

# Lagrangians with $(2,0)$ Supersymmetry

Neil Lambert

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## Introduction

Understanding M5-branes is a major challenge. It is a defining issue in M-Theory and it is important for QFT more generally.

We don't expect to have a traditional Lagrangian description:

- Modular anomalies = violation of diffeomorphism
- 'Tachikawa' test (twisted compactification of  $SU(2n)$  theory leads to  $SO(2n + 1)$  )
- No marginal deformations or even discrete limiting theories
- Reduction to 5D gives  $g^2 \propto R$  not  $g^2 \propto 1/R$
- No family of interacting renormalizable Lagrangians with Energy bounded from below.
- Difficulties with self-duality of the three-form and two-form gauge theory

But we are here because we like a challenge (or are stubborn)

On the other hand without some kind of Lagrangian or Hamiltonian construction it is difficult to see how to find a workable formulation of the  $(2, 0)$  theory or understand its robust relations to lower dimensional gauge theories.

Several proposals involve Lagrangians/Hamiltonians *e.g.*:

- DLCQ based on Instanton Quantum Mechanics
- Deconstruction based on 4D  $\mathcal{N} = 2$  SCFT Lagrangians
- 5D super-Yang-Mills as  $(2, 0)$  on  $S^1$  of any radius.
- Various novel Lagrangians in 5D and/or 6D *e.g.*  
[\[Saemann's talk\]](#)

Maybe we have to learn how to piece these together to get a complete picture.

In this talk we will construct Lagrangians in six-dimensions with  $(2, 0)$  supersymmetry.

A recent general approach due to [Sen](#) offers a new window to self-duality and diffeomorphisms which we will look through.

We will largely put aside all the no-go statements above and see how far we get. If only to test the boundaries. As with M2-branes one may hope that two M5-branes are more amenable than three or more ('Tachikawa Test').

The hope is that we will find interesting things and novel mathematics that are relevant to M-theory.

## An Abelian (2,0) Action

In flat Minkowski space the action is

$$S = \int \left( \frac{1}{2} dB \wedge \star_{\eta} dB - 2H \wedge dB - \frac{1}{2} \partial_{\mu} X^I \partial^{\mu} X^I + \frac{i}{2} \bar{\Psi} \Gamma^{\mu} \partial_{\mu} \Psi \right)$$

- $H = \star_{\eta} H$
- $H$  equation of motion sets  $dB = \star_{\eta} dB$
- $B$  equation of motion sets  $d(H + \frac{1}{2} dB + \frac{1}{2} \star_{\eta} dB) = 0$
- and hence  $dH = 0$

So two closed self-dual three-forms:  $H$  and

$$H_{(s)} = \frac{1}{2} (dB + \star_{\eta} dB) + H$$

Key idea [Sen]: ensure  $H_{(s)}$  decouples.

We want to keep  $B$  decoupled, even from the metric:

$$S = \int \left( \frac{1}{2} dB \wedge \star_{\eta} dB - 2H \wedge dB + H \wedge \tilde{\mathcal{M}}(H) - \frac{1}{2} dX^I \wedge \star_g dX^I + \frac{i}{2} \bar{\Psi} \Gamma_{\mu} dx^{\mu} \wedge \star_g \nabla \Psi - \frac{1}{5} R X^I X^I \right)$$

Now we find

$$d\left(H - \tilde{\mathcal{M}}(H)\right) = 0$$

and we define  $\tilde{\mathcal{M}}$  so that

$$H_{(g)} = H - \tilde{\mathcal{M}}(H) = \star_g H_{(g)}$$

$H_{(g)}$  plays the role of the physical  $\star_g$ -self-dual three-form. One can also introduce sources for  $H_{(g)}$ , keeping  $H_{(s)}$  decoupled - we will not consider this here but it can be included.

## Geometrical Properties

Thus the metric dependence of the forms is contained in  $\tilde{\mathcal{M}}$

To define  $\tilde{\mathcal{M}}$  we have the following requirements

- $\tilde{\mathcal{M}}(H) = -\star_{\eta} \tilde{\mathcal{M}}(H)$
- $H_1 \wedge \tilde{\mathcal{M}}(H_2) = H_2 \wedge \tilde{\mathcal{M}}(H_1)$
- $\tilde{\mathcal{M}}(Q) = 0$  for  $\star_{\eta} Q = -Q$
- if  $H = \star_{\eta} H$  then  $H - \tilde{\mathcal{M}}(H) = \star_g(H - \tilde{\mathcal{M}}(H))$

To construct  $\tilde{\mathcal{M}}$  we consider a basis of three-forms

$$\{\omega_+^A, \omega_{-A}\}$$
$$\star_{\eta} \omega_+^A = \omega_+^A, \quad \star_{\eta} \omega_{-A} = -\omega_{-A}$$

and hence we have, for some  $\tilde{\mathcal{M}}^{AB}$ ,

$$\tilde{\mathcal{M}}(\omega_{-A}) = 0, \quad \tilde{\mathcal{M}}(\omega_+^A) = \tilde{\mathcal{M}}^{AB} \omega_{-B}$$



Next we consider a basis of  $\star_g$ -self-dual three-forms:

$$\varphi^A = \mathcal{N}^A{}_B \omega_+^B + \mathcal{K}^{AB} \omega_{-B} \quad \varphi^A = \star_g \varphi^A$$

and define

$$\tilde{\mathcal{M}}^{AB} = -(\tilde{\mathcal{N}}^{-1})^A{}_C \tilde{\mathcal{K}}^{CB}$$

so that if  $H = H_A \omega_+^A$  then

$$\begin{aligned} H_{(g)} &= H - \tilde{\mathcal{M}}(H) \\ &= H_A \omega_+^A - H_A \tilde{\mathcal{M}}^{AB} \omega_{-B} \\ &= H_A \omega_+^A + H_A (\tilde{\mathcal{N}}^{-1})^A{}_C \tilde{\mathcal{K}}^{CB} \omega_{-B} \\ &= H_A (\tilde{\mathcal{N}}^{-1})^A{}_B \varphi^B \\ &= \star_g H_{(g)} \end{aligned}$$

Thus we have a map

$$\mathfrak{m}(H) = H - \tilde{\mathcal{M}}(H) \quad \mathfrak{m}(H) = H_{(g)}$$

from  $\star_\eta$ -self-dual forms to  $\star_g$ -self-dual forms

There is a novel invariance under diffeomorphisms.

Consider  $x^\mu \rightarrow x^\mu + \xi^\mu(x)$ . Some calculations show that

$$\delta_\xi \tilde{\mathcal{M}}(H) = \frac{1}{2}(1 - \star_\eta) \left[ \xi(H) - \xi(\tilde{\mathcal{M}}(H)) + \tilde{\mathcal{M}}(\xi(H)) - \tilde{\mathcal{M}}(\xi(\tilde{\mathcal{M}}(H))) \right]$$

where  $\xi(H) = \frac{1}{2} \nabla_\mu \xi^\lambda H_{\lambda\nu\rho} dx^\mu \wedge dx^\nu \wedge dx^\rho$ .

So  $\tilde{\mathcal{M}}$  transforms a bit like a connection: if it vanishes in one frame it need not vanish in others.

In terms of the map  $\mathfrak{m}$  we can write this as

$$\delta_\xi \tilde{\mathcal{M}}(H) = \frac{1}{2}(1 - \star_\eta) \mathfrak{m}^{-1}(\xi(\mathfrak{m}(H)))$$

How do  $B$  and  $H$  transform: They look like differential forms but they don't transform as differential forms: pseudo-forms.

Keep  $H_{(s)}$  invariant:

$$\delta_\xi H = -\frac{1}{2}d\delta_\xi B - \frac{1}{2}\star_\eta d\delta_\xi B$$

Invariance of the action, up to a total derivative, determines:

$$\delta_\xi B = i_\xi H_{(g)} = \frac{1}{2}\xi^\lambda H_{(g)\lambda\mu\nu} dx^\mu \wedge dx^\nu$$

and hence

$$\begin{aligned}\delta_\xi H_{(g)} &= \delta_\xi H - \tilde{\mathcal{M}}(\delta_\xi H) - \delta_\xi \tilde{\mathcal{M}}(H) \\ &= -\xi(H_{(g)}) - i_\xi H_{(g)} - \frac{1}{2}(1 + \star_\eta)i_\xi dH_{(g)} + \tilde{\mathcal{M}}(i_\xi dH_{(g)})\end{aligned}$$

We only recover the usual tensor transformation of  $H_{(g)}$  on on-shell.

We can now compute the energy momentum tensor defined as the response to a variation in the metric:

$$\begin{aligned} T_{\mu\nu} &= -\frac{2}{\sqrt{-g}} \frac{\delta \mathcal{L}}{\delta g^{\mu\nu}} \\ &= -4H \wedge \frac{\delta \tilde{\mathcal{M}}}{\delta g^{\mu\nu}}(H) \\ &= H_{\mu\lambda\rho}^{(g)} g^{\lambda\sigma} g^{\rho\tau} H_{\nu\sigma\tau}^{(g)} \end{aligned}$$

and the conserved energy (à la Noether):

$$E = \int d^5x \left( -\frac{1}{2} H_{0ij}^{(s)} H_{0ij}^{(s)} - \sqrt{-g} g^{0\mu} T_{\mu 0} \right)$$

Notably  $H_{(s)}$  has the wrong sign

We can also compute the Hamiltonian. To cut a longer story short (see [Sen]):

The fields are  $B_{ij}$ ,  $B_{0i}$  and  $H_{ijk}$ . Only  $B_{ij}$  has a conjugate momentum  $\Pi_{ij}$ . The others give constraints;

$$\partial_i \Pi_{ij} = 0 \quad \text{imposed by } B_{0i}$$

$$\frac{1}{2} \varepsilon_{ijklm} \Pi_{lm} = H_{ijk}^{(g)}(H) + \frac{3}{2} \partial_{[i} B_{jk]} \quad \text{imposed by } H_{ijk}$$

So we use the second equation to solve for  $H_{ijk}$  and work with

$$\Pi_{ij}^{\pm} = \frac{1}{2} \left( \Pi_{ij} \pm \frac{1}{4} \varepsilon_{ijklm} \partial_k B_{lm} \right)$$

that satisfy

$$\{\Pi_{ij}^{\pm}(x), \Pi_{kl}^{\pm}(y)\} = \pm \frac{1}{4} \varepsilon_{ijklm} \frac{\partial}{\partial x^m} \delta(x - y)$$

$$\{\Pi_{ij}^{+}(x), \Pi_{kl}^{-}(y)\} = 0$$

In particular we find

$$\begin{aligned}\Pi_{ij}^+ &= -\frac{1}{2}H_{0ij}^{(s)} \\ \Pi_{ij}^- &= \frac{1}{2 \cdot 3!}\varepsilon_{ijklm}H_{klm}^{(g)} = \frac{1}{2}\sqrt{-g}H_{(g)}^{0ij}\end{aligned}$$

The hamiltonian is (at least if  $g_{0i} = 0$ )

$$\begin{aligned}H &= H_+ + H_- \\ H_- &= \int d^5x -2\Pi_{ij}^+\Pi_{ij}^+ \\ H_- &= \int d^5x 4\Pi_{ij}^-\partial_i B_{0j} - \frac{2}{\sqrt{-g}}g_{00}g_{ik}g_{jl}\Pi_{ij}^-\Pi_{kl}^-\end{aligned}$$

which agrees with the energy  $E$  that we computed above.

In the end all the expressions for  $T_{\mu\nu}$  and  $\Pi_{ij}^\pm$  are what we would expect from an action of the form  $-dB \wedge \star_g dB$ .

## Sources

To include a source  $J$  we take

$$S_H = \int \left( \frac{1}{2} dB \wedge \star_\eta dB - 2H \wedge dB \right. \\ \left. + (H + J_+) \wedge \tilde{\mathcal{M}}(H + J_+) + 2H \wedge J_- - J_- \wedge J_+ \right)$$

and so

$$dH_{(g)}^J = dJ$$

but still

$$dH_{(s)} = d \left( \frac{1}{2} dB + \frac{1}{2} \star_\eta dB + H \right) = 0$$

We find similar expressions for diffeomorphisms, hamiltonian *etc.* as those above with

$$H_{(g)} \rightarrow H_{(g)}^J = H_{(g)} + J_+ - \tilde{\mathcal{M}}(J)$$

## Supersymmetry

Recall our action is

$$S = \int \left( \frac{1}{2} dB \wedge \star_{\eta} dB - 2H \wedge dB + H \wedge \tilde{\mathcal{M}}(H) \right. \\ \left. - \frac{1}{2} dX^I \wedge \star_g dX^I + \frac{i}{2} \bar{\Psi} \Gamma_{\mu} dx^{\mu} \wedge \star_g \nabla \Psi - \frac{1}{5} R X^I X^I \right)$$

This is invariant under  $(\nabla_{\mu} \epsilon = \frac{1}{6} \Gamma_{\mu} \Gamma^{\nu} \nabla_{\nu} \epsilon)$

$$\delta X^I = i \bar{\epsilon} \Gamma^I \Psi$$

$$\delta B_{\mu\nu} = -i \bar{\epsilon} \Gamma_{\mu\nu} \Psi$$

$$\delta H_{\mu\nu\lambda} = \frac{3i}{2} \bar{\epsilon} \Gamma_{[\mu\nu} \nabla_{\lambda]} \Psi + \frac{3i}{2 \cdot 3!} \epsilon_{\mu\nu\lambda\rho\sigma\tau} \eta^{\rho\alpha} \eta^{\sigma\beta} \eta^{\tau\gamma} \bar{\epsilon} \Gamma_{\alpha\beta} \nabla_{\gamma} \Psi \\ - \frac{i}{4} \nabla^{\rho} \bar{\epsilon} \Gamma_{\rho} \Gamma_{\mu\nu\lambda} \Psi - \frac{i}{4 \cdot 3!} \epsilon_{\mu\nu\lambda\rho\sigma\tau} \eta^{\rho\alpha} \eta^{\sigma\beta} \eta^{\tau\gamma} \nabla^{\omega} \bar{\epsilon} \Gamma_{\omega} \Gamma_{\alpha\beta\gamma} \Psi$$

$$\delta \Psi = \Gamma^{\mu} \Gamma^I \partial_{\mu} X^I \epsilon + \frac{1}{3!} \Gamma_{\mu\nu\lambda} (H - \tilde{\mathcal{M}}(H))^{\mu\nu\lambda} \epsilon$$

In this case  $H_{(s)} = \frac{1}{2} dB + \frac{1}{2} \star_{\eta} dB + H$  is a singlet



## Example: Reduction on $S^1$

The simplest case to consider is  $x^5 \sim x^5 + l$  and

$$g = \begin{pmatrix} \eta_5 & 0 \\ 0 & R^2 \end{pmatrix}$$

(**N.B.**  $R$  is dimensionless). A basis of three-forms is

$$\begin{aligned}\omega_+^A &= \Omega^A \wedge dx^5 + \star_5 \Omega^A \\ \omega_{-A} &= \Omega^A \wedge dx^5 - \star_5 \Omega^A\end{aligned}$$

and  $\star_g$  self-dual three-forms are given by:

$$\begin{aligned}\varphi^A &= \Omega^A \wedge dx^5 + \frac{1}{R} \star_5 \Omega^A \\ &= \frac{R+1}{2R} \omega_+^A + \frac{R-1}{2R} \omega_{-A}\end{aligned}$$

so  $\tilde{\mathcal{M}}^{AB} = -(R-1)/(R+1)\delta^{AB}$ .

Thus we find  $(a, b, = 1, 2, 3, 4)$

$$H_- = \int d^5x \left( \frac{2}{R} \Pi_{ab}^- \Pi_{ab}^- + 4R \Pi_{a5}^- \Pi_{a5}^- \right. \\ \left. + 4 \Pi_{ab}^- \partial_a B_{b5} + \Pi_{a5}^- (\partial_a B_{05} - \partial_5 B_{0a}) \right)$$

Let us set  $\partial_5 = 0$  and solve the  $B_{a5}$  constraint by

$$\Pi_{ab}^- = -\frac{1}{4l} \varepsilon_{abcd} \partial_c A_d$$

and hence  $\Pi_{a5}^-$  is the conjugate momentum to  $A_a$ :

$$\{A_a(x), \Pi_{b5}^-(y)\} = \delta_{ab} \delta_4(x - y)$$

Thus

$$\partial_0 A_a = \{A_a, H\} = 8Rl \Pi_{a5}^- + l \partial_a B_{05}$$

and hence we arrive at 5D Maxwell:

$$L_- = \partial_0 A_a \Pi_{a5}^- - H_- \\ = \frac{1}{8Rl} \int d^4x \left( (\partial_0 A_a - l \partial_a B_{05})^2 - (\partial_a A_b - \partial_b A_a)^2 \right)$$

## Example: M5 on a Riemann Surface

Subject to suitable boundary conditions, corresponding to intersecting branes, a single M5-brane wraps the Seiberg-Witten curve [Witten] of the associated gauge theory:

$$s = X^6 + iX^{10}, \quad z = x^4 + ix^5 \quad s = s(z; u)$$

where the  $u$  are moduli.

The induced metric on the M5-brane is

$$g = \begin{pmatrix} \eta_4 & 0 & 0 \\ 0 & 0 & (1 + \partial s \bar{\partial} \bar{s})/2 \\ 0 & (1 + \partial s \bar{\partial} \bar{s})/2 & 0 \end{pmatrix}$$

The low energy dynamics for the scalars of the M5-brane agrees with the SW effective action ( $m = 0, 1, 2, 3$ )

[Howe,NL,West]:

$$\begin{aligned} S_s &= \int d^4x \int d^2z \partial_m s \partial^m \bar{s} \\ &= \int d^4x \int d^2z \frac{\partial s}{\partial u} \frac{\partial \bar{s}}{\partial \bar{u}} \partial_m u \partial^m \bar{u} \\ &= \int d^4x \text{Im}(\tau \partial_m a \partial^m \bar{a}) \end{aligned}$$

Here  $\lambda = (\partial s / \partial u) dz$  is the holomorphic one-form and

$$\frac{da}{du} = \oint_A \lambda \quad \frac{da^D}{du} = \oint_B \lambda \quad \tau = \frac{da^D}{da}$$

However obtaining the correct vector equations knowing only the equations of motion was quite involved [NL,West].

Now we can reduce the form part of action on the Riemann surface  $\Sigma$  defined by  $s(z)$

We perform a standard KK reduction ansatz

$$\begin{aligned}H &= \mathcal{F} \wedge \vartheta + \bar{\mathcal{F}} \wedge \bar{\vartheta} \\ B &= C \wedge \vartheta + \bar{C} \wedge \bar{\vartheta}\end{aligned}$$

where  $\mathcal{F} = i \star_4 \mathcal{F}$  and  $\vartheta = (du/da)\lambda$ .

Since  $\Sigma$  is non-compact the 0-form and 2-form terms in the ansatz give divergent contributions and must be dropped.

For an  $H$  of this type  $\star_g H = H$  and hence  $\tilde{\mathcal{M}}(H) = 0$ .

We find the four-dimensional form part of the action is

$$\begin{aligned}
 S_H = \int & \left( (\tau - \bar{\tau}) (dC \wedge i \star d\bar{C} + 2\mathcal{F} \wedge d\bar{C} - 2\bar{\mathcal{F}} \wedge dC) \right. \\
 & + \frac{d\tau}{da} (-i \star d\bar{C} \wedge C \wedge da + 2\bar{\mathcal{F}} \wedge C \wedge da) \\
 & \left. + \frac{d\bar{\tau}}{d\bar{a}} (i \star dC \wedge \bar{C} \wedge d\bar{a} + 2\mathcal{F} \wedge \bar{C} \wedge d\bar{a}) \right)
 \end{aligned}$$

The equations of motion are

$$\begin{aligned}
 0 &= (\tau - \bar{\tau})dC + d\tau \wedge C - i \star \left( (\tau - \bar{\tau})dC + d\tau \wedge C \right) \\
 0 &= d \left( (\tau - \bar{\tau})i \star dC + 2(\tau - \bar{\tau})\mathcal{F}_\beta + i \star d\tau \wedge C \right) \\
 &+ d\bar{\tau} \wedge i \star dC + 2d\bar{\tau} \wedge \mathcal{F}
 \end{aligned}$$

We can substitute the first equation into the second to find

$$d((\tau - \bar{\tau})\mathcal{F}) + d\bar{\tau} \wedge (\mathcal{F} + \frac{1}{2}(i \star dC - dC)) = 0$$

This agrees with Seiberg-Witten if  $\mathcal{F} = -\frac{1}{2}d\bar{C} - \frac{i}{2} \star d\bar{C}$ .

## A Non-abelian (2,0) Action

Next we want to construct a non-abelian (2,0) action.

We can construct a free theory by including a gauge field along with a Lagrange multiplier term that imposes flatness:

$$S = \int \left[ \frac{1}{4} \langle DB \wedge \star DB \rangle - \langle H \wedge DB \rangle - \frac{1}{2} \langle D_\mu X^I D^\mu X^I \rangle + \frac{i}{2} \langle \bar{\Psi} \Gamma^\mu D_\mu \Psi \rangle + (\tilde{F} \wedge \tilde{W}) \right]$$

where  $D = d - \tilde{A}$  and  $\tilde{F} = d\tilde{A} - \tilde{A} \wedge \tilde{A}$  with

$$\delta \tilde{A}_\mu = 0$$
$$\delta \tilde{W}_{\mu\nu\lambda\rho}(\cdot) = 3i\bar{\epsilon} \Gamma_{[\mu\nu} [B_{\lambda\rho}], \Psi, \cdot] + i\bar{\epsilon} \Gamma_{\mu\nu\lambda\rho} \Gamma^I [X^I, \Psi, \cdot]$$

Here the matter fields take values in a vector space  $\mathcal{V}$  and the gauge field in a Lie-algebra  $\mathcal{G}$  with a representation  $\tilde{T}^r$  on  $\mathcal{V}$ .

- $\mathcal{V}$  has an inner-product  $\langle \cdot, \cdot \rangle$
- $\mathcal{G}$  has an inner-product  $(\cdot, \cdot)$

This leads to a three-algebra structure [Figueroa-O'Farrill, de Medeiros]:

$$[\cdot, \cdot, \cdot] : \mathcal{V} \otimes \mathcal{V} \otimes \mathcal{V} \rightarrow \mathcal{V}$$
$$[X, Y, Z] = \sum_r \langle X, \tilde{T}^r(Y) \rangle \tilde{T}_r(Z)$$

which implies the combatability conditions

$$(\tilde{T}, [U, V, \cdot]) = \langle \tilde{T}(U), V \rangle = -\langle U, \tilde{T}(V) \rangle$$

$$[U, V, [X, Y, Z]] = [[U, V, X], Y, Z] + [X, [U, V, Y], Z] + [X, Y, [U, V, Z]]$$



In order to construct interactions we consider the (2, 0) system of [NL, Papageogakis] and introduce a non-dynamical vector field  $Y^\mu$  with scaling dimension  $-1$

$$D_\mu Y^\nu = 0 \quad [Y^\mu, D_\mu(\cdot), \cdot'] = 0 \quad [Y^\mu, Y^\nu, \cdot] = 0$$

Here the three-algebra is totally anti-symmetric and so we take  $\mathcal{V} = \mathbb{R}^4$  leading to the gauge algebra  $\mathfrak{su}(2) \oplus \mathfrak{su}(2)$ .

$$0 = D^2 X^I - \frac{i}{2} [Y^\sigma, \bar{\Psi}, \Gamma_\sigma \Gamma^I \Psi] + [Y^\sigma, X^J, [Y_\sigma, X^J, X^I]]$$

$$0 = D_{[\lambda} H_{\mu\nu\rho]} + \frac{1}{4} \varepsilon_{\mu\nu\lambda\rho\sigma\tau} [Y^\sigma, X^I, D^\tau X^I] + \frac{i}{8} \varepsilon_{\mu\nu\lambda\rho\sigma\tau} [Y^\sigma, \bar{\Psi}, \Gamma^\tau \Psi]$$

$$0 = \Gamma^\rho D_\rho \Psi + \Gamma_\rho \Gamma^I [Y^\rho, X^I, \Psi]$$

$$0 = \tilde{F}_{\mu\nu}(\cdot) - [Y^\lambda, H_{\mu\nu\lambda}, \cdot]$$

Now the flatness condition on  $\tilde{F}$  is replaced by  $\tilde{F} \sim [Y, H, ]$

So we adjust the Lagrange multiplier term to

$$\mathcal{L}_{\tilde{W}} = \langle H \wedge \tilde{W}(Y) \rangle + (\tilde{F} \wedge \tilde{W})$$

where  $\tilde{W}(Y) = \frac{1}{3!} W_{\mu\nu\lambda\rho}(Y^\rho) dx^\mu \wedge dx^\nu \wedge dx^\lambda$  and make a guess

$$\begin{aligned} S_{guess} = \int & \left[ \frac{1}{4} \langle DB \wedge \star DB \rangle - \langle H \wedge (DB - \tilde{W}(Y)) \rangle + (\tilde{F} \wedge \tilde{W}) \right. \\ & - \frac{1}{2} \langle D_\mu X^I D^\mu X^I \rangle - \frac{1}{4} \langle [Y^\mu, X^I, X^J][Y_\mu, X^I, X^J] \rangle \\ & \left. + \frac{i}{2} \langle \bar{\Psi} \Gamma^\mu D_\mu \Psi \rangle + \frac{i}{2} \langle \bar{\Psi} \Gamma_\mu \Gamma^I [Y^\mu, X^I, \Psi] \rangle \right] \end{aligned}$$

The matter terms clearly reproduce their correct equations.

This has introduced a source for  $H$  of the form  $\tilde{W}(Y)$ .

Alas this isn't quite right:

- self-dual part of  $\tilde{W}(Y)$  is non-zero.
- $D^2 \sim \tilde{F} \neq 0$

After some more guess work we find [NL]

$$\begin{aligned} S = \int & \left[ \frac{1}{4} \langle \mathcal{D}B \wedge \star \mathcal{D}B \rangle + \frac{1}{6} \langle \mathcal{D}B \wedge DB \rangle + \frac{1}{4} \langle \tilde{W}(Y) \wedge \star \tilde{W}(Y) \rangle \right. \\ & - \langle H \wedge (\mathcal{D}B - \tilde{W}(Y)) \rangle - \frac{1}{2} \langle (\mathcal{D}B - \star \mathcal{D}B) \wedge \tilde{W}(Y) \rangle + (\tilde{F} \wedge \tilde{W}) \\ & - \frac{1}{2} \langle D_\mu X^I D^\mu X^I \rangle - \frac{1}{4} \langle [Y^\mu, X^I, X^J] [Y_\mu, X^I, X^J] \rangle \\ & \left. + \frac{i}{2} \langle \bar{\Psi} \Gamma^\mu D_\mu \Psi \rangle + \frac{i}{2} \langle \bar{\Psi} \Gamma_\mu \Gamma^I [Y^\mu, X^I, \Psi] \rangle \right] \end{aligned}$$

Here  $\mathcal{D}_\mu = \partial_\mu - \tilde{\mathcal{A}}_\mu(\cdot)$  with

$$\tilde{\mathcal{A}}_\mu(\cdot) = \tilde{A}_\mu(\cdot) - \frac{1}{2} [B_{\mu\nu}, Y^\nu, \cdot]$$

This reproduces all the equations of motion of the (2, 0) system.

In particular  $B$  and  $\tilde{W}$  can be removed from the equations for the remaining fields.

It is invariant under (2, 0) supersymmetry:

$$\delta X^I = i\bar{\epsilon}\Gamma^I\Psi$$

$$\delta B_{\mu\nu} = -i\bar{\epsilon}\Gamma_{\mu\nu}\Psi$$

$$\delta\Psi = \Gamma^\mu\Gamma^I D_\mu X^I \epsilon + \frac{1}{2 \cdot 3!} H_{\mu\nu\lambda}\Gamma^{\mu\nu\lambda}\epsilon - \frac{1}{2}\Gamma_\mu\Gamma^{IJ}[Y^\mu, X^I, X^J]\epsilon$$

$$\delta H_{\mu\nu\lambda} = \frac{3}{2}(1 + \star\eta)i\bar{\epsilon}\Gamma_{[\mu\nu}D_{\lambda]}\Psi - i\bar{\epsilon}\Gamma_\rho\Gamma_{\mu\nu\lambda}\Gamma^I[Y^\rho, X^I, \Psi]$$

$$\delta\tilde{A}_\mu(\cdot) = i\bar{\epsilon}\Gamma_{\mu\nu}[Y^\nu, \Psi, \cdot]$$

$$\delta\tilde{W}_{\mu\nu\lambda\rho}(\cdot) = 3i\bar{\epsilon}\Gamma_{[\mu\nu}[B_{\lambda\rho}], \Psi, \cdot] + i\bar{\epsilon}\Gamma_{\mu\nu\lambda\rho}\Gamma^I[X^I, \Psi, \cdot]$$

Note that this is a reducible representation of supersymmetry:

$$\mathcal{H}_{(s)} = \frac{1}{2}(\mathcal{D}B - \tilde{W}(Y)) + \frac{1}{2} \star (\mathcal{D}B - \tilde{W}(Y)) + H$$
$$\tilde{\mathcal{A}}_{(s)\mu}(\cdot) = \tilde{A}_{\mu}(\cdot) - [B_{\mu\nu}, Y^{\nu}, \cdot]$$

are singlets.

The interacting part is five-dimensional:  $[Y^{\mu} D_{\mu}, \cdot] = 0$ .

Coupling constant

$$g^2 = R_5 \left( \frac{\langle Y_{\mu}, Y^{\mu} \rangle}{R_5^2} \right)$$

Depending on the choice of  $Y$  one finds different five-dimensional theories.

- $Y$  spacelike: (4+1)-dimensional super-Yang-Mills
- $Y$  timelike: (5+0)-dimensional super-Yang-Mills
- $Y$  null: novel non-Lorentzian theory ( $G = \star G$ ):

$$S = \frac{1}{g^2} \text{tr} \int d^4x dx^0 \left( \frac{1}{2} F_{0i} F_{0i} + \frac{1}{2} F_{ij} G_{ij} - \frac{1}{2} (D_i X^I) (D_i X^I) \right. \\ \left. - \frac{i}{2} \bar{\Psi} \Gamma_- D_0 \Psi + \frac{i}{2} \bar{\Psi} \Gamma_i D_i \Psi + \frac{1}{2} \bar{\Psi} \Gamma_- \Gamma^I [X^I, \Psi] \right)$$

16 supersymmetries and 8 superconformal supersymmetries  
[\[NL, Owen\]](#)[\[NL, Mouland\]](#).

Path integral reduces to instanton QM[\[Mouland\]](#)

An  $\Omega$ -deformed version has an  $SU(3, 1)$  symmetry, 8 supersymmetries, 16 superconformal symmetries and an  $AdS_7$  dual [\[NL, Lipstein, Richmond\]](#) [\[NL, Lipstein, Mouland, Richmond\]](#)

# Conclusions

In this talk we adapted [Sen's](#) prescript for self-dual forms to the  $(2, 0)$  theory.

- Obtained a more geometrical formulation
- Obelian theory reproduces the dynamics of a single M5
- Presented an interacting non-abelian version which describes two M5-branes on an  $S^1$

## Comments

Interesting new geometrical structure for self-dual forms:  $\tilde{\mathcal{M}}$ .  
Diffeomorphisms are enabled unusually.

Extend to DBI-like M5's: Make  $H - \tilde{\mathcal{M}}(H)$  non-linear?  
[\[Perry,Schwarz\]](#),[\[Howe,Sezgin West\]](#),[\[Pasti,Sorokin,Tonin\]](#)

Extend to  $(1, 0)$  theories [\[Sambtleben,Sezgin,Wimmer\]](#)

Is the appearance of a second connection  
 $\tilde{D}_\mu = D_\mu - \frac{1}{2}[B_{\mu\nu}, Y^\nu, \cdot]$  suggestive of some 2-form structure?

Better understanding of modular anomalies vs  
diffeomorphisms?



شکراً