$  is an [open cover](#) of  $Y$ :

$$\{(U_y \cap Y) \subset Y\}_{y \in Y}.$$

Now by the assumption that  $Y$  is compact, there exists a finite subcover, hence a [finite set](#)  $S \subset Y$  such that

$$\{(U_y \cap Y) \subset Y\}_{y \in S \subset Y}$$

is still a cover.

But the finite intersection

$$U_x := \bigcap_{s \in S \subset Y} U_{x,s}$$

of the corresponding open neighbourhoods of  $x$  is still open, and by construction it is disjoint from all the  $U_s$ , hence in particular from their union

$$U_Y := \bigcup_{s \in S \subset Y} U_s.$$

Therefore  $U_x$  and  $U_Y$  are two open subsets as required. ■

Lemma [6.21](#) immediately implies the following:

**Lemma 6.22. ([compact subspaces of Hausdorff spaces are closed](#))**

Let  $(X, \tau)$  be a [Hausdorff topological space](#) (def. [4.4](#)) and let  $C \subset X$  be a [compact](#) (def. [6.4](#)) [topological subspace](#) (example [2.16](#)). Then  $C \subset X$  is also a [closed subspace](#) (def. [2.21](#)).

**Proof.** Let  $x \in X \setminus C$  be any point of  $X$  not contained in  $C$ . We need to show that there exists an [open neighbourhood](#) of  $x$  in  $X$  which does not [intersect](#)  $C$ . This is implied by lemma [6.21](#). ■

**Proposition 6.23. ([Heine-Borel theorem](#))**

For  $n \in \mathbb{N}$ , regard  $\mathbb{R}^n$  as the  $n$ -dimensional [Euclidean space](#) via example [1.6](#), regarded as a [topological space](#) via its [metric topology](#) (example [2.9](#)).

Then for a [topological subspace](#)  $S \subset \mathbb{R}^n$  the following are equivalent:

1.  $S$  is [compact](#) (def. [6.4](#));
2.  $S$  is [closed](#) (def. [2.21](#)) and [bounded](#) (def. [1.3](#)).

**Proof.** First consider a [subset](#)  $S \subset \mathbb{R}^n$  which is closed and bounded. We need to show that regarded as a [topological subspace](#) it is [compact](#).

The assumption that  $S$  is bounded by (hence contained in) some [open ball](#)  $B_x^\circ(\epsilon)$  in  $\mathbb{R}^n$  implies that it is contained in  $\{(x_i)_{i=1}^n \in \mathbb{R}^n \mid -\epsilon \leq x_i \leq \epsilon\}$ . By [example 3.28](#), this topological subspace is homeomorphic to the  $n$ -cube  $[-\epsilon, \epsilon]^n$ . Since the closed interval  $[-\epsilon, \epsilon]$  is compact by [example 6.8](#), the binary [Tychonoff theorem](#) (prop. [6.9](#)) implies that this  $n$ -cube is compact. Since [closed subspaces of compact spaces are compact](#) (lemma [6.20](#)) this implies that  $S$  is compact.

Conversely, assume that  $S \subset \mathbb{R}^n$  is a compact subspace. We need to show that it is closed and bounded.

The first statement follows since the [Euclidean space](#)  $\mathbb{R}^n$  is [Hausdorff](#) ([example 4.8](#)) and since [compact subspaces of Hausdorff spaces are closed](#) (prop. [6.22](#)).

Hence what remains is to show that  $S$  is bounded.

To that end, choose any [positive real number](#)  $\epsilon \in \mathbb{R}_{>0}$  and consider the [open cover](#) of all of  $\mathbb{R}^n$  by the open [n-cubes](#)

$$(k_1 - \epsilon, k_1 + 1 + \epsilon) \times (k_2 - \epsilon, k_2 + 1 + \epsilon) \times \cdots \times (k_n - \epsilon, k_n + 1 + \epsilon)$$

for [n-tuples](#) of [integers](#)  $(k_1, k_2, \dots, k_n) \in \mathbb{Z}^n$ . The restrictions of these to  $S$  hence form an open cover of the subspace  $S$ . By the assumption that  $S$  is compact, there is then a finite subset of  $n$ -tuples of integers such that the corresponding  $n$ -cubes still cover  $S$ . But the union of any finite number of bounded closed  $n$ -cubes in  $\mathbb{R}^n$  is clearly a bounded subset, and hence so is  $S$ . ■

**Proposition 6.24. ([maps from compact spaces to Hausdorff spaces are closed and proper](#))**

Let  $f: (X, \tau_X) \rightarrow (Y, \tau_Y)$  be a [continuous function](#) between [topological spaces](#) such that

1.  $(X, \tau_X)$  is a [compact topological space](#);
2.  $(Y, \tau_Y)$  is a [Hausdorff topological space](#).

Then  $f$  is

1. a [closed map](#) (def. [3.14](#));
2. a [proper map](#) (def. [6.14](#)).

**Proof.** For the first statement, we need to show that if  $C \subset X$  is a [closed subset](#) of  $X$ , then also  $f(C) \subset Y$  is a closed subset of  $Y$ .

Now

1. since [closed subsets of compact spaces are compact](#) (lemma [6.20](#)) it follows

that  $C \subset X$  is also compact;

2. since [continuous images of compact spaces are compact](#) (cor. 6.13) it then follows that  $f(C) \subset Y$  is compact;
3. since [compact subspaces of Hausdorff spaces are closed](#) (prop. 6.22) it finally follow that  $f(C)$  is also closed in  $Y$ .

For the second statement we need to show that if  $C \subset Y$  is a [compact subset](#), then also its [pre-image](#)  $f^{-1}(C)$  is compact.

Now

1. since [compact subspaces of Hausdorff spaces are closed](#) (prop. 6.22) it follows that  $C \subseteq Y$  is closed;
2. since [pre-images](#) under continuous of closed subsets are closed (prop. 3.2), also  $f^{-1}(C) \subset X$  is closed;
3. since [closed subsets of compact spaces are compact](#) (lemma 6.20), it follows that  $f^{-1}(C)$  is compact.

■

**Proposition 6.25. ([continuous bijections from compact spaces to Hausdorff spaces are homeomorphisms](#))**

Let  $f: (X, \tau_X) \rightarrow (Y, \tau_Y)$  be a [continuous function](#) between [topological spaces](#) such that

1.  $(X, \tau_X)$  is a [compact topological space](#);
2.  $(Y, \tau_Y)$  is a [Hausdorff topological space](#).
3.  $f: X \rightarrow Y$  is a [bijection](#) of [sets](#).

Then  $f$  is a [homeomorphism](#), i. e. its [inverse function](#)  $Y \rightarrow X$  is also a [continuous function](#).

In particular then both  $(X, \tau_X)$  and  $(Y, \tau_Y)$  are [compact Hausdorff spaces](#).

**Proof.** Write  $g: Y \rightarrow X$  for the [inverse function](#) of  $f$ .

We need to show that  $g$  is continuous, hence that for  $U \subset X$  an [open subset](#), then also its [pre-image](#)  $g^{-1}(U) \subset Y$  is open in  $Y$ . By prop. 3.2 this is equivalent to the statement that for  $C \subset X$  a [closed subset](#) then the [pre-image](#)  $g^{-1}(C) \subset Y$  is also closed in  $Y$ .

But since  $g$  is the [inverse function](#) to  $f$ , its [pre-images](#) are the [images](#) of  $f$ . Hence the last statement above equivalently says that  $f$  sends closed subsets to closed subsets. This is true by prop. 6.24. ■

**Proposition 6.26. (compact Hausdorff spaces are normal)**

Every compact Hausdorff topological space is a normal topological space (def. 4.13).

**Proof.** First we claim that  $(X, \tau)$  is regular. To show this, we need to find for each point  $x \in X$  and each disjoint closed subset  $Y \in X$  disjoint open neighbourhoods  $U_x \supset \{x\}$  and  $U_Y \supset Y$ . But since closed subspaces of compact spaces are compact (lemma 6.20), the subset  $Y$  is in fact compact, and hence this is in fact the statement of lemma 6.21.

Next to show that  $(X, \tau)$  is indeed normal, we apply the idea of the proof of lemma 6.21 once more:

Let  $Y_1, Y_2 \subset X$  be two disjoint closed subspaces. By the previous statement then for every point  $y_1 \in Y_1$  we find disjoint open neighbourhoods  $U_{y_1} \supset \{y_1\}$  and  $U_{Y_2, y_1} \supset Y_2$ . The union of the  $U_{y_1}$  is a cover of  $Y_1$ , and by compactness of  $Y_1$  there is a finite subset  $S \subset Y_1$  such that

$$U_{Y_1} := \bigcup_{s \in S \subset Y_1} U_{y_1}$$

is an open neighbourhood of  $Y_1$  and

$$U_{Y_2} := \bigcap_{s \in S \subset Y_1} U_{Y_2, s}$$

is an open neighbourhood of  $Y_2$ , and both are disjoint. ■

**Relation to quotient spaces****Proposition 6.27. (*continuous surjections from compact spaces to Hausdorff spaces are quotient projections*)**

Let

$$\pi : (X, \tau_X) \longrightarrow (Y, \tau_Y)$$

be a continuous function between topological spaces such that

1.  $(X, \tau_X)$  is a compact topological space (def. 6.4);
2.  $(Y, \tau_Y)$  is a Hausdorff topological space (def. 4.4);
3.  $\pi : X \rightarrow Y$  is a surjective function.

Then  $\tau_X$  is the quotient topology inherited from  $\tau_Y$  via the surjection  $f$  (def. 2.17).

**Proof.** We need to show that an subset  $U \subset Y$  is an open subset  $(Y, \tau_Y)$  precisely if

its [pre-image](#)  $\pi^{-1}(U) \subset X$  is an open subset in  $(X, \tau_X)$ . Equivalently, as in prop. [3.2](#), we need to show that  $U$  is a [closed subset](#) precisely if  $\pi^{-1}(U)$  is a closed subset. The implication

$$(U \text{ closed}) \Rightarrow (f^{-1}(U) \text{ closed})$$

follows via prop. [3.2](#) from the continuity of  $\pi$ . The implication

$$(f^{-1}(U) \text{ closed}) \Rightarrow (U \text{ closed})$$

follows since  $\pi$  is a [closed map](#) by prop. [6.24](#). ■

The following proposition allows to recognize when a [quotient space](#) of a compact Hausdorff space is itself still Hausdorff.

**Proposition 6.28. (*quotient projections out of compact Hausdorff spaces are closed precisely if the codomain is Hausdorff*)**

Let

$$\pi : (X, \tau_X) \longrightarrow (Y, \tau_Y)$$

be a [continuous function](#) between [topological spaces](#) such that

1.  $(X, \tau)$  is a [compact Hausdorff topological space](#) (def. [6.4](#), def. [4.4](#));
2.  $\pi$  is a [surjection](#) and  $\tau_Y$  is the corresponding [quotient topology](#) (def. [2.17](#)).

Then the following are equivalent

1.  $(Y, \tau_Y)$  is itself a [Hausdorff topological space](#) (def. [4.4](#));
2.  $\pi$  is a [closed map](#) (def. [3.14](#)).

**Proof.** The implicaton  $((Y, \tau_Y) \text{ Hausdorff}) \Rightarrow (\pi \text{ closed})$  is given by prop. [6.24](#). We need to show the converse.

Hence assume that  $\pi$  is a closed map. We need to show that for every pair of distinct point  $y_1 \neq y_2 \in Y$  there exist [open neighbourhoods](#)  $U_{y_1}, U_{y_2} \in \tau_Y$  which are disjoint,  $U_{y_1} \cap U_{y_2} = \emptyset$ .

Therefore consider the [pre-images](#)

$$C_1 := \pi^{-1}(\{y_1\}) \quad C_2 := \pi^{-1}(\{y_2\}) .$$

Observe that these are [closed subsets](#), because in the Hausdorff space  $(Y, \tau_Y)$  (which is hence in particular  $T_1$ ) the singleton subsets  $\{y_i\}$  are closed by prop. [4.11](#), and since pre-images under continuous functions preserves closed subsets by prop. [3.2](#).

Now since [compact Hausdorff spaces are normal](#) it follows (by def. [4.13](#)) that we



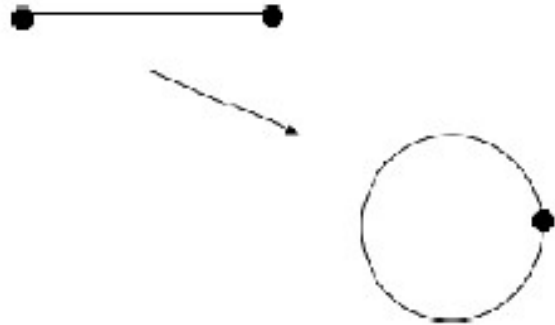
may find disjoint open subset  $U_1, U_2 \in \tau_X$  such that

$$C_1 \subset U_1 \quad C_2 \subset U_2 .$$

Moreover, by lemma 3.20 we may find these  $U_i$  such that they are both [saturated subsets](#) (def. 3.16). Therefore finally lemma 3.20 says that the images  $\pi(U_i)$  are open in  $(Y, \tau_Y)$ . These are now clearly disjoint open neighbourhoods of  $y_1$  and  $y_2$ . ■

**Example 6.29.** Consider the function

$$\begin{aligned} [0, 2\pi] / \sim &\rightarrow S^1 \subset \mathbb{R}^2 \\ t &\mapsto (\cos(t), \sin(t)) \end{aligned}$$



- from the [quotient topological space](#) (def. 2.17) of the [closed interval](#) (def. 1.12) by the [equivalence relation](#) which identifies the two endpoints

$$(x \sim y) \Leftrightarrow ((x = y) \text{ or } ((x \in \{0, 2\pi\} \text{ and } (y \in \{0, 2\pi\}))))$$

- to the unit [circle](#)  $S^1 = S_0(1) \subset \mathbb{R}^2$  (def. 1.2) regarded as a [topological subspace](#) of the 2-dimensional [Euclidean space](#) (example 1.6) equipped with its [metric topology](#) (example 2.9).

This is clearly a [continuous function](#) and a [bijection](#) on the underlying sets. Moreover, since [continuous images of compact spaces are compact](#) (cor. 6.13) and since the closed interval  $[0, 1]$  is compact (example 6.8) we also obtain another proof that the [circle](#) is compact.

Hence by prop. 6.25 the above map is in fact a [homeomorphism](#)

$$[0, 2\pi] / \sim \simeq S^1 .$$

Compare this to the counter-example 3.23, which observed that the analogous function

$$\begin{aligned} [0, 2\pi) &\rightarrow S^1 \subset \mathbb{R}^2 \\ t &\mapsto (\cos(t), \sin(t)) \end{aligned}$$

is *not* a homeomorphism, even though this, too, is a bijection on the the underlying sets. But the [half-open interval](#)  $[0, 2\pi)$  is not compact, and hence prop. 6.25 does not apply.

## 7. Paracompact spaces

**Definition 7.1.** ([locally finite cover](#))

Let  $(X, \tau)$  be a [topological space](#).

An [open cover](#)  $\{U_i \subset X\}_{i \in I}$  of  $X$  is called *locally finite* if for all point  $x \in X$ , there exists a [neighbourhood](#)  $U_x \supset \{x\}$  such that it [intersects](#) only finitely many elements of the cover, hence such that  $U_x \cap U_i \neq \emptyset$  for only a [finite number](#) of  $i \in I$ .

### Definition 7.2. ([refinement of open covers](#))

Let  $(X, \tau)$  be a [topological space](#), and let  $\{U_i \subset X\}_{i \in I}$  be a [open cover](#).

Then a [refinement](#) of this open cover is a set of open subsets  $\{V_j \subset X\}_{j \in J}$  which is still an [open cover](#) in itself and such that for each  $j \in J$  there exists an  $i \in I$  with  $V_j \subset U_i$ .

### Definition 7.3. ([paracompact topological space](#))

A [topological space](#)  $(X, \tau)$  is called *paracompact* if every [open cover](#) of  $X$  has a [refinement](#) (def. 7.2) by a [locally finite open cover](#) (def. 7.1).

The following says that if there exists a [locally finite refinement](#) of a cover, then in fact there exists one with the same index set as the original cover. This will be useful in some of the proofs that follow.

### Lemma 7.4. (*every locally finite refinement induces one with the original index set*)

Let  $(X, \tau)$  be a [topological space](#), let  $\{U_i \subset X\}_{i \in I}$  be an [open cover](#), and let  $(\phi: J \rightarrow I, \{V_j \subset X\}_{j \in J})$ , be a [refinement](#) to a [locally finite cover](#).

Then  $\{W_i \subset X\}_{i \in I}$  with

$$W_i := \left\{ \bigcup_{j \in \phi^{-1}(\{i\})} V_j \right\}$$

is still a [refinement](#) of  $\{U_i \subset X\}_{i \in I}$  to a [locally finite cover](#).

**Proof.** It is clear by construction that  $W_i \subset U_i$ , hence that we have a [refinement](#). We need to show local finiteness.

Hence consider  $x \in X$ . By the assumption that  $\{V_j \subset X\}_{j \in J}$  is locally finite, it follows that there exists an [open neighbourhood](#)  $U_x \supset \{x\}$  and a [finite subset](#)  $K \subset J$  such that

$$\forall_{j \in J \setminus K} (U_x \cap V_j = \emptyset).$$

Hence by construction

$$\forall_{i \in I \setminus \phi(K)} (U_x \cap W_i = \emptyset).$$

Since the [image](#)  $\phi(K) \subset I$  is still a [finite set](#), this shows that  $\{W_i \subset X\}_{i \in I}$  is locally

finite. ■

## Partitions of unity

### Definition 7.5. (partition of unity)

Let  $(X, \tau)$  be a topological space, and let  $\{U_i \subset X\}_{i \in I}$  be an open cover. Then a partition of unity subordinate to the cover is

- a set  $\{f_i\}_{i \in I}$  of continuous functions

$$f_i : U_i \rightarrow [0, 1]$$

(where  $U_i \subset X$  and  $[0, 1] \subset \mathbb{R}$  are equipped with their subspace topology, the real numbers  $\mathbb{R}$  is regarded as the 1-dimensional Euclidean space equipped with its metric topology);

such that with

$$\text{Supp}(f_i) := \text{Cl}(f_i^{-1}((0, 1]))$$

denoting the support of  $f_i$  (the topological closure of the subset of points on which it does not vanish) then

1.  $\forall_{i \in I} (\text{Supp}(f_i) \subset U_i)$ ;
2.  $\{\text{Supp}(f_i) \subset X\}_{i \in I}$  is a locally finite cover (def. 7.1);
3.  $\forall_{x \in X} (\sum_{i \in I} f_i(x) = 1)$ .

**Remark 7.6.** Due to the second clause in def. 7.5, the sum in the third clause involves only a finite number of elements not equal to zero, and therefore is well defined.

**Proposition 7.7.** Let  $(X, \tau)$  be a topological space. Then the following are equivalent:

1.  $(X, \tau)$  is a paracompact Hausdorff space.
2. Every open cover of  $(X, \tau)$  admits a subordinate partition of unity (def. 7.5).

**Proof.** One direction is immediate: Assume that every open cover  $\{U_i \subset X\}_{i \in I}$  admits a subordinate partition of unity  $\{f_i\}_{i \in I}$ . Then by definition (def. 7.5)  $\{\text{Int}(\text{Supp}(f_i)) \subset X\}_{i \in I}$  is a locally finite open cover refining the original one.

We need to show the converse: If  $(X, \tau)$  is a paracompact topological space, then for every open cover  $\{U_i \subset X\}_{i \in I}$  there is a subordinate partition of unity (def. 7.5).

To that end, first apply lemma 4.17 to the given locally finite open cover  $\{U_i \subset X\}$ ,

to obtain a smaller locally finite open cover  $\{V_i \subset X\}_{i \in I}$ , and then apply the lemma once more to that result to get a yet small open cover  $\{W_i \subset X\}_{i \in I}$ , so that now

$$\forall_{i \in I} (W_i \subset \text{Cl}(W_i) \subset V_i \subset \text{Cl}(V_i) \subset U_i) .$$

It follows that for each  $i \in I$  we have two disjoint [closed subsets](#), namely the [topological closure](#)  $\text{Cl}(W_i)$  and the [complement](#)  $X \setminus V_i$

$$\text{Cl}(W_i) \cap X \setminus V_i = \emptyset .$$

Now since [paracompact Hausdorff spaces are normal](#), [Urysohn's lemma](#) says that there exist [continuous functions](#)

$$h_i : X \rightarrow [0, 1]$$

with the property that

$$h_i(\text{Cl}(W_i)) = \{1\}, \quad h_i(X \setminus V_i) = \{0\} .$$

This means in particular that  $h_i^{-1}((0, 1]) \subset V_i$  and hence that

$$\text{Supp}(h_i) = \text{Cl}(h_i^{-1}((0, 1])) \subset \text{Cl}(V_i) \subset U_i .$$

By construction, the set of function  $\{h_i\}_{i \in I}$  already satisfies two of the three conditions on a partition of unity subordinate to  $\{U_i \subset X\}_{i \in I}$  from def. [7.5](#). It just remains to normalize these functions so that they indeed sum to unity. To that end, consider the continuous function

$$h : X \rightarrow [0, 1]$$

defined on  $x \in X$

$$h(x) := \sum_{i \in I} h_i(x) .$$

Notice that the [sum](#) on the right has only a [finite number](#) of non-zero summands, due to the local finiteness of the cover, so that this is well-defined.

Then set

$$f_i := g_i / g .$$

This is now manifestly such that  $\sum_{i \in I} f_i = 1$ , and so

$$\{f_i\}_{i \in I}$$

is a partition of unity as required. ■

## Manifolds

- [topological manifold](#)
- [smooth manifold](#)
- [tangent space](#)
- [tangent bundle](#)
- [frame bundle](#)
- [G-structure](#)

## 8. Universal constructions

One point of the general definition of [topological space](#) above is that it admits constructions which intuitively should exist on “continuous spaces”, but which do not in general exist on [metric spaces](#).

Examples include the construction of [quotient topological spaces](#) of metric spaces, which are not [Hausdorff](#) anymore (e.g. example 4.3), and hence in particular are not metric spaces anymore (by example 4.8).

Now from a more abstract point of view, a [quotient topological space](#) is a special case of a “[colimit](#)” of topological spaces. This we explain now.

Generally, for every [diagram](#) in the [category Top](#) of topological spaces (remark \ref{TopCat}), hence for every collection of topological spaces with a system of [continuous functions](#) between them, then there exists a further topological space, called the [colimiting space](#) of the diagram, which may be thought of as the result of “gluing” all the spaces in the diagram together, while using the maps between them in order to identify those parts “along which” the spaces are to be glued.

One may formalize this intuition by saying that the colimiting space has the property that it receives compatible continuous functions from all the spaces in the diagram, and that it is characterized by the fact that it is [universal with this property](#): every compatible system of maps to another space uniquely factors through the colimiting one.

Therefore forming colimits of topological spaces is a convenient means to construct new spaces which have prescribed properties for continuous functions out of them. We implicitly used a simple special case of this phenomenon in the proof of the [Hausdorff reflection](#) in prop. 4.22, when we concluded the existence of certain unique factorizing maps out of the Hausdorff quotient of a topological space.

[Dual](#) to the concept of [colimits](#) of topological space is that of “[limits](#)” of [diagrams](#) of topological spaces (not to be confused with [limits of sequences](#) in a topological space). Here one considers topological spaces with the [universal property](#) of having compatible continuous functions into a given [diagram](#) of spaces.

Most constructions of new topological spaces that one builds from given spaces are obtained by forming limits and/or colimits of diagrams of the original spaces.

# Limits and colimits

## Definition 8.1. (**diagram** in a **category**)

A **diagram**  $X_\bullet$  in a **category**, such as the **category** **Top** of **topological spaces** or the category **Set** of **sets** from remark 3.3, is

1. a **set**  $\{X_i\}_{i \in I}$  of **objects** in the category;
2. for every **pair**  $(i, j) \in I \times I$  of labels of objects a **set**  $\{X_i \xrightarrow{f_\alpha} X_j\}_{\alpha \in I_{i,j}}$  of **morphisms** between these objects;
3. for each **triple**  $i, j, k \in I$  **function**

$$\text{comp}_{i,j,k} : I_{i,j} \times I_{j,k} \longrightarrow I_{i,k}$$

such that

1. for every  $i \in I$  the **identity morphisms**  $\text{id}_{X_i} : X_i \rightarrow X_i$  is part of the diagram;
2.  $\text{comp}$  is **associative** and **unital** in the evident sense,
3. for every composable pair of morphisms

$$X_i \xrightarrow{f_\alpha} X_j \xrightarrow{f_\beta} X_k$$

then the **composite** of these two morphisms equals the morphisms of the diagram that is labeled by the value of  $\text{comp}_{i,j,k}$  on their labels:

$$f_\beta \circ f_\alpha = f_{\text{comp}_{i,j,k}(\alpha, \beta)} .$$

The last condition we depict as follows:

$$\begin{array}{ccc} & X_j & \\ f_\alpha \nearrow & & \searrow f_\beta \\ X_i & \xrightarrow{\text{comp}_{i,j,k}(\alpha, \beta)} & X_k \end{array} .$$

## Definition 8.2. (**cone** over a **diagram**)

Consider a **diagram**

$$X_\bullet = \left( \left\{ X_i \xrightarrow{f_\alpha} X_j \right\}_{i,j \in I, \alpha \in I_{i,j}}, \text{comp} \right)$$

in some **category** (def. 8.1). Then

1. a **cone** over this diagram is
  1. an **object**  $\tilde{X}$  in the category;

2. for each  $i \in I$  a morphism  $\tilde{X} \xrightarrow{p_i} X_i$  in the category

such that

- for all  $(i, j) \in I \times I$  and all  $\alpha \in I_{i,j}$  then the condition

$$f_\alpha \circ p_i = p_j$$

holds, which we depict as follows:

$$\begin{array}{ccc} & \tilde{X} & \\ p_i \swarrow & & \searrow p_j \\ X_i & \xrightarrow{f_\alpha} & X_j \end{array}$$

2. a co-cone over this diagram is

1. an object  $\tilde{X}$  in the category;
2. for each  $i \in I$  a morphism  $q_i: X_i \rightarrow \tilde{X}$  in the category

such that

- for all  $(i, j) \in I \times I$  and all  $\alpha \in I_{i,j}$  then the condition

$$q_j \circ f_\alpha = q_i$$

holds, which we depict as follows:

$$\begin{array}{ccc} X_i & \xrightarrow{f_\alpha} & X_j \\ q_i \searrow & & \swarrow q_j \\ & \tilde{X} & \end{array} .$$

### Definition 8.3. (limiting cone over a diagram)

Consider a diagram

$$X_\bullet = \left( \left\{ X_i \xrightarrow{f_\alpha} X_j \right\}_{i,j \in I, \alpha \in I_{i,j}}, \text{comp} \right)$$

in some category (def. 8.1). Then

1. its limiting cone (or just limit for short) is, if it exists, the cone

$$\left\{ \begin{array}{ccc} & \varprojlim_i X_i & \\ p_i \swarrow & & \searrow p_j \\ X_i & \xrightarrow{f_\alpha} & X_j \end{array} \right\}$$

over this diagram (def. 8.2) which is *universal* or *initial* among all possible cones, in that it has the property that for

$$\left\{ \begin{array}{ccc} & \tilde{X} & \\ p'_i \swarrow & & \searrow p'_j \\ X_i & \xrightarrow{f_\alpha} & X_j \end{array} \right\}$$

any other [cone](#), then there is a unique morphism

$$\phi : \tilde{X} \longrightarrow \varinjlim_i X_i$$

that factors the given cone through the limiting cone, in that for all  $i \in I$  then

$$p'_i = p_i \circ \phi$$

which we depict as follows:

$$\begin{array}{ccc} \tilde{X} & & \\ \phi \downarrow & & \searrow p_i \\ \varinjlim_i X_i & \xrightarrow{p_i} & X_i \end{array}$$

2. its [colimiting cocone](#) (or just [colimit](#) for short) is, if it exists, [the cocone](#)

$$\left\{ \begin{array}{ccc} X_i & \xrightarrow{f_\alpha} & X_j \\ q_i \searrow & & \swarrow q_j \\ & \varinjlim_i X_i & \end{array} \right\}$$

under this diagram (def. 8.2) which is *universal* or *terminal* among all possible co-cones, in that it has the property that for

$$\left\{ \begin{array}{ccc} X_i & \xrightarrow{f_\alpha} & X_j \\ q'_i \searrow & & \swarrow q'_j \\ & \tilde{X} & \end{array} \right\}$$

any other [cocone](#), then there is a unique morphism

$$\phi : \varinjlim_i X_i \longrightarrow \tilde{X}$$

that factors the given co-cone through the co-limiting cocone, in that for all  $i \in I$  then

$$q'_i = \phi \circ q_i$$

which we depict as follows:



$$\begin{array}{ccc}
 X_i & \xrightarrow{q_i} & \varinjlim_i X_i \\
 \phi \downarrow & \swarrow q'_i & \\
 \tilde{X} & & 
 \end{array}$$

### Proposition 8.4. (limits of sets)

Let

$$X_{\bullet} = \left( \left\{ X_i \xrightarrow{f_{\alpha}} X_j \right\}_{i,j \in I, \alpha \in I_{i,j}} \right)$$

be a [diagram](#) of [sets](#) (def. 8.1). Then

1. its [limit cone](#) (def. 8.3) exists and is given by the following [subset](#) of the [Cartesian product](#)  $\prod_{i \in I} X_i$  of all the [sets](#)  $X_i$  appearing in the diagram

$$\varprojlim_i X_i \hookrightarrow \prod_{i \in I} X_i$$

on those [tuples](#) of elements which match the [graphs](#) of the functions appearing in the diagram:

$$\varprojlim_i X_i \simeq \left\{ (x_i)_{i \in I} \in \prod_{i \in I} X_i \mid \forall_{i,j \in I} \forall_{\alpha \in I_{i,j}} (f_{\alpha}(x_i) = x_j) \right\}$$

2. its [colimiting co-cone](#) (def. 8.3) exists and is given by the [quotient set](#) of the [disjoint union](#)  $\bigsqcup_{i \in I} X_i$  of all the [sets](#)  $X_i$  appearing in the diagram

$$\bigsqcup_{i \in I} X_i \longrightarrow \varinjlim_{i \in I} X_i$$

with respect to the [equivalence relation](#) which is generated from the [graphs](#) of the functions in the diagram:

$$\varinjlim_i X_i \simeq \left( \bigsqcup_{i \in I} X_i \right) / \left( (x \sim x') \Leftrightarrow \left( \exists_{i,j \in I} \exists_{\alpha \in I_{i,j}} (f_{\alpha}(x) = x') \right) \right)$$

Now we turn to limits of diagrams of topological spaces.

**Definition 8.5.** Let  $\{X_i = (S_i, \tau_i) \in \mathbf{Top}\}_{i \in I}$  be a [class](#) of [topological spaces](#), and let  $S \in \mathbf{Set}$  be a bare [set](#). Then

- For  $\{S \xrightarrow{f_i} S_i\}_{i \in I}$  a set of [functions](#) out of  $S$ , the [initial topology](#)  $\tau_{\text{initial}}(\{f_i\}_{i \in I})$  is the topology on  $S$  with the [minimum](#) collection of [open subsets](#) such that all  $f_i: (S, \tau_{\text{initial}}(\{f_i\}_{i \in I})) \rightarrow X_i$  are [continuous](#).

- For  $\{S_i \xrightarrow{f_i} S\}_{i \in I}$  a set of [functions](#) into  $S$ , the [final topology](#)  $\tau_{\text{final}}(\{f_i\}_{i \in I})$  is the topology on  $S$  with the [maximum](#) collection of [open subsets](#) such that all  $f_i: S_i \rightarrow (S, \tau_{\text{final}}(\{f_i\}_{i \in I}))$  are [continuous](#).

**Example 8.6.** For  $X$  a single topological space, and  $\iota_S: S \hookrightarrow U(X)$  a subset of its underlying set, then the initial topology  $\tau_{\text{initial}}(\iota_S)$ , def. 8.5, is the [subspace topology](#), making

$$\iota_S : (S, \tau_{\text{initial}}(\iota_S)) \hookrightarrow X$$

a [topological subspace](#) inclusion.

**Example 8.7.** Conversely, for  $p_S: U(X) \rightarrow S$  an [epimorphism](#), then the final topology  $\tau_{\text{final}}(p_S)$  on  $S$  is the [quotient topology](#).

**Proposition 8.8.** Let  $I$  be a [small category](#) and let  $X_\bullet: I \rightarrow \mathbf{Top}$  be an  $I$ -[diagram](#) in [Top](#) (a [functor](#) from  $I$  to  $\mathbf{Top}$ ), with components denoted  $X_i = (S_i, \tau_i)$ , where  $S_i \in \mathbf{Set}$  and  $\tau_i$  a topology on  $S_i$ . Then:

1. The [limit](#) of  $X_\bullet$  exists and is given by [the](#) topological space whose underlying set is [the](#) limit in [Set](#) of the underlying sets in the diagram, and whose topology is the [initial topology](#), def. 8.5, for the functions  $p_i$  which are the limiting [cone](#) components:

$$\begin{array}{ccc} & \varprojlim_{i \in I} S_i & \\ p_i \swarrow & & \searrow p_j \\ S_i & \longrightarrow & S_j \end{array}$$

Hence

$$\varprojlim_{i \in I} X_i \simeq \left( \varprojlim_{i \in I} S_i, \tau_{\text{initial}}(\{p_i\}_{i \in I}) \right)$$

2. The [colimit](#) of  $X_\bullet$  exists and is the topological space whose underlying set is the colimit in [Set](#) of the underlying diagram of sets, and whose topology is the [final topology](#), def. 8.5 for the component maps  $\iota_i$  of the colimiting [cocone](#)

$$\begin{array}{ccc} S_i & \longrightarrow & S_j \\ \iota_i \searrow & & \swarrow \iota_j \\ & \varinjlim_{i \in I} S_i & \end{array}$$

Hence

$$\varinjlim_{i \in I} X_i \simeq \left( \varinjlim_{i \in I} S_i, \tau_{\text{final}}(\{\iota_i\}_{i \in I}) \right)$$

(e.g. [Bourbaki 71](#), section I.4)

**Proof.** The required [universal property](#) of  $\left(\lim_{\leftarrow i \in I} S_i, \tau_{\text{initial}}(\{p_i\}_{i \in I})\right)$  is immediate: for

$$\begin{array}{ccc} & (S, \tau) & \\ f_i \swarrow & & \searrow f_j \\ X_i & \longrightarrow & X_j \end{array}$$

any [cone](#) over the diagram, then by construction there is a unique function of underlying sets  $S \rightarrow \lim_{\leftarrow i \in I} S_i$  making the required diagrams commute, and so all that is required is that this unique function is always [continuous](#). But this is precisely what the initial topology ensures.

The case of the colimit is [formally dual](#). ■

## Examples

**Example 8.9.** The limit over the empty diagram in  $\mathbf{Top}$  is the [point space](#)  $*$  (example [2.10](#)).

**Example 8.10.** For  $\{X_i\}_{i \in I}$  a set of topological spaces, their [coproduct](#)  $\bigsqcup_{i \in I} X_i \in \mathbf{Top}$  is their [disjoint union](#) (example [2.15](#)).

**Example 8.11.** For  $\{X_i\}_{i \in I}$  a set of topological spaces, their [product](#)  $\prod_{i \in I} X_i \in \mathbf{Top}$  is the [Cartesian product](#) of the underlying sets equipped with the [product topology](#), also called the [Tychonoff product](#).

In the case that  $S$  is a [finite set](#), such as for binary product spaces  $X \times Y$ , then a [sub-basis](#) for the product topology is given by the [Cartesian products](#) of the open subsets of (a basis for) each factor space.

**Example 8.12.** The [equalizer](#) of two [continuous functions](#)  $f, g: X \rightrightarrows Y$  in  $\mathbf{Top}$  is the equalizer of the underlying functions of sets

$$\text{eq}(f, g) \hookrightarrow S_X \xrightleftharpoons[g]{f} S_Y$$

(hence the targets subset of  $S_X$  on which both functions coincide) and equipped with the [subspace topology](#), example [8.6](#).

**Example 8.13.** The [coequalizer](#) of two [continuous functions](#)  $f, g: X \rightrightarrows Y$  in  $\mathbf{Top}$  is the coequalizer of the underlying functions of sets

$$S_X \xrightleftharpoons[g]{f} S_Y \twoheadrightarrow \text{coeq}(f, g)$$

(hence the [quotient set](#) by the [equivalence relation](#) generated by  $f(x) \sim g(x)$  for

all  $x \in X$ ) and equipped with the [quotient topology](#), example 8.7.

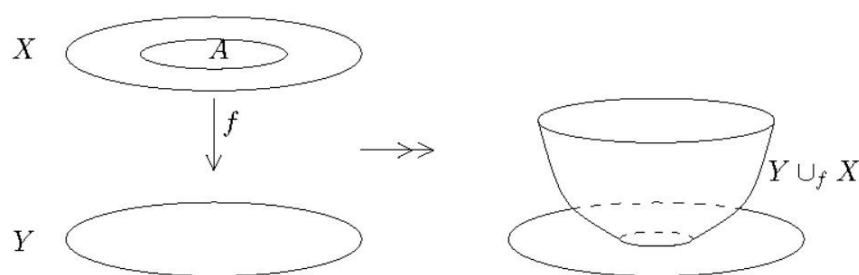
**Example 8.14.** For

$$\begin{array}{ccc} A & \xrightarrow{g} & Y \\ f \downarrow & & \\ X & & \end{array}$$

two [continuous functions](#) out of the same [domain](#), then the [colimit](#) under this diagram is also called the [pushout](#), denoted

$$\begin{array}{ccc} A & \xrightarrow{g} & Y \\ f \downarrow & & \downarrow g_* f \\ X & \longrightarrow & X \sqcup_A Y . \end{array}$$

(Here  $g_* f$  is also called the pushout of  $f$ , or the [cobase change](#) of  $f$  along  $g$ .) If  $g$  is an inclusion, one also write  $X \cup_f Y$  and calls this the [attaching space](#).



By example 8.13 the pushout/attaching space is the [quotient topological space](#)

$$X \sqcup_A Y \simeq (X \sqcup Y) / \sim$$

of the [disjoint union](#) of  $X$  and  $Y$  subject to the

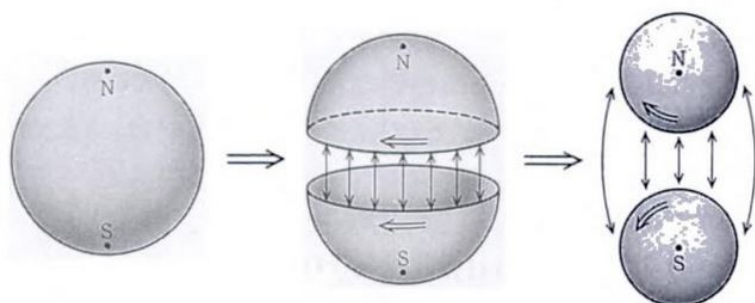
[equivalence relation](#) which identifies a point in  $X$  with a point in  $Y$  if they have the same pre-image in  $A$ .

(graphics from [Aguilar-Gitler-Prieto 02](#))

**Example 8.15.** As an important special case of example 8.14, let

$$i_n : S^{n-1} \rightarrow D^n$$

be the canonical inclusion of the standard [\(n-1\)-sphere](#) as the [boundary](#) of the standard [n-disk](#) from example 2.20.



Then the colimit in [Top](#) under the diagram, i.e. the [pushout](#) of  $i_n$  along itself,

$$\{D^n \xleftarrow{i_n} S^{n-1} \xrightarrow{i_n} D^n\},$$

is the [n-sphere](#)  $S^n$ :

$$\begin{array}{ccc}
 S^{n-1} & \xrightarrow{i_n} & D^n \\
 i_n \downarrow & (\text{po}) & \downarrow \\
 D^n & \longrightarrow & S^n
 \end{array}$$

(graphics from Ueno-Shiga-Morita 95)

### Definition 8.16. (single cell attachment)

For  $X$  any [topological space](#) and for  $n \in \mathbb{N}$ , then an  $n$ -cell *attachment* to  $X$  is the result of gluing an [n-disk](#) to  $X$ , along a prescribed image of its bounding [\(n-1\)-sphere](#) (def. 2.20):

Let

$$\phi : S^{n-1} \rightarrow X$$

be a [continuous function](#), then the “attaching space”

$$X \cup_{\phi} D^n \in \text{Top}$$

is the topological space which is the [pushout](#) of the boundary inclusion of the  $n$ -sphere along  $\phi$ , hence the universal space that makes the following [diagram commute](#):

$$\begin{array}{ccc}
 S^{n-1} & \xrightarrow{\phi} & X \\
 i_n \downarrow & (\text{po}) & \downarrow \\
 D^n & \longrightarrow & X \cup_{\phi} D^n
 \end{array}$$

**Example 8.17.** A single cell attachment of a 0-cell, according to example 8.16 is the same as forming the [disjoint union space](#)  $X \sqcup *$  with the [point](#) space  $*$ :

$$\begin{array}{ccc}
 (S^{-1} = \emptyset) & \xrightarrow{\exists!} & X \\
 \downarrow & (\text{po}) & \downarrow \\
 (D^0 = *) & \longrightarrow & X \sqcup *
 \end{array}$$

In particular if we start with the [empty topological space](#)  $X = \emptyset$  itself, then by attaching 0-cells we obtain a [discrete topological space](#). To this then we may attach higher dimensional cells.

### Definition 8.18. (attaching many cells at once)

If we have a [set](#) of attaching maps  $\{S^{n_i-1} \xrightarrow{\phi_i} X\}_{i \in I}$  (as in def. 8.16), all to the same space  $X$ , we may think of these as one single continuous function out of the [disjoint union space](#) of their [domain](#) spheres

$$(\phi_i)_{i \in I} : \bigsqcup_{i \in I} S^{n_i-1} \rightarrow X.$$

Then the result of attaching *all* the corresponding  $n$ -cells to  $X$  is the pushout of

the corresponding [disjoint union](#) of boundary inclusions:

$$\begin{array}{ccc} \bigsqcup_{i \in I} S^{n_i-1} & \xrightarrow{(\phi_i)_{i \in I}} & X \\ \downarrow & \text{(po)} & \downarrow \\ \bigsqcup_{i \in I} D^{n_i} & \longrightarrow & X \cup_{(\phi_i)_{i \in I}} \left( \bigsqcup_{i \in I} D^{n_i} \right) \end{array} .$$

Apart from attaching a set of cells all at once to a fixed base space, we may “attach cells to cells” in that after forming a given cell attachment, then we further attach cells to the resulting attaching space, and ever so on:

**Definition 8.19. ([relative cell complexes](#) and [CW-complexes](#))**

Let  $X$  be a topological space, then A *topological [relative cell complex](#)* of countable height based on  $X$  is a [continuous function](#)

$$f: X \rightarrow Y$$

and a [sequential diagram](#) of [topological space](#) of the form

$$X = X_0 \hookrightarrow X_1 \hookrightarrow X_2 \hookrightarrow X_3 \hookrightarrow \dots$$

such that

1. each  $X_k \hookrightarrow X_{k+1}$  is exhibited as a cell attachment according to def. [8.18](#), hence presented by a [pushout](#) diagram of the form

$$\begin{array}{ccc} \bigsqcup_{i \in I} S^{n_i-1} & \xrightarrow{(\phi_i)_{i \in I}} & X_k \\ \downarrow & \text{(po)} & \downarrow \\ \bigsqcup_{i \in I} D^{n_i} & \longrightarrow & X_{k+1} \end{array} .$$

2.  $Y = \bigcup_{k \in \mathbb{N}} X_k$  is the [union](#) of all these cell attachments, and  $f: X \rightarrow Y$  is the canonical inclusion; or stated more abstractly: the map  $f: X \rightarrow Y$  is the inclusion of the first component of the diagram into its [colimiting cocone](#)  $\varinjlim_k X_k$ :

$$\begin{array}{ccccccc} X = X_0 & \longrightarrow & X_1 & \longrightarrow & X_2 & \longrightarrow & \dots \\ & f \searrow & \downarrow & \swarrow & & & \dots \\ & & Y = \varinjlim_k X_k & & & & \end{array}$$

If here  $X = \emptyset$  is the [empty space](#) then the result is a map  $\emptyset \hookrightarrow Y$ , which is equivalently just a space  $Y$  built from “attaching cells to nothing”. This is then called just a *topological [cell complex](#)* of countable height.

Finally, a topological (relative) cell complex of countable height is called a **CW-complex** is the  $(k+1)$ -st cell attachment  $X_k \rightarrow X_{k+1}$  is entirely by  $(k+1)$ -cells, hence exhibited specifically by a pushout of the following form:

$$\begin{array}{ccc}
 \bigsqcup_{i \in I} S^k & \xrightarrow{(\phi_i)_{i \in I}} & X_k \\
 \downarrow & (\text{po}) & \downarrow \\
 \bigsqcup_{i \in I} D^{k+1} & \longrightarrow & X_{k+1}
 \end{array}$$

A [finite CW-complex](#) is one which admits a presentation in which there are only finitely many attaching maps, and similarly a *countable CW-complex* is one which admits a presentation with countably many attaching maps.

Given a CW-complex, then  $X_n$  is also called its  $n$ -[skeleton](#).

(...)

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This concludes *Section 1 [Point-set topology](#)*.

For the next section see *[Section 2 -- Basic homotopy theory](#)*.

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## 9. References

A canonical compendium is

- [Nicolas Bourbaki](#), chapter 1 *Topological Structures of Elements of Mathematics III: General topology*, Springer 1971, 1990

Introductory textbooks include

- [James Munkres](#), *Topology*, Prentice Hall (1975, 2000)
- [Steven Vickers](#), *Topology via Logic*, Cambridge University Press (1989)

See also

- [Alan Hatcher](#), *[Algebraic Topology](#)*

and see also the references at [algebraic topology](#).

Lecture notes include

- [Friedhelm Waldhausen](#), *Topologie* ([pdf](#))

Discussion of [sober topological spaces](#) is in

- [Peter Johnstone](#), section II 1. of *Stone Spaces*, Cambridge Studies in Advanced Mathematics **3**, Cambridge University Press 1982. xxi+370 pp. [MR85f:54002](#), reprinted 1986.

See also

- [Topospaces](#), a Wiki with basic material on topology.

*Revised on April 29, 2017 04:51:11 by [Urs Schreiber](#)*