

# Flux Quantization on M5-branes

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## Abstract

We highlight the need for global completion of the field content in the M5-brane sigma-model analogous to Dirac’s charge/flux quantization, and we point out that the superspace Bianchi identities on the worldvolume and on its ambient supergravity background constrain the M5’s flux-quantization law to be in a non-abelian cohomology theory rationally equivalent to a twisted form of co-Homotopy. In order to clearly bring out this subtle point we give a streamlined re-derivation of the worldvolume 3-flux via M5 “super-embeddings”. Finally, assuming the flux-quantization law to actually be in co-Homotopy (“Hypothesis H”) we show how this implies Skyrmion-like solitons on general M5-worldvolumes and (abelian) anyonic solitons on the boundaries of “open M5-branes” in heterotic M-theory.

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# 1 Introduction and Overview

**The quest for non-perturbative strongly-coupled quantum theory.** The key contemporary open question in the foundations of theoretical physics — which traditionally relied on perturbation theory and mean field theory for weakly-coupled systems — remains (cf. [BaSh10][HW15, §4.1]) the general analytic understanding of strongly-coupled quantum systems (such as confined chromodynamics, c.f. [Br14]). With it (cf. [AFFK15][FGSS20]) comes the closely related issue of strongly-*interacting* and -*correlated* (long-range entangled) quantum systems (such as topologically ordered quantum materials [ZCZW19, §6.3][SS23c], envisioned to provide future hardware for robust topological quantum computers, e.g. [FKLW03][MySS24]).

**The expected M5-brane model for strongly-coupled quantum systems.** Meanwhile, the refinement of quantum field theory by string theory (e.g. [BLT13]) — for whatever else its motivations and aims have been at any time — has had the remarkable effect of leading to a glimpse of a general non-perturbative formulation of fundamental quantum physics, famously going by the working title “M-theory” (cf. [Du96][Du99]). Notably for holographic arguments about strongly-coupled quantum systems [ZLSS15][RZ16, §IV][HLS18] to become realistic by *not* passing to their large- $N$  limit requires including M-theoretic corrections in the dual gravitational theory [AGMOY00, p. 60][SS23c, Fig. 4].

Within M-theory, the object most directly expressing (strongly coupled) quantum field theory in realistic numbers of spacetime dimensions is the “Fivebrane” or “M5-brane” (cf. [Du99, §3] and below (1)). Here, apart from the widely appreciated implications on understanding weak/strong coupling S-dualities [Wi04][Wi09, §3-4] (see also [MaSa15]), it is worth highlighting that:

- (i) the quantum fields on suitable M5-brane configurations engineer at least an approximation to confined quantum chromodynamics (the Witten-Sakai-Sugimoto model [Wi98, §4] for “holographic QCD” [Re15], including the realization of hadron bound states [Su16][ILP18]) via skyrmions – cf. §4.2 below;
- (ii) co-dimension=2 defects inside M5-branes have been argued [CGK20][SS23b][SS24c] to carry anyonic quantum observables (cf. (156) below) as expected in topologically ordered quantum materials [SS23c].

This means that a deep understanding of M5-branes may plausibly go a long way towards resolving outstanding problems in contemporary strongly-coupled/correlated quantum systems.

At the same time, along with the ambient M-theory also a complete theory of the M-branes has been missing (after all, the term “M-theory” is the “non-committal” abbreviation [HW96, p. 2] of “Membrane Theory” due to doubts about the nature of the M2-brane theory): The above results are all deduced just from expected subsectors of a would-be M5-brane theory. This lack of a complete “M5-brane model” is commonplace for the quantum theory of coincident M5-worldvolumes in its decoupling limit expected to be given by a largely elusive  $D = 6$   $\mathcal{N} = (2, 0)$  superconformal field theory (e.g. [HR18][La19a, §3][SäS18]). However, the problem reaches deeper:

**The open problem of flux quantization on the M5-brane.** Our starting point here is to highlight that an open question had already remained both at a more fundamental level, namely concerning the full definition of the classical (or pre-quantum<sup>1</sup>) on-shell field content on the single M5-brane worldvolume, as well as on a more universal level, namely concerning the classification of “fractional” (i.e., torsion-charged, see §4.2) solitons on the M5-worldvolume. This is the open problem of *flux quantization* (pointers and survey in [SS25]) on the M5-brane worldvolume.

The root cause is that alongside the ambient 11d supergravity field (for pointers and review see [MiSc06][GSS24a]) with its 4-form and dual 7-form flux densities  $G_4, G_7$  on 11-dimensional target spacetime  $X$ , also the field theory on the worldvolume  $\Sigma$  of an M5-brane

$$\begin{array}{ccc} \text{M5-brane} & & \text{11-dimensional} \\ \text{worldvolume} & \Sigma \xrightarrow{\text{“embedding” field } \phi} & \text{spacetime} \end{array} X$$

famously carries a 3-form flux density  $H_3$ , subject to the following *Bianchi identity* ([HS97b, (36)][So00, (5.75)], we give a streamlined account below in §3)

$$dH_3 = \phi^* G_4. \tag{1}$$

So far this is very well known. However, most if not all authors now consider the corresponding higher gauge field configuration to be exhibited by a *globally defined* gauge potential 2-form  $B_2$  on  $\Sigma$  (e.g. [APPS97, (27)][HS97b, (37)][BLNPST97, (4)][CKvP98, (5.3)][SS98, (27)][CKKTvP98, (3.21)][So00, (5.74)][Ba11, (4.44)][BaSo23, (5.78)]). Furthermore, together with gauge potential 3- and 6-forms  $C_3, C_6$  on  $X$  this is taken to define the 3-form flux

<sup>1</sup>Flux quantization applies to the classical fields of a higher gauge theory, but it thereby determines the “pre-quantum line bundle” for sigma-model branes which are charged under (i.e., sense the Lorentz force exerted by) these gauge fields.

density  $H_3$  by the following formulas, which we (re-)derive these below in §4.1 from systematic flux quantization, cf. Rem. 4.2:

$$H_3 = dB_2 + \phi^* C_3, \quad G_4 = dC_3, \quad G_7 = dC_6 + \frac{1}{2} C_3 G_4. \quad (2)$$

The problem here is that these equations (2) in general only make sense locally, namely on (open covers here to be incarnated as) surjective submersions  $\tilde{X}$  (29) onto  $X$  with compatible surjective submersion  $\tilde{\Sigma}$  (42) onto  $\Sigma$ :

$$\begin{array}{ccc} \text{submersion} & \tilde{\Sigma} & \xrightarrow{\tilde{\phi}} & \tilde{X} & \text{submersion} \\ \text{onto...} & & & & \text{onto...} \\ & \downarrow p_\Sigma & & \downarrow p_X & \\ \text{...M5-brane} & \Sigma & \xrightarrow[\text{"embedding" field}]{\phi} & X & \text{...11-dimensional} \\ \text{worldvolume} & & & & \text{spacetime} \end{array}$$

But this means that the local gauge-potential form fields

$$\left( \begin{array}{l} C_3 \in \Omega_{\text{dR}}^3(\tilde{X}) \mid dC_3 = G_4 \\ C_6 \in \Omega_{\text{dR}}^6(\tilde{X}) \mid dC_6 = G_7 - \frac{1}{2} C_3 G_4 \\ B_2 \in \Omega_{\text{dR}}^2(\tilde{\Sigma}) \mid dB_2 = H_3 - \phi^* C_3 \end{array} \right)$$

by themselves do *not* represent a *complete* higher gauge field configuration: Further field content is needed to *glue* ( $C_3$  and)  $B_2$  on all higher intersections (30):

$$\tilde{\Sigma} \times_x \cdots \times_x \tilde{\Sigma} \xrightarrow{\tilde{\phi} \times_x \cdots \times_x \tilde{\phi}} \tilde{X} \times_x \cdots \times_x \tilde{X}$$

in a coherent manner that we recall in a moment.

The admissible choices of this remaining global field content are the *flux quantization laws* [SS25] — these determine which non-rational torsion brane charges (fractional branes, §4.2) may appear as sources of the field fluxes; and it is only with this extra choice that even the classical on-shell field content of the higher gauge theory is actually complete (cf. [SS24a]).

**The analog problem of Dirac charge quantization.** To appreciate the issue, we quickly compare it to the analogous traditional situation in vacuum electromagnetism (cf. [SS25, §2.1][SS24a, §3.1]): Here the flux density is a 2-form  $F_2$  on spacetime  $X$  (the Faraday tensor), and the local gauge potential is a 1-form  $A_1$  on a submersion  $\tilde{X}$  onto spacetime. There are in fact infinitely many admissible flux quantization laws even in this basic situation (cf. [SS24b, §2]), but the standard one going back to [Dirac1931] says (as maybe first made explicit by [Al85a][Al85b]) that alongside the local gauge potential

$$(A_1 \in \Omega_{\text{dR}}^1(\tilde{X}) \mid dA_1 = F_2)$$

an electromagnetic field configuration consists, in addition, of a *transition function*

$$\left( A_0 \in \Omega_{\text{dR}}^0(\tilde{X} \times_x \tilde{X}) \mid \begin{array}{l} dA_0 = \text{pr}_2^* A_1 - \text{pr}_1^* A_1, \\ \text{pr}_{12}^* A_0 + \text{pr}_{23}^* A_0 = \text{pr}_{13}^* A_0 \pmod{C^0(\tilde{X} \times_x \tilde{X} \times_x \tilde{X}; \mathbb{Z})} \end{array} \right). \quad (3)$$

This data is of course (the Čech-Deligne cocycle presentation, for exposition see [FSS13, §2][FSS15a]) equivalent to a connection on a  $U(1)$ -principal bundle over  $X$ . The point here is that this extra field content (3) has experimentally measurable consequences, as it implies that

- (i) there is a smallest unit of electric charge<sup>2</sup> (as observed) and
- (ii) Dirac-monopoles (hypothetical) but also Abrikosov-vortices (experimentally observed) carry integer multiples of a unit magnetic charge
- (iii) should the cosmos have the non-trivial topology such as that of a lens space with its torsion cohomology group in degree 2 (for which, incidentally, there is mild observational support [AL12]), then it may carry torsion magnetic charge (cf. [FMS07, p. 28]) of “fractional monopoles” (cf. §4.2).

These simple examples already show that (determination and understanding of) flux quantization is (or should be) a crucial step in understanding the full phenomenological scope of a higher gauge theory, in particular with respect to non-perturbative phenomena.

<sup>2</sup>Electric charge quantization is traditionally said to be conditioned on the assumption that magnetic monopoles exist (which remains hypothetical) – but we highlight that the actual logic is slightly different: Magnetic monopoles are (just as the experimentally observed Abrikosov vortices) compatible with and hence indicative of the assumption of EM-flux quantization in ordinary differential (Čech-Deligne) cohomology, and *this assumption* generally implies that the exponentiated Lorentz-(inter)action is the holonomy “ $\exp(e \int_{S^1} A)$ ” =  $\text{hol} : \text{Map}(S^1, X) \rightarrow U(1)$  (for electrically unit charged particles) of the flux-quantized background EM-field  $\hat{A}$  regarded as a  $U(1)$ -principal connection, or at most an integer power “ $\exp(ne \int_{S^1} \hat{A})$ ” =  $\text{hol}^n$  (for particles carrying  $n$  units of fundamental electric charge).

Clearly then, it is important to understand flux quantization also for the M5-brane worldvolume theory. We may approach this problem as follows.

**The general rule for flux quantization on phase space.** There is a beautiful general definition and rule for admissible flux quantization laws ([FSS23][SS24a], review in [SS25]) which applies naturally to all higher gauge theories of higher Maxwell-type and recovers existing proposals for flux quantization, showing how to systematically extend these to previously neglected theories:

If spacetime  $X^{d+1}$  is globally hyperbolic with spatial Cauchy surface  $X^d$

$$X^{1+d} \simeq \mathbb{R}^1 \times X^d, \quad (4)$$

so that the flux densities restricted to  $X^d$  constitute Cauchy data for the solution space of on-shell flux densities on  $X^{d+1}$ , then the simple idea is that flux quantization means to

(i) accompany

$$\text{flux densities } \vec{F} \equiv (F^{(i)} \in \Omega_{\text{dR}}^{\text{deg}_i}(X^d))_{i \in I} \text{ satisfying Bianchi ids. } dF^{(i)} = P^{(i)}(\vec{F}) \quad (5)$$

(ii) with

$$\text{charges } \vec{c} \text{ defining classes } [\vec{c}] \in H^1(X^d; \Omega\mathcal{A}) \text{ in a generalized cohomology theory } \mathcal{A} \quad (6)$$

(iii) subject to an

**identification**  $\vec{A}: \vec{F} \Rightarrow \vec{c}$  of the flux densities with the charges in de Rham cohomology,

where the key technical issue is to understand what it means for both the flux densities and the charges to be regarded as cocycles in a suitable form of de Rham cohomology where they can be compared. This is accomplished by observing that (cf. [SS25, §3][GSS24a, §2.1]):

(i) any system of Bianchi identities (5) is equivalently the closure condition on differential forms with coefficients in a *characteristic*  $L_\infty$ -algebra  $\mathfrak{a}$

$$\vec{F} \in \Omega_{\text{dR}}^1(X^d; \mathfrak{a})_{\text{clsd}} \quad (7)$$

whose concordance classes constitute the corresponding  $\mathfrak{a}$ -valued de Rham cohomology

$$[\vec{F}] \in H_{\text{dR}}^1(X^d; \mathfrak{a}) = \Omega_{\text{dR}}^1(X^d; \mathfrak{a})_{\text{clsd}} / \text{cnrd}, \quad (8)$$

(ii) any generalized cohomology theory (6) is characterized by its (pointed) classifying space  $\mathcal{A}$  as

$$H^1(X^d; \Omega\mathcal{A}) := \pi_0 \text{Maps}(X^d; \mathcal{A})$$

whose *character map* landing in de Rham cohomology with coefficients (8) in the *Whitehead*  $L_\infty$ -algebra  $\mathcal{L}\mathcal{A}$  is classified by the  $\mathbb{R}$ -rationalization map on  $\mathcal{A}$ :

$$\begin{array}{ccc} \mathcal{A} & \xrightarrow{\eta^{\mathbb{R}}} & L^{\mathbb{R}}\mathcal{A} \\ H^1(X^d; \mathcal{A}) & \xrightarrow{H^1(X^d; \eta^{\mathbb{R}})} & H^1(X^d; L^{\mathbb{R}}\mathcal{A}) \simeq H_{\text{dR}}^1(X^d; \mathcal{L}\mathcal{A}), \end{array}$$

(iii) the required identification is a homotopy in the deformation  $\infty$ -stack of closed  $\mathfrak{a} \simeq \mathcal{L}\mathcal{A}$ -valued differential forms

$$\begin{array}{ccc} & & \mathcal{A} \\ & \nearrow \text{charges } \vec{c} & \downarrow \eta^{\mathbb{R}} \\ & \vec{A} \text{ gauge potentials} & L^{\mathbb{R}}\mathcal{A} \\ & \downarrow \vec{F} & \downarrow \wr \\ X^d & \xrightarrow{\text{flux densities } \vec{F}} \Omega_{\text{dR}}^1(-; \mathfrak{a})_{\text{clsd}} \xrightarrow{\eta^{\mathbb{J}}} \int \Omega_{\text{dR}}^1(-; \mathfrak{a})_{\text{clsd}} & \downarrow \wr \\ & & \mathcal{L}\mathcal{A} \end{array} \quad (9)$$

This general prescription notably subsumes (as reviewed in [SS25] with extensive pointers to the literature):

- traditional Dirac charge quantization of electromagnetism in (differential) ordinary integral 2-cohomology [SS24a, §3.1][SS24b, §2],
- B-field flux quantization in (differential) ordinary integral 3-cohomology [SS25, Ex. 3.10],
- flux quantization of self-dual higher gauge fields in (differential) ordinary cohomology [SS24a, §3.2],
- quantization of RR-fluxes in topological K-theory [SS24a, §3.3][SS25, §4.1] (cf. [GS22]),
- a couple of proposed flux quantization laws for the C-field in 11d supergravity [SS24a, §3.4][SS25, §4.2], including the C-field model of [DFM07] following [Wi97a][Wi97b],
- flux quantization for additional Green-Schwarz terms with (abelian) 2-flux densities [Sa19][FSS22][SS20c].

**The issue of (self-)duality in flux quantization.** What makes the above examples work is – besides the assumption of globally hyperbolic spacetime (4) – that in all these cases the full equations of motion of the higher gauge theories are

- (i) the Bianchi identities (5) (7)

$$dF^{(i)} = P^{(i)}(\vec{F})$$

- (ii) and one more *linear* system of (self-)duality constraints

$$\star F^{(i)} = \mu^{(i)}(\vec{F}), \quad (10)$$

because it turns out [SS24a, Thm. 2.2] that for flux densities on a Cauchy surface the linear duality constraint (10) is entirely absorbed into the isomorphism between the space of such Cauchy data and the solution space of flux densities over all of spacetime.

However, each of the assumptions, that of globally hyperbolic spacetimes (4) and that of the linear self-duality constraint (10) is somewhat restrictive; in particular, the latter is actually violated for the 3-flux density on M5-branes ([HSW97b], cf. Rem. 3.19 below).

**Resolution by flux-quantization on super-spaces.** Our key move now for solving the problem of flux quantization also on M5-branes is the observation that both of the above problems go away when considering the M5-brane as immersed *in super-spacetime* (following [HS97b][So00, §5.2]). The reason is that here the self-duality condition on the flux forms turns out to be all absorbed into the Bianchi identities on their super-field versions (re-derived as Prop. 3.18)! Since this result — which in light of the problem of flux quantization is now revealed to be quite profound — has perhaps remained under-appreciated outside the original specialist literature, our main contribution in §3.3 below is to give a streamlined and rigorous re-derivation, based on some more mathematically informed commentary on the proper definition of the underlying concept of “super-embeddings” [HSW98][HRS98][So00][BaSo23] in §2.

This resolution of the problem of flux quantization on the M5 builds on and extends the super-flux quantization of the background 11d supergravity fields which we established in [GSS24a]:

**Super-flux of 11d Supergravity.** Namely, the analogous miracle of on-shell 11d supergravity (going back to [CF80][BH80][CDF91, §III.8.5]), is that on super-spacetimes  $X$  (“curved superspace”, namely super-manifolds of super-dimension  $(1, 10)$  | **32** equipped with super-coframe fields  $(E, \Psi)$  and super-torsion-free spin connection  $\Omega$ ) the Bianchi identities

$$dG_4^s = 0, \quad dG_7^s = \frac{1}{2}G_4^s G_4^s \quad (11)$$

on the duality-symmetric *super-flux* densities

$$\begin{aligned} G_4^s &\equiv \underbrace{(G_4)_{a_1 \dots a_4} E^{a_1} \dots E^{a_4}}_{G_4} + \underbrace{\frac{1}{2}(\bar{\Psi} \Gamma_{a_1 a_2} \Psi) E^{a_1} E^{a_2}}_{G_4^0} \\ G_7^s &\equiv \underbrace{(G_7)_{a_1 \dots a_7} E^{a_1} \dots E^{a_7}}_{G_7} + \underbrace{\frac{1}{5!}(\bar{\Psi} \Gamma_{a_1 \dots a_5} \Psi) E^{a_1} \dots E^{a_5}}_{G_7^0} \end{aligned} \quad (12)$$

are already equivalent (as brought out in this form in [GSS24a, Thm. 3.1]) to the equations of motion of 11d SuGra; in particular they *imply* the Hodge duality relation

$$G_7 = \star G_4 \in \Omega_{\text{dR}}^7(\tilde{X}) \quad (13)$$

on the underlying bosonic spacetime manifold  $\tilde{X} \leftrightarrow X$ .

This is remarkable, because it means ([GSS24a, Claim 1.1]) that the flux quantization (9) applied to the super-flux densities (12) on  $(1, 10|\mathbf{32})$ -dimensional super-spacetime may be regarded the full globally completed field content of on-shell 11d supergravity, reflecting also all torsion/fractional charges of M-branes (according to that choice of flux quantization).

Here we are concerned with further refining this result to include the M5-brane worldvolume theory in such a background.

**Super-flux on the M5-brane.** Namely, a similar miracle occurs (this goes back to [HS97b][So00, §5.2], re-derived in §3.3 below) for M5-brane worldvolumes  $\Sigma \xrightarrow{\phi} X$  understood as “super-embeddings” ([HSW98][HRS98]<sup>3</sup>, or more precisely *1/2BPS immersions*, cf. Defs. 2.19, 3.12 below) of  $(1, 5 | 2 \cdot \mathbf{8})$ -dimensional super-worldvolumes (with induced super-coframe fields  $(e, \psi)$  and spin-connection  $\omega$ ) into  $(1, 10|\mathbf{32})$ -dimensional super-spacetimes as above. Here the worldvolume Bianchi identity (1)

<sup>3</sup>Early discussion of the idea of brane sigma-models where both the worldvolume as well as the target spacetime are treated as supermanifolds is due to [GH86][BMG86], under the name “supersymmetry squared”.

$$dH_3^s = \phi^* G_4^s \quad (14)$$

is now imposed on the super-flux densities (12). Furthermore, the expression

$$H_3^s \equiv \underbrace{(H_3)_{a_1 a_2 a_3} e^{a_1} e^{a_2} e^{a_3}}_{H_3} + \underbrace{0}_{H_3^0} \quad (15)$$

already implies (re-derived as Prop. 3.18 below) the subtle non-linear Hodge self-duality property of  $H_3$  (cf. Rem. 3.19), namely that it is expressed as a rational function of a super-3-form which is actually self-dual:

$$\Rightarrow (H_3)_{abc} = \frac{-4}{1 - 2/3 \operatorname{tr}(\tilde{H}_3^2 \cdot \tilde{H}_3^2)} (\delta_{a'}^a + 2(\tilde{H}_3^2)_{a'}^a) (\tilde{H}_3)_{a'b'c}, \quad \text{for } \begin{cases} (\tilde{H}_3) \equiv \frac{1}{3!} (\tilde{H}_3)_{a_1 a_2 a_3} e^{a_1} e^{a_2} e^{a_3} \\ (\tilde{H}_3)_{a_1 a_2 a_3} = \frac{1}{3!} \epsilon_{a_1 a_2 a_3 b_1 b_2 b_3} (\tilde{H}_3)^{b_1 b_2 b_3}. \end{cases} \quad (16)$$

With this result in hand, the admissible flux-quantization laws for completed field content on M5-branes now follows from general considerations:

**Characteristic flux  $L_\infty$ -algebra on the M5.** The immediate consequence is that the on-shell flux densities on the M5 super-worldvolume are entirely characterized by the Bianchi identities (11) on the super-fluxes and (14); and the first step towards flux-quantizing them is hence to identify their characteristic  $L_\infty$ -algebra (7).

- For the 11d SUGRA C-field Bianchi identity (11), this is ([Sa10, §4][SS25, (24)][GSS24a, Ex. 2.29]) the ‘‘M-theory gauge algebra’’ [CJLP98, (2.6)]

$$\mathfrak{IS}^4 \simeq \mathbb{R} \left\langle \begin{matrix} v_3 \\ v_6 \end{matrix} \right\rangle / ([v_3, v_3] = v_6) \quad \Leftrightarrow \quad \operatorname{CE}(\mathfrak{IS}^4) \simeq \mathbb{R} \begin{bmatrix} g_4 \\ g_7 \end{bmatrix} / \left( \begin{matrix} dg_4 = 0 \\ dg_7 = \frac{1}{2} g_4 g_4 \end{matrix} \right), \quad (17)$$

- while with the M5’s B-field Bianchi identity (14) *adjoined*, in addition a non-trivial unary bracket  $[-]$  appears:

$$\mathfrak{I}_{S^4} S^7 \simeq \mathbb{R} \left\langle \begin{matrix} v_3 \\ v_6 \\ v_2 \end{matrix} \right\rangle / \left( \begin{matrix} [v_3, v_3] = v_6 \\ [v_3] = v_2 \end{matrix} \right) \quad \Leftrightarrow \quad \operatorname{CE}(\mathfrak{I}_{S^4} S^7) \simeq \mathbb{R} \begin{bmatrix} g_4 \\ g_7 \\ h_3 \end{bmatrix} / \left( \begin{matrix} dg_4 = 0 \\ dg_7 = \frac{1}{2} g_4 g_4 \\ dh_3 = g_4 \end{matrix} \right). \quad (18)$$

Here the notation on the left indicates that these  $L_\infty$ -algebras happen to coincide (by [FSS20b, Prop. 3.20], cf. [FSS21a, (38)]) with the (relative)  $\mathbb{R}$ -Whitehead  $L_\infty$ -algebras (cf. [FSS23, Prop. 5.16][SV22]) of (the homotopy type of) the 4-sphere and of the quaternionic Hopf fibration  $S^7 \xrightarrow{h_{\mathbb{H}}} S^4$ , respectively, corresponding to the  $L_\infty$ -fibration

$$\begin{array}{ccc} \mathfrak{I}_{S^4} S^7 & v_3 & v_6 & v_2 \\ \downarrow h_{\mathbb{H}} & \downarrow & \downarrow & \downarrow \\ \mathfrak{IS}^4 & v_3 & v_6 & 0. \end{array}$$

This means that the on-shell flux density content on the M5-brane is concisely embodied by commutative diagrams of smooth super-spaces (as explained in [GSS24a, §2.1], for background see [GS23][GSS24d]) of the following form:

$$\begin{array}{ccc} \text{Super-worldvolume} & \Sigma^{1,5|2\cdot 8} & \xrightarrow{\text{worldvolume B-field flux } (\phi^* G_4^s, \phi^* G_7^s, H_3^s)} \Omega_{\text{dR}}^1(-; \mathfrak{I}_{S^4} S^7)_{\text{clsd}} \\ \downarrow \phi & & \downarrow (h_{\mathbb{H}})_* \\ \text{M5 super-immersion} & & \\ \text{(Def. 3.12)} & & \\ \text{11d super-spacetime} & X^{1,10|32} & \xrightarrow{\text{background C-field flux } (G_4^s, G_7^s)} \Omega_{\text{dR}}^1(-; \mathfrak{IS}^4)_{\text{clsd}} \end{array} \quad \Leftrightarrow \quad \begin{cases} dH_3^s = \phi^* G_4^s \\ dG_4^s = 0 \\ dG_7^s = \frac{1}{2} G_4^s G_4^s. \end{cases} \quad (19)$$

Here the bottom map reflects a solution to 11d supergravity (by [GSS24a, Ex. 2.30, Thm. 3.1], following [CF80][BH80]), the left map reflects a solution to the M5-brane’s equations of motion (discussed in §3, following [HS97b][So00, §5.2]) in this background, and the unique top map making the diagram commute extracts the corresponding worldvolume flux density (re-derived in Prop. 3.18 below).

**Super-flux quantization on M5-branes.** The upshot of casting the equations of motion of the M5-brane in the diagrammatic form (19) is that it reveals the admissible flux quantization laws (cf. [SS25, §3.2]) to be classified by fibrations  $p : \mathcal{A} \rightarrow \mathcal{B}$  (of connected nilpotent spaces of finite rational homotopy type  $\ell p$ , cf. [FSS23, Def. 5.1]) whose rational homotopy type (the target of the twisted character map, cf. [FSS23, §V]) is that of the quaternionic





denoted as follows:

$$\begin{array}{l}
\text{M-brane charge in} \\
\text{4-Cohomotopy}
\end{array}
\quad [c_3, c_6] \in \pi^4(X) := \pi_0 \text{Maps}(X, S^4) = \left\{ X \overset{(c_3, c_6)}{\dashrightarrow} S^4 \right\} /_{\text{hmtpt.}}$$

$$\begin{array}{l}
\text{Charges on M5-branes in} \\
\text{twisted 3-Cohomotopy}
\end{array}
\quad \pi^{3+\phi^*(c_3, c_6)}(\Sigma) := \pi_0 \text{Maps}(\Sigma, S^7) /_{S^4} = \left\{ \begin{array}{ccc} \Sigma & \overset{b_2}{\dashrightarrow} & S^7 \\ \phi \downarrow & \swarrow & \downarrow h_{\mathbb{H}} \\ X & \xrightarrow{(c_3, c_6)} & S^4 \end{array} \right\} /_{\text{rel.hmtpt.}} \quad (22)$$

Therefore, the hypothesis that this “evident” choice of flux-quantization is the “correct” one for completing the theory of the M5-brane in M-theory has been called “Hypothesis H” in [FSS20b][FSS21a][FSS21c][GS21][SS23a], following [Sa13, §2.5] (the corresponding differential co-Homotopy for the M5-brane fields was first considered in [FSS15b]), which may be thought of as an M-theoretic version of the traditional “Hypothesis K” that D-brane charges are in (twisted) K-theory (cf. [SS23b, Rem. 4.1]).

Notice that maps to the 4-sphere also appear on  $N$  M5-worldvolumes  $\Sigma$  in the guise of the scalar fields  $\Phi$  taking values in the surrounding  $\mathbb{R}^5 \setminus \{0\} \simeq \mathbb{R}_{>0} \times S^4$ , from which the  $G_4$ -flux density  $\simeq N \text{dvol}_{S^4}$  on spacetime thus gets pulled back to the worldvolume as  $\Phi^* G_4 = N \cdot \Phi^* \text{dvol}_{S^4}$  (first highlighted in [GM98, §3][In00], as such reviewed in [Be08, p. 20] and further developed in [FSS21a]). Now by *Hypothesis H* already  $G_4$  itself is the “Cohomotopical character” ([FSS23, §12]) on spacetime of — hence (by [FSS20b, (47)]) the pullback of the unit volume form along — a map  $c_3$  from the ambient spacetime to the homotopy type of  $S^4$  (playing the role of the Cohomotopy classifying space), which near the horizon of a black M5-brane is (cf. [SS21a, Rem. 1][GSS24b]) just a multiple  $N \in \mathbb{Z}$  of the projection map  $p_{S^4}$  identifying the geometric  $S^4$  around the M5-brane with the “classifying”  $S^4$  for Cohomotopy theory:

$$\begin{array}{ccc}
\Sigma & & \\
\downarrow \text{id}_{\Sigma} \times \Phi & \searrow N \cdot \Phi^* \text{dvol}_{S^4} \leftarrow \text{dvol}_{S^4} & \\
\underbrace{\Sigma \times \mathbb{R}_{>0} \times S^4}_X & \xrightarrow{c_3 = N \cdot p_{S^4}} & S^4 \\
\text{Spacetime near black M5 horizon} & \text{classifying map of C-field charge by Hypothesis H} & \text{Classifying space for 4-Cohomotopy}
\end{array} \quad (23)$$

Here Hypothesis H entails that the global C-field charge on  $\Sigma$  is not just the pulled back flux shown on the diagonal above, but the homotopy class of that diagonal map itself (of which the pullback flux is just the “character” in de Rham cohomology). E.g.: if  $\Sigma \simeq \mathbb{R} \times S^5$  then there is a torsion charge  $[S^5 \rightarrow S^4] \in \pi^4(\Sigma) \simeq \mathbb{Z}_2$  (a homotopy group of spheres, cf. [SS23a]) which is non-trivial in Cohomotopy but not detected by the de Rham class of  $\Phi^* G_4$ .

Hypothesis H is supported by the fact that it *implies* a series of subtle topological (anomaly cancellation-) conditions (survey in [FSS20b, Tbl 1][FSS23, §12]) that are expected to hold in M-theory (including M5-brane anomaly cancellation [SS21a]), notably the following two <sup>4</sup> which ensure that the exponentiation of the usual gauge-coupling action functionals for the M-branes ([PST97, §3]) are globally well-defined:

- [FSS20b, Prop. 3.13] the shifted flux quantization [Wi97a, p 2-3] of the flux sourced by M5-branes:

$$[G_4 + \frac{1}{4} p_1] \in H^4(X; \mathbb{Z}) \longrightarrow H^4_{\text{dR}}(X), \quad (24)$$

which serves as the Wess-Zumono-term on M2-branes,

- [FSS21a, Thm. 4.8]: the integral flux quantization of the *Page charge*

$$[\tilde{2}G_7 + H_3(G_4 + \frac{1}{4} p_1)] \in H^7(\Sigma^7; \mathbb{Z}) \longrightarrow H^7_{\text{dR}}(\Sigma^7) \quad (25)$$

sourced by M2-branes, which serves as the completed *Hopf-Wess-Zumino term* on M5-branes.

Note here that the homotopy fiber of the quaternionic Hopf fibration is the 3-sphere  $S^3 \xrightarrow{\text{fib}(h_{\mathbb{H}})} S^7 \xrightarrow{h_{\mathbb{H}}} S^4$ ,

(which remains the case after  $\widehat{\text{Sp}(2)}$ -twisting) and which implies that the charges on the M5 (22) are *locally* cocycles in 3-Cohomotopy, globally twisted by the 4-Cohomotopy of the supergravity background ([FSS20b, Rem.

<sup>4</sup> The gray terms in (24) and (25) do arise on curved spacetimes by flux-quantization in *tangentially twisted co-Homotopy* [FSS20b].

Here we disregard discussion of the tangential twist for the sake of brevity. Under this simplifying assumption the gray term in (24) is not implied by the cohomotopical quantization condition, and thereby the implied integrality condition on  $G_4$  is the expected one (only) on spacetimes for which  $\frac{1}{4} p_1$  is integral. This however is the case for the main examples of interest here, such as the Freund-Rubin spacetime  $\text{AdS}_7 \times S^4$  (cf. Ex. 3.15) where the Pontrjagin classes actually vanish [SS21a, Prop. 22].



3.17][FSS21a, pp. 21][FSS21c, p. 6]; a twist of this kind was anticipated early on in [Sa06][Sa10]). In [FSS21c] it was explained how, under Hypothesis H with gravitational twists included, as above, this reveals the  $H_3$ -flux as associated with a kind of “non-abelian gerbe field” on the M5-brane not unlike the proposals previously made in [Wi04, p. 6, 15][Wi09, §3][SäS18][SäS20].

**The need for super-flux quantization.** However, in previous discussions of Hypothesis H it had been left open which effect, if any, the duality-relations on the flux densities have on the flux quantization process (away from a Cauchy surface, where the issue was solved in [SS24a]). This is the remaining point which we solve here (in tandem with [GSS24a]), by passing to super-spacetimes and observing that here the duality relations on the bosonic flux densities are absorbed within the Bianchi identities of their super-flux enhancements, so that flux quantization on super-space is revealed to already deal with the exact on-shell field content, not requiring any further constraints. In order to properly bring out this remarkable but subtle point we proceed as follows:

in §2 **Revisiting super-embeddings** we review the idea of “super-embeddings” of super  $p$ -branes with attention to what we feel have remained loose ends: the global nature of co-frame fields, the relation to the classical theory of Darboux co-frame fields, and an observation on how to naturally unify/streamline what actually is a list of traditional “super-embedding” conditions.

in §3 **M5-brane super-immersions** we systematically re-derive the equations of motion of the 3-flux on M5-branes using a transparent algebraic description of the all-important reduction and branching of spin representations on the M5-brane.

**Analyzing quantized flux on M5-branes.** With these results in hand, we close

in §4 **Flux quantization on M5 branes** by showing how flux quantization on the M5 reproduces the traditional local formulas for higher gauge potentials while completing these to global fields that may exhibit skyrmionic and anyonic topological properties.

## 2 Revisiting “super-embeddings”

Here we give a streamlined and rigorous account of the “super-embedding approach” to super  $p$ -brane sigma models (due to [BPSTV95][HS97a][HRS98][So00], previously reviewed in [Ba11][BaSo23]), providing a precise super-geometric formulation (which seems previously to have been missed by super-geometers, cf. [Ro07, §13.3]). Besides setting the scene for the analysis following in §3 and clearing up some fine-print not usually considered in the literature, the main observation here is (Prop. 2.21) a slick way to unify (Def. 2.19 of “BPS super-immersions”) the traditional data of “super-embeddings” (Rem. 2.23) by generalizing the classical notion of *Darboux coframe fields* for Riemannian immersions (discussed in §2.1); see also Rem. 2.10 for the distinction between immersions and embeddings.

**Conventions.** Our conventions are standard, but since the computations in §3 crucially depend on the corresponding prefactors, here to briefly make them explicit:

**Notation 2.1 (Tensor conventions).**

- The Einstein summation convention applies throughout: Given a product of terms indexed by some  $i \in I$ , with the index of one factor in superscript and the other in subscript, then a sum over  $I$  is implied:  $x_i y^i := \sum_{i \in I} x_i y^i$ .
- Our Minkowski metric is the matrix

$$(\eta_{ab})_{a,b=0}^d = (\eta^{ab})_{a,b=0}^d := \left( \text{diag}(-1, +1, +1, \dots, +1) \right)_{a,b=0}^d \quad (26)$$

- Shifting position of frame indices always refers to contraction with the Minkowski metric (26):

$$V^a := V_b \eta^{ab}, \quad V_a = V^b \eta_{ab}.$$

- Skew-symmetrization of indices is denoted by square brackets ( $(-1)^{|\sigma|}$  is sign of the permutation  $\sigma$ ):

$$V_{[a_1 \dots a_p]} := \frac{1}{p!} \sum_{\sigma \in \text{Sym}(n)} (-1)^{|\sigma|} V_{a_{\sigma(1)} \dots a_{\sigma(p)}}.$$

- We normalize the Levi-Civita symbol to

$$\epsilon_{012\dots} := +1 \quad \text{hence} \quad \epsilon^{012\dots} := -1. \quad (27)$$

- We normalize the Kronecker symbol to

$$\delta_{b_1 \dots b_p}^{a_1 \dots a_p} := \delta_{[b_1 \dots b_p]}^{[a_1 \dots a_p]} = \delta_{[b_1}^{a_1} \dots \delta_{b_p]}^{a_p} = \delta_{b_1}^{a_1} \dots \delta_{b_p}^{a_p}$$

so that

$$V_{a_1 \dots a_p} \delta_{b_1 \dots b_p}^{a_1 \dots a_p} = V_{[b_1 \dots b_p]} \quad \text{and} \quad \epsilon^{c_1 \dots c_p a_1 \dots a_q} \epsilon_{c_1 \dots c_p b_1 \dots b_q} = -p! \cdot q! \delta_{b_1 \dots b_q}^{a_1 \dots a_q}. \quad (28)$$

### 2.1 Darboux co-frame fields

We recall the classical notion of *Darboux co-frame fields* for (pseudo-)Riemannian immersions (Def. 2.12 below, which may not to have found due attention in the super-embedding literature before) and re-cast it into an equivalent form (Prop. 2.16) whose super-geometric generalization turns out to be just that of  $1/2$ BPS super-immersions (“super-embeddings”) of super  $p$ -branes (§2.2 below).

In order to be precise, we begin now by being a little pedantic about some maybe underappreciated global aspects of local coframe fields (which can be and typically are ignored in local analysis but can no longer be ignored for global discussions such as of flux quantization) — the impatient reader may want to skip ahead to §2.2 and come back here only as need be.

**Relativistic local co-frame fields.** In much of the physics literature, coframe fields  $E$  on a spacetime  $X$  are shown on a single tacitly-assumed chart  $U \hookrightarrow X$  only, instead of on all of spacetime  $X$ , leaving their global definition to the imagination of the reader. But since global issues cannot be neglected for our purpose of flux quantization, we introduce a tad of extra notation that allows to elegantly deal with this issue properly.

**Open covers.** Namely given an open cover of spacetime  $\{U_j \xrightarrow{\iota_j} X\}_{j \in J}$  such that the coframe field  $E$  is naively defined on each of the charts  $U_j$ , then we denote smooth manifold which is the disjoint union of all these charts as follows

$$\begin{array}{ccc} \text{open cover} & \text{corresponding open submersion} & \tilde{X} \xrightarrow{p} X \\ \{U_j \xrightarrow{\iota_j} X\}_{j \in J} & \tilde{X} := \coprod_{j \in J} U_j, \quad \text{with} & \underbrace{(x, j)}_{\in U_j} \mapsto x. \end{array} \quad (29)$$



**Remark 2.3 (Čech cocycle data from co-frames).** Beware that in the above Def. 2.2 there are no further conditions imposed on triple overlaps, because we are *not constructing* a bundle from Čech cocycle data, but instead are *extracting* Čech data (in order to impose orthogonality conditions on it) from picking local trivializations (the co-frames) of an already given bundle (the tangent bundle). Indeed, the transition function (31) induced by a choice of co-frames necessarily satisfies on triple overlaps

$$\begin{array}{ccc} & \tilde{X} \times_X \tilde{X} \times_X \tilde{X} & \\ \swarrow \text{pr}_{12}^* & \downarrow \text{pr}_{13} & \searrow \text{pr}_{23} \\ \tilde{X} \times_X \tilde{X} & \tilde{X} \times_X \tilde{X} & \tilde{X} \times_X \tilde{X} \end{array}$$

its Čech cocycle condition

$$\text{pr}_{23}^* g \cdot \text{pr}_{12}^* g = \text{pr}_{13}^* g \quad \text{hence} \quad \forall_{\substack{ijk \\ x \in U_{ijk}}} g_{jk}(x) \cdot g_{ij}(x) = g_{ik}(x)$$

because the following diagram commutes by construction:

$$\begin{array}{ccc} & \mathbb{R}^{1+d} \times \hat{X} & \\ \swarrow \text{pr}_{12}^* g & \uparrow \text{pr}_{23}^* t & \searrow \text{pr}_{23}^* g \\ \mathbb{R}^{1+d} \times \hat{X} & p^* TX & \mathbb{R}^{1+d} \times \hat{X} \\ \swarrow \text{pr}_2^* t & & \searrow \text{pr}_3^* t \\ & \mathbb{R}^{1+d} \times \hat{X} & \\ \swarrow \text{pr}_{13}^* g & & \searrow \end{array} \quad \text{hence} \quad \forall_{\substack{ijk \\ x \in U_{ijk}}} \begin{array}{ccc} & \mathbb{R}^{1+d} & \\ \swarrow g_{ij}(x) & \uparrow E_j(x) & \searrow g_{jk}(x) \\ \mathbb{R}^{1+d} & T_x X & \mathbb{R}^{1+d} \\ \swarrow E_i(x) & & \searrow E_k(x) \\ & \mathbb{R}^{1+d} & \\ \swarrow g_{ik}(x) & & \searrow \end{array}$$

This is closely related to the equivalence of co-frame fields to metric tensors, which we come to in Lem. 2.7 and Rem. 2.8 below.

**Notation 2.4 (Co-frame components).** With the canonical coordinate projection functions denoted

$$\mathbb{R}^{1,d} \simeq \mathbb{R}^1 \times \mathbb{R}^1 \times \dots \times \mathbb{R}^1 \xrightarrow{(-)^a} \mathbb{R}, \quad a \in \{0, 1, \dots, d\},$$

we have the usual component-expression of a co-frame field (Def. 2.2):

$$E^a \in \Omega_{\text{dR}}^1(\tilde{X}) \quad \text{for} \quad T\tilde{X} \xrightarrow{E} \mathbb{R}^{1,10} \xrightarrow{(-)^a} \mathbb{R}.$$

For instance, in these components the transition function (31) and the transformation property (34) reads:

$$\text{pr}_2^*(E^a) = g^a_b(\text{pr}_1^* E^b).$$

**Definition 2.5 (Orthonormal local co-frames).** A coframe field (Def. 2.2) induces a metric tensor  $ds^2$  on  $X$ , as the tensor square of the associated 1-form  $E$  (33) by the formula

$$ds^2 := E^a \otimes E_a := \eta_{ab} E^a \otimes E^b. \quad (35)$$

By (34) this tensor descends from the cover  $\tilde{X}$  to  $X$ , making it a pseudo-Riemannian manifold  $(X, ds^2)$ .

Conversely, given a (pseudo)-Riemannian metric on  $X$ , a local co-frame field  $E$  is called *orthonormal* if it represents that metric, in that the above relation holds (cf. e.g. [Lee18, p. 14]).

The following Lem. 2.6 is a classical fact, but worth recording as preparation for the construction of Darboux co-frames in Lem. 2.15, which is needed for “super-embeddings” in Def. 2.19 to be well-defined.

**Lemma 2.6 (Existence of orthonormal co-frames).** *On a (pseudo-)Riemannian manifold  $(X, ds^2)$  there exists a (relativistic) orthonormal co-frame (Def. 2.5).*

*Proof.* Since  $X$  is a smooth manifold, we may find an open cover  $\hat{X}$  of  $X$  by coordinate charts, with associated coordinate function  $x : \hat{X} \rightarrow \mathbb{R}^{1,d}$ . This locally induces a canonical co-frame given by the tuple of coordinate differentials  $(dx^0, dx^1, \dots, dx^d)$  and a *frame* given by the tuple of coordinate vector fields  $(\partial_0, \partial_1, \dots, \partial_d)$ . While these will in general not be orthonormal with respect to  $ds^2$ , the pseudo-Riemannian version of the Gram-Schmidt algorithm (e.g. [O’N83, Lem. 2.24], here for matrices with coefficients in  $C^\infty(\hat{X})$ ) produces a local frame that is orthonormal.

$$(V_a := E_a^\mu \partial_\mu)_{a=0}^d, \quad ds^2(V_a, V_b) = \eta_{ab}. \quad (36)$$

The Gram-Schmidt coefficient matrix is invertible, with inverse to be denoted by shifting its indices, as usual:

$$(E_\mu^a)_{a,\mu=0}^d := \left( (E_a^\mu)_{a,\mu=0}^d \right)^{-1}. \quad (37)$$

These inverse coefficients define the desired orthonormal co-frame

$$(E^a := E^a_\mu dx^\mu)_{a=0}^d, \quad \eta_{ab} E^a \otimes E^b = ds^2 \quad (38)$$

due to the orthonormality (36) and the invertibility (37):

$$\eta_{ab} E^a_\mu E^b_\nu = ds^2_{\mu\nu} \quad \Leftrightarrow \quad \eta_{ab} = E^a_\mu E^b_\nu ds^2_{\mu\nu}. \quad (39)$$

It just remains to verify that (38) satisfies the global conditions on a co-frame from Def. 2.2, which amounts to checking that on double overlaps  $\tilde{X} \times_x \tilde{X}$  the transition matrix is orthogonal

$$(g^a_{a'} := (\text{pr}_1^* E^a_\mu)(\text{pr}_2^* E^{\mu}_{a'}))_{a,a'=0}^d \in C^\infty(\tilde{X}; \text{O}(1, d)), \quad (40)$$

which is indeed the case:

$$\begin{aligned} \eta_{ab} g^a_{a'} g^b_{b'} &= \eta_{ab} \left( (\text{pr}_1^* E^a_\mu)(\text{pr}_2^* E^{\mu}_{a'}) \right) \left( (\text{pr}_1^* E^b_\nu)(\text{pr}_2^* E^{\nu}_{b'}) \right) && \text{by (40)} \\ &= \underbrace{\eta_{ab} (\text{pr}_1^* E^a_\mu)(\text{pr}_1^* E^b_\nu)}_{ds^2_{\mu\nu}} (\text{pr}_2^* E^{\mu}_{a'}) (\text{pr}_2^* E^{\nu}_{b'}) && \text{by (39)} \\ &= \eta_{a'b'} && \text{by (39)}. \quad \square \end{aligned} \quad (41)$$

**Lemma 2.7 (Essential uniqueness of orthonormal co-frame fields).** *Any pair of orthonormal frames  $E, \tilde{E}$  for the same metric  $ds^2$  is equivalent by a unique transformation (32).*

*Proof.* We may assume without restriction that the two co-frames are given by differential forms  $E, \tilde{E} : T\tilde{X} \rightarrow \mathbb{R}^{1+d}$  with respect to the same cover by coordinate charts  $x : \tilde{X} \rightarrow \mathbb{R}^{1+d}$  (otherwise pull them back to the common refinement cover  $\tilde{X}_1 \times_x \tilde{X}_2$  and then further to any coordinate atlas  $\tilde{X}$  of that). Here, both are expanded in components of the corresponding coordinate frame

$$E^a = E^a_\mu dx^\mu, \quad \tilde{E}^a = \tilde{E}^a_\mu dx^\mu.$$

By their co-frame property, the coefficient matrices are pointwise invertible with inverses to be denoted by shifting the indices, as usual:

$$(E^\mu_a)_{a,\mu=0}^d := ((E^a_\mu)_{a,\mu=0}^d)^{-1}.$$

Therefore

$$(k^a_{a'} := \tilde{E}^a_\mu E^\mu_{a'})_{a,a'=0}^d \in C^\infty(\tilde{X}, \text{GL}(1+d))$$

is the unique transformation

$$k^a_{a'} E^{a'} = \tilde{E}^a \quad \begin{array}{ccc} \mathbb{R}^{1+d} & \xrightarrow{k} & \mathbb{R}^{1+d} \\ & \swarrow E(x) \quad \searrow \tilde{E}(x) & \\ & T_x X & \end{array}$$

and the fact that this is an orthogonal transformation  $\eta_{ab} k^a_{a'} k^b_{b'} = \eta_{a'b'}$ , follows as in (41).  $\square$

**Remark 2.8 (Groupoid of co-frame fields equivalent to set of metrics).** The pair of Lemmas 2.6 and 2.7 may jointly be understood as saying that the functor from the groupoid of (relativistic) co-frame fields  $E$  to the set of (pseudo-)Riemannian metric tensors  $ds^2$  (on a given smooth manifold  $X$ ) is essentially surjective (in fact surjective) and fully faithful, hence is an equivalence.

**Remark 2.9 (Lifting smooth maps to covers).** The notion of equivalence on the data in Def. 2.2 ensures that the specific choice of open cover  $\tilde{X}$  is irrelevant — which justifies our notation suggestive of *any one* open cover of  $X$ . But to lift a smooth map  $\Sigma \rightarrow X$  to a map between chosen covers

$$\begin{array}{ccc} \tilde{\Sigma} & \xrightarrow{\tilde{\phi}} & \tilde{X} \\ \downarrow & & \downarrow \\ \Sigma & \xrightarrow{\phi} & X \end{array} \quad (42)$$

the cover  $\tilde{\Sigma}$  needs to be fine enough, relative to the given  $\tilde{X}$ . This can always be achieved. Given  $\phi$ , the canonical choice for the cover of  $\Sigma$  is the pullback  $\tilde{\Sigma} := \Sigma \times_X \tilde{X} \cong \coprod_{j \in J} \phi^{-1}(U_j)$  of the cover on  $X$ , hence the case where (42) is a Cartesian square. <sup>5</sup>

<sup>5</sup>The general way of dealing with these matters is to work with (model categories of) “smooth  $\infty$ -stacks”, where the issue of passing to covers is reflected in the notion of cofibrant resolutions. The interested reader may find these methods concisely reviewed in [FSS23, §1], but for the present purpose the above considerations are sufficient.

**Immersion.** The notion of *isometric embeddings* of Riemannian manifolds into each other is of course a classical one, with the “isometric embedding problem” – namely the task of finding isometric embeddings of given abstract Riemannian manifolds into large-dimensional but flat Euclidean spaces – being a seminal problem in the field of Riemannian geometry (cf. [HL23]). The key observation of the “super-embedding approach” to super  $p$ -branes is that certain immersions of supermanifolds are considerably richer than their bosonic counterpart might suggest, in that their super-odd component may encode extra data (Rem. 2.15) of *differential forms* on the embedded submanifold, playing the role of flux densities of higher gauge fields appearing on these brane worldvolumes.

**Remark 2.10 (Immersion vs. embeddings).** In developing this here with mathematical precision, we start by noticing that it is not really embeddings but *immersions*

$$\begin{array}{ccc}
 T\Sigma & \xrightarrow[\text{fiberwise injection}]{d\phi} & TX \\
 \downarrow & \swarrow & \downarrow \\
 \Sigma & \xrightarrow[\text{immersion (colloq.: "embedding field")}]{\phi} & X \\
 \text{Immersed manifold} & & \text{Ambient manifold} \\
 \text{(brane worldvolume)} & & \text{(bulk/target space)}
 \end{array}
 \quad (43)$$

$\Sigma \times_x TX$  (pb)

that are relevant here — recalling (e.g. [Bo75, §III.4]) that an embedding of smooth manifolds is

- (i) an immersion — namely a smooth map  $\phi$  whose differential  $d\phi$  is fiberwise an injection of tangent spaces (43),
- (ii) which in addition is a homeomorphism onto its topological image.

These are non-degeneracy conditions on  $\phi$ , locally and globally: The first condition is *local* and translates, as we will see, to differential equations on  $\phi$ , but the second condition is to rule out *global* degeneracies of  $\phi$ , such as points in target space where two distinct points of the embedded manifold touch.

Strikingly, it is the differential equations of (i) which, in the super-geometric situation below, translate to the equations of motion of super  $p$ -branes — this is the phenomenon of interest here. But no global constraints (ii) on  $p$ -brane dynamics are meant to be imposed. Therefore “super-embedding approach” is a little bit of a misnomer – what the literature is really concerned with is both weaker and stronger than super-embeddings: weaker because only *super-immersions* are required, and stronger because these immersions are required to “preserve half of the local supersymmetry”, hence to be “ $1/2$ BPS” (e.g. [DEGKS08]).

Therefore we speak of “ $1/2$ BPS super-immersions” (Def. 2.19 below, see Rem. 2.23 for relating back to the “super-embedding” terminology).

**Darboux co-frames for immersions.** We observe in §3 that what in the super- $p$ -brane literature came to be known as the “super-embedding condition” is what in classical differential geometry is known as the characterization of *Darboux coframes* adapted to immersions (43). Therefore we here first dwell a little on Darboux coframes over ordinary manifolds. The following Def. 2.12 of *Darboux co-frames* may be found in [St64, p. 246 (2.11)][GH79, (1.13)][Za88, p. 426][MRS12, Def. 1.17][Gi20, §3]; it is the evident higher-dimensional generalization of É. Cartan’s characterization of embedded surfaces by adapted coframes (cf. [Cartan26, p. 211]) and the evident dualization of the notion of *Darboux frames* [St64, p. 244 Def. 2.1][GH79, (1.12)][BBG83, p. 818], which in turn are the evident higher-dimensional generalization of the original Darboux frames used in the differential geometry of curves and surfaces embedded into Euclidean 3-space (e.g. [Gu77, p. 210][PB20, p. 107]).

**Notation 2.11 (Tangential and transversal components).** Given an immersion  $\phi : \Sigma \hookrightarrow X$  of smooth manifolds of dimensions  $1 + p \leq 1 + d \in \mathbb{N}$ , respectively, we write

$$P : \mathbb{R}^{1+d} \twoheadrightarrow \mathbb{R}^{1+p} \hookrightarrow \mathbb{R}^{1,d} \quad \text{Tangential projector} \quad (44)$$

for the linear projector onto the first  $1 + p$  coordinate axes in the corresponding local model space, and

$$\bar{P} : \mathbb{R}^{1+d} \twoheadrightarrow \mathbb{R}^{d-p} \hookrightarrow \mathbb{R}^{1,d} \quad \text{Transversal projector} \quad (45)$$

for the complementary projector onto the last  $d - p$  coordinate axes.

Given moreover a co-frame field  $T\tilde{X} \xrightarrow{E} \mathbb{R}^{1+d}$  (Def. 2.2) and a lift  $\tilde{\phi} : \tilde{\Sigma} \rightarrow \tilde{X}$  (Rem. 2.9) we denote by  $e := P \circ E \circ d\tilde{\phi}$  the pullback of  $E$  along  $\tilde{\phi}$  to  $\tilde{\Sigma}$ , post-composed with the projection operator (44)

$$e := P \circ E \circ d\tilde{\phi} : T\tilde{\Sigma} \xrightarrow{d\tilde{\phi}} T\tilde{X} \xrightarrow{E} \mathbb{R}^{1+d} \xrightarrow{P} \mathbb{R}^{1+p} \hookrightarrow \mathbb{R}^{1+d}. \quad (46)$$



Notationally, this means that  $e$  may still be regarded as carrying an index ranging through both tangential and transverse directions, while it just happens to vanish on all transverse indices:

$$e^a = \begin{cases} \phi^* E^a & \text{for tangential } a, \\ 0 & \text{for transversal } a. \end{cases}$$

This terminology is adapted to the following situation:

**Definition 2.12 (Darboux co-frame fields).** For  $(X, ds^2)$  a smooth (pseudo-)Riemannian manifold and  $\phi : \Sigma \rightarrow X$  an immersion (43) of a smooth manifold  $\Sigma$ , then an orthonormal co-frame field  $E$  (Def. 2.5) is called *adapted* or *Darboux* for  $\phi$  if, in the terminology of Ntn. 2.11

$$\phi^* E^a = 0 \quad \text{for transversal } a \quad \Leftrightarrow \quad \phi^* \bar{P}E = 0. \quad (47)$$

**Remark 2.13 (Coframe field implied by Darboux condition).** Due to the split short exact sequence of vector spaces

$$0 \longrightarrow \mathbb{R}^{1+p} \xleftarrow{P} \mathbb{R}^{1+d} \xrightarrow{\bar{P}} \mathbb{R}^{d-p} \longrightarrow 0$$

the Darboux-condition (47) implies that the projected pullback  $e$  of  $E$  (46) is a co-frame field on  $\Sigma$  (cf. [GH79, (1.13)]):

$$\begin{array}{c} \forall_{\sigma \in \tilde{\Sigma}} \quad \begin{array}{c} \begin{array}{c} \xrightarrow{e = \phi^* P E} \mathbb{R}^{1+p} \\ \sim \\ T_{\sigma} \tilde{\Sigma} \xrightarrow{d\tilde{\phi}} T_{\phi(\sigma)} \tilde{X} \xrightarrow{\sim} \mathbb{R}^{1+d} \xrightarrow{\sim} \mathbb{R}^{1+p} \times \mathbb{R}^{d-p} \\ \sim \\ \mathbb{R}^{1+p} \xrightarrow{P} \mathbb{R}^{d-p} \\ \sim \\ \mathbb{R}^{d-p} \end{array} \\ \xrightarrow{0 = \phi^* \bar{P} E} \mathbb{R}^{d-p} \end{array} \end{array} \quad (48)$$

Notice that this situation of Darboux co-frames:

- (i) is just what was eventually called the “embedding condition” in the “super-embedding”-literature, cf. [Ba11, (2.6-9)][BaSo23, (5.13-14)] – noticing that this is crucially stronger than just the top part of (48) which was the original “geometrodynamical condition” of [BPSTV95, (2.23)];
- (ii) justifies the terminology “tangential” and “transversal” in Ntn. 2.11, because with a Darboux co-frame given, the co-frame fields  $E^a$  at  $\phi(\Sigma) \subset X$  carrying a tangential or transversal index according to (87) are exactly those which are tangential or transversal to the immersed manifold  $\Sigma$ , respectively.

**Definition 2.14 (Pseudo-Riemannian immersion).** We say that an immersion  $\phi : \Sigma \hookrightarrow X$  into a pseudo-Riemannian manifold  $(X, ds^2)$  is itself *pseudo-Riemannian* if the pullback form  $\phi^* ds^2$  is still a pseudo-Riemannian metric.

**Lemma 2.15 (Existence of Darboux co-frames).** *Given a pseudo-Riemannian immersion  $\phi : \Sigma \hookrightarrow X$  (Def. 2.14) into a pseudo-Riemannian manifold  $(X, ds^2)$ , then a Darboux co-frame field (Def. 2.2) exists.*

*Proof.* On the complement of  $\Sigma$  in  $X$  the Darboux condition is trivial and we may use the construction of general orthonormal co-frame fields from Lem. 2.6. By the argument there, what remains is just to construct a Darboux co-frame locally on open neighborhoods around each point  $\phi(\sigma)$  for  $\sigma \in \Sigma$ .

Now by classical facts: There exists an open neighborhood  $U_\sigma$ ,  $\phi(\sigma) \in U_\sigma \subset X$ , where the immersion  $\phi$  restricts to an embedding of the manifold  $\phi(\Sigma) \cap U$  (e.g. [Bo75, Thm. 4.12]), and there exists a further open neighborhood  $U'_\sigma$ ,  $\phi(\sigma) \in U'_\sigma \subset U_\sigma \subset X$  carrying a “slice chart”  $x_\sigma : U'_\sigma \hookrightarrow \mathbb{R}^{1,d}$  for  $\phi$  that identifies  $\phi(\Sigma) \cap U'$  with a rectilinear hyperplane in an open subset of  $\mathbb{R}^{1,d}$  (e.g. [Lee12, Thm. 5.8]).

This implies that as we apply the Gram-Schmidt process (36) to this slice coordinate frame  $x_\sigma$ , the coefficient matrix  $(E_a^\mu)_{a,\mu \in 0}^d$  is *block-diagonal*, and hence so is its inverse  $(E_\mu^a)_{a,\mu \in 0}^d$  (37). But this means that the corresponding  $E := E_\mu^\bullet dx^\mu$  (38) satisfies the Darboux property (47), since  $(\phi^* E^a)(\partial_\mu) = E_\mu^a$  vanishes when  $a$  and  $\mu$  are not in the same block, with one being transversal and the other tangential.  $\square$

**Second fundamental form.** Now given a pseudo-Riemannian immersion  $\phi : \Sigma \hookrightarrow X$  into a pseudo-Riemannian manifold and an adapted choice of Darboux co-frame field  $E$  on  $X$  (via Lem. 2.15) with respect to some open cover  $\tilde{X} \rightarrow X$ , let

$$\Omega \in \Omega_{\text{dR}}^1(\tilde{X}; \mathfrak{so}(1, d)) \quad \text{with components} \quad (\Omega^{ab} \equiv -\Omega^{ba})_{a,b=0}^d \in \Omega_{\text{dR}}^1(\tilde{X})$$

be the unique torsion-free connection for  $E$ , in that

$$dE^a - \Omega^a_b E^b = 0. \quad (49)$$

Denote the pullback of the tangential and transversal components of this connection, respectively, by:

$$\begin{aligned} \omega^a_b &:= \phi^* \Omega^a_b && \text{for tangential } a \\ &&& \text{and tangential } b, \\ e^{b_1} \Pi^a_{b_1 b_2} &:= \phi^* \Omega^a_{b_2} && \text{for transversal } a \\ &&& \text{and tangential } b_2. \end{aligned} \quad (50)$$

Then the Darboux-condition on  $E$  (48) implies that the pullback of the torsion constraint (49) to  $\Sigma$  is equivalent to the following two equations:

$$\phi^*(dE^a - \Omega^a_b E^b = 0) \Leftrightarrow \begin{cases} de^a - \omega^a_b e^b = 0 & \text{for tangential } a \\ \Pi^a_{b_1 b_2} e^{b_1} e^{b_2} = 0 & \text{for transversal } a. \end{cases} \quad (51)$$

Here the first line just says that  $\omega$  is the torsion-free connection for  $e$  on  $\Sigma$ , while the second line says that

$$\Pi^a_{b_1 b_2} = \Pi^a_{b_2 b_1} \quad (52)$$

is a symmetric tensor on  $\Sigma$ . As such this is historically known as the **second fundamental form** of the immersion  $\phi$  (e.g., [BBG83, p. 819][Ch93, (II.2.12)]).

**Reformulating the Darboux condition.** We now re-formulate the Darboux coframe condition (Def. 2.12) in a form that generalizes naturally to  $1/2$ BPS super-immersions.

**Proposition 2.16 (The Darboux condition reformulated).** *Let  $(X, ds^2)$  be a smooth (pseudo-)Riemannian manifold of dimension  $1 + p$  and  $\phi : \Sigma \rightarrow X$  an immersion (43) of a smooth manifold. Then a relativistic local coframe field  $E : T\tilde{X} \rightarrow \mathbb{R}^{1+d}$  on  $X$  (Def. 2.5) is Darboux for  $\phi$  (Def. 2.12) if and only if there exists*

$$\text{Sh} \in C^\infty(\tilde{\Sigma}; \text{Hom}_{\text{Vect}}(P(\mathbb{R}^{1+d}), \bar{P}(\mathbb{R}^{1+d}))), \quad P, \bar{P} \text{ as in Ntn. 2.11}$$

such that

(a)  $\phi^*(PE')$  is a relativistic local coframe field on  $\Sigma$  (Def. 2.2),

(b)  $\phi^*(\bar{P}E') = \text{Sh} \cdot \phi^*(PE')$ ,

for all local coframe fields  $E'$  on  $X$  that are in the same transversal gauge-orbit as  $E$ :

$$E' = U \cdot E, \quad \text{for } U \in C^\infty(\tilde{X}; \text{O}(\bar{P}\mathbb{R}^{1+d})).$$

This is an elementary argument, and yet the implications are somewhat profound (cf. Rem. 2.17 below):

*Proof.* Noticing that by assumption that

$$P \circ U = P \quad \text{and} \quad \bar{P} \circ U = U \circ \bar{P}, \quad (53)$$

the key point is that the second condition equivalently says that  $\text{Sh}$  takes values in  $\text{O}(\bar{P}(\mathbb{R}^{1+p}))$ -invariant maps:

$$\begin{aligned} \phi^*(\bar{P}UE) &= \text{Sh} \cdot \phi^*(PUE) \\ \Leftrightarrow \phi^*(U\bar{P}E) &= \text{Sh} \cdot \phi^*(PE) && \text{by (53)} \\ \Leftrightarrow \phi^*(\bar{P}E) &= \phi^*(U)^{-1} \cdot \text{Sh} \cdot \phi^*(PE). \end{aligned}$$

But since the only fixed point of  $\text{O}(\bar{P}\mathbb{R}^{1+p})$  is the origin  $0 \in \bar{P}\mathbb{R}^{1+d}$  this implies that

$$\text{Sh} = 0, \quad (54)$$

whereby the second condition above is equivalently the Darboux condition  $\phi^*(\bar{P}E) = 0$  (47), whence the first condition follows by Rem. 2.13.  $\square$

**Remark 2.17 (Outlook on the supergeometric generalization).**

(i) The formulation of the Darboux condition in Prop. 2.16 makes immediate sense also for super-immersion (recalled as Def. 2.18 below), but in this generality the strong implication (54) turns out to be relaxed.

(ii) It is this extra freedom in choosing a *shear map*  $\text{Sh}$  expressing the pullback of the transversal super-coframe in terms of the tangential super-coframe which becomes the source of higher gauge fields on super  $p$ -branes (discussed in §2.2), in particular of the B-field on M5-branes (discussed in §3).

## 2.2 $1/2$ BPS Super-immersions

Now we pass to super-geometry and specifically to super-spacetimes and their (higher) super Cartan geometry. Our notation follows [GSS24a, §2] to which we refer the reader for review, references and further discussion.

**Supergeometric generalization by internalization.** Many differential-geometric concepts generalize straightforwardly to supergeometry, by just interpreting their algebraic formulation verbatim in superalgebra (a general process called “internalization” in category theory). This is the case for instance for the notion of immersions (43):

**Definition 2.18 (Super-immersion, e.g. [Va04, above Thm. 4.4.3]).** A map of smooth super-manifolds  $\phi : \Sigma \rightarrow X$  is an *immersion* if its differential at each point  $\sigma \in \tilde{\Sigma} \hookrightarrow \Sigma$  is an injective map of super-vector spaces

$$T_\sigma \Sigma \xrightarrow{d\phi} T_{\phi(\sigma)} X.$$

**On the general nature of super-Darboux coframe fields.** However, the case of Lorentzian (super-)spacetimes is a little different: The *verbatim* generalization of co-frame structure (Def. 2.2) to supergeometry modeled on  $\mathbb{R}^{1,d|\mathbf{N}}$  would ask for a reduction of the structure group to the ortho-symplectic supergroup

$$\mathrm{OSp}(1, d | \mathbf{N}) \equiv \mathrm{O}(\mathbb{R}^{1,d|\mathbf{N}}) \hookrightarrow \mathrm{GL}(\mathbb{R}^{1,d|\mathbf{N}}).$$

For this notion the above discussion of Darboux co-frames would generalize verbatim. But instead, for Lorentzian super-spacetimes one asks, of course, for *further* reduction to just the Spin-group (the “external automorphisms” of  $\mathbb{R}^{1,d|\mathbf{N}}$ , cf. [HS18, Prop. 6]):

$$\begin{array}{ccccc} \mathrm{Spin}(1, d) & \hookrightarrow & \mathrm{O}(\mathbb{R}^{1,d|\mathbf{N}}) & \hookrightarrow & \mathrm{GL}(\mathbb{R}^{1,d|\mathbf{N}}) \\ \text{Spin-group} & & \text{ortho(-symplectic)} & & \text{general-linear} \\ & & \text{super-group} & & \text{super-group} \end{array} \quad (55)$$

which means that one is now dealing with co-frames for stronger  $G$ -structures. Therefore, the general existence proof (Prop. 2.15) for Darboux coframe fields does not pass to super-immersions into super-spacetimes.

**BPS Super-immersions.** Instead, the existence of Darboux coframes now becomes a *condition* on the super-immersion. This is essentially the condition known in the literature as “super-embedding” (cf. Rem. f2.23). Since it is not really about embeddings but about immersions (by Rem. 2.10), and here specifically those that preserve “half of the local supersymmetry”, and since we will streamline the definition a little, we shall instead speak of  *$1/2$ BPS super-immersions*.

To that end, consider

(i)  $X$  a super-spacetime (cf. [GSS24a, §2.2.2]) locally modeled on a Minkowski super-space  $\mathbb{R}^{1,d|\mathbf{N}}$  for a real  $\mathrm{Pin}(1, d)$ -representation  $\mathbf{N}$  with canonical Clifford generators  $(\Gamma_a : \mathbf{N} \rightarrow \mathbf{N})_{a=0}^d$ ,

(ii)  $p \leq d$  such that

$$P := \frac{1}{2}(1 + \Gamma_{p+1} \cdot \Gamma_{p+2} \cdots \Gamma_d) : \mathbb{R}^{1,d|\mathbf{N}} \longrightarrow \mathbb{R}^{1,d|\mathbf{N}} \quad (56)$$

is a projector ( $P \circ P = P$ ) with complementary projector denoted  $\bar{P} := 1 - P$ ,

(iii)  $\Sigma$  a super-manifold locally modeled on  $\mathbb{R}^{1,p|P(\mathbf{N})}$ .

and notice that then the action of  $\mathrm{Spin}(d-p) \hookrightarrow \mathrm{Spin}(1, p) \times \mathrm{Spin}(d-p) \hookrightarrow \mathrm{Spin}(1+d)$  on  $\mathbf{N}$  evidently commutes with  $P$  and with  $\bar{P}$ , which allows to regard

$$P(\mathbf{N}), \bar{P}(\mathbf{N}) \in \mathrm{Rep}_{\mathbb{R}}(\mathrm{Spin}(d-p)). \quad (57)$$

**Definition 2.19 ( $1/2$ BPS super-immersion).** In the above situation, we call a super immersion  $\phi : \Sigma \hookrightarrow X$  (Def. 2.18) a  *$1/2$ BPS immersion* if it admits the super-analog of a Darboux co-frame field in the form Prop. 2.16, namely if there exists an orthonormal super co-frame field  $(E, \Psi)$  on  $X$  which is<sup>6</sup> *super-Darboux* for  $\phi$  in that there is a “super-shear map”

$$\mathrm{Sh} \in C^\infty\left(\tilde{\Sigma}; \mathrm{Hom}_{\mathbb{R}}(P(\mathbb{R}^{1,d|\mathbf{N}}), \bar{P}(\mathbb{R}^{1,d|\mathbf{N}}))\right) \quad (58)$$

such that

$$\text{(a)} \quad (e', \psi') := \phi^*(P(E', \Psi')) \quad \text{is a local super co-frame field on } \Sigma \quad (59)$$

$$\text{(b)} \quad \phi^*(\bar{P}(E', \Psi')) = \mathrm{Sh} \cdot \phi^*(P(E', \Psi')) \equiv \mathrm{Sh} \cdot (e', \psi'). \quad (60)$$

for all super-coframe fields  $(E', \Psi')$  in the same transversal gauge orbit as  $(E, \Psi)$ :

$$(E', \Psi') = U \cdot (E, \Psi), \quad \text{for } U \in C^\infty(\tilde{X}; \mathrm{Spin}(d-p)). \quad (61)$$

<sup>6</sup>Beware that, by the discussion around (55), a choice of such super Darboux co-frames is, even locally, more than just a choice of Lorentz- (i.e.: Spin-)gauge: In contrast to the bosonic situation, not every local super-coframe field need to be Spin-gauge equivalent to a super-Darboux coframe field on super-spacetime.

In supergeometric generalization of Prop. 2.16, we may re-cast the above super-Darboux condition as follows:

**Lemma 2.20 (Reformulation of super-Darboux condition).** *The condition (60) on a super-shear map Sh (58) is equivalently its  $\text{Spin}(d-p)$ -equivariance*

$$\phi^*(\bar{P}(E', \Psi')) = \text{Sh} \cdot \phi^*(P(E', \Psi')) \quad \Leftrightarrow \quad \phi^*(U) \cdot \text{Sh} = \text{Sh} \cdot \phi^*(U).$$

*Proof.* Noticing that the transversal spin-action (61) commutes with the projection (56)

$$U \circ P = P \circ U, \quad U \circ \bar{P} = \bar{P} \circ U \quad (62)$$

as well as with pullback to the worldvolume, in that

$$\phi^*(U \cdot (-)) = \phi^*(U) \cdot \phi^*(-) \quad \text{i.e.:} \quad \begin{array}{ccc} T\tilde{\Sigma} & \xrightarrow{(p_{T\tilde{\Sigma}}, \phi^*(E, \Psi))} & \tilde{\Sigma} \times \mathbb{R}^{1, d|\mathbf{N}} \\ \downarrow d\tilde{\phi} & & \downarrow \phi \times \text{id} \\ T\tilde{X} & \xrightarrow{(p_{T\tilde{X}}, (E, \Psi))} & \tilde{X} \times \mathbb{R}^{1, d|\mathbf{N}} \xrightarrow{U} \mathbb{R}^{1, d|\mathbf{N}}, \end{array} \quad (63)$$

we have the following sequence of logical equivalences:

$$\begin{aligned} & \phi^*(\bar{P}(E', \Psi')) = \text{Sh} \cdot \phi^*(P(E', \Psi')) \\ \Leftrightarrow & \phi^*(\bar{P}U(E, \Psi)) = \text{Sh} \cdot \phi^*(PU(E, \Psi)) && \text{by (61)} \\ \Leftrightarrow & \phi^*(U\bar{P}(E, \Psi)) = \text{Sh} \cdot \phi^*(UP(E, \Psi)) && \text{by (62)} \\ \Leftrightarrow & \phi^*(U) \cdot \phi^*(\bar{P}(E, \Psi)) = \text{Sh} \cdot \phi^*(U) \cdot \phi^*(P(E, \Psi)) && \text{by (63)} \\ \Leftrightarrow & \phi^*(U) \cdot \text{Sh} \cdot \phi^*(P(E, \Psi)) = \text{Sh} \cdot \phi^*(U) \cdot \phi^*(P(E, \Psi)) && \text{by (61)} \\ \Leftrightarrow & \phi^*(U) \cdot \text{Sh} = \text{Sh} \cdot \phi^*(U) && \text{by (59)}. \end{aligned} \quad \square$$

It follows that most components of a super-shear map vanish identically – as in the bosonic case (54) – but, remarkably, the odd-odd component may be non-trivial:

**Proposition 2.21 (Components of  $1/2$ BPS immersions).** *A super-immersion  $\phi : \Sigma^{1+p} \rightarrow X^{1+d}$  is a  $1/2$ BPS immersion (Def. 2.19) if and only if the pullback of any super-Darboux coframe field  $(E, \Psi)$  is of the form*

$$\left. \begin{array}{l} \phi^*(PE) = e \quad \phi^*(\bar{P}E) = 0 \\ \phi^*(P\Psi) = \psi \quad \phi^*(\bar{P}\Psi) = \text{Sh}_{11} \cdot \psi \end{array} \right\} \Leftrightarrow \left\{ \begin{array}{l} \phi^*E = e \\ \phi^*\Psi = \psi + \text{Sh}_{11} \cdot \psi, \end{array} \right. \quad (64)$$

for some

$$\text{Sh}_{11} \in C^\infty(\tilde{\Sigma}; \text{Hom}_{\text{Rep}_{\mathbb{R}}(\text{Spin}(d-p))}(P\mathbf{N}, \bar{P}\mathbf{N})). \quad (65)$$

*Proof.* Since  $(e, \psi) := \phi^*(E, \Psi)$  is a super-coframe field by assumption (59), the pullback of  $\bar{P}(E, \Psi)$  to  $\tilde{\Sigma}$  may uniquely be expanded in  $(e, \psi)$ :

$$\begin{aligned} \phi^*(\bar{P}E) &= \text{Sh}_{00} \cdot e + \text{Sh}_{01} \cdot \psi \\ \phi^*(\bar{P}\Psi) &= \text{Sh}_{10} \cdot e + \text{Sh}_{11} \cdot \psi, \end{aligned} \quad (66)$$

and by (60) the coefficients are just the components of the super-shear map Sh (58).

Now, by Lem. 2.20, Sh and hence its components are  $\text{Spin}(d-p)$ -equivariant, and as such they map between the following  $\text{Spin}(d-p)$ -representations:

$$\begin{aligned} \text{Sh}_{00} &: (1+p) \longrightarrow (\mathbf{d}-\mathbf{p}) \\ \text{Sh}_{01} &: P(\mathbf{N}) \longrightarrow (\mathbf{d}-\mathbf{p}) \\ \text{Sh}_{10} &: (1+p) \longrightarrow \bar{P}(\mathbf{N}) \\ \text{Sh}_{11} &: P(\mathbf{N}) \longrightarrow \bar{P}(\mathbf{N}). \end{aligned}$$

Here  $(1+p) := P(\mathbb{R}^{1,d})$  denotes the trivial  $\text{Spin}(d-p)$ -representation of dimension  $1+p$ , while  $(\mathbf{d}-\mathbf{p}) := \bar{P}(\mathbb{R}^{1,d})$  denotes the vectorial irrep (via the defining irrep of  $\text{SO}(d-p)$ ), and  $P(\mathbf{N}), \bar{P}(\mathbf{N})$  are regarded as  $\text{Spin}(d-p)$ -representations via (57).

But since these maps are  $\text{Spin}(d-p)$ -equivariant, Schur's lemma (e.g. [Et11, Prop. 1.16]) says that they are trivial between non-isomorphic irrep summands. This manifestly implies that  $\text{Sh}_{00} = 0$ . Similarly, since the  $\text{Spin}(d-p)$ -representations  $P(\mathbf{N})$  and  $\bar{P}(\mathbf{N})$  are spinorial (in that their fixed subspace of  $-1 \in \text{Spin}(d-p)$  is zero) they do not contain a vectorial summand like  $(\mathbf{d} - \mathbf{p})$  (which is fixed by the central element  $-1$ ), also  $\text{Sh}_{01} = 0$  and  $\text{Sh}_{10} = 0$ .  $\square$

**Remark 2.22 (Existence of fermionic shear).** The noteworthy point in Prop. 2.21 is that, in general, the one component  $\text{Sh}_{11}$  in (66) of the super-shear map *need not* vanish, since  $P(\mathbf{N})$  and  $\bar{P}(\mathbf{N})$  may contain the same  $\text{Spin}(d-p)$  irreps. Concretely, we see this below for the example of the M5-brane, where these two representations are in fact isomorphic, cf. (98) below. Remarkably, this freedom in BPS super-immersions is the origin of the worldvolume higher gauge fields, discussed for the M5 in §3.3.

**Remark 2.23 (The “super-embedding”-condition).** In summary, Prop. 2.21 says in particular that a  $1/2$ BPS immersion (Def. 2.19) comes with the following structure:

$$\begin{array}{ccc}
\begin{array}{c} \text{Brane} \\ \text{worldvolume} \\ \text{supermanifold} \end{array} & \Sigma & \xrightarrow[\text{super-immersion}]{\phi} & X & \begin{array}{c} \text{Target} \\ \text{spacetime} \\ \text{supermanifold} \end{array} \\
0 & \xleftarrow{\phi^*} & \bar{P}E & & \begin{array}{c} \text{Transversal part} \\ \text{of bosonic co-frame} \end{array} \\
& & \uparrow (\bar{P}, 0) & & \\
& & \begin{array}{c} \text{Super-Darboux} \\ \text{co-frame field} \end{array} & (E, \Psi) \xleftarrow{U} & (\tilde{E}, \tilde{\Psi}) & \begin{array}{c} \text{Any spacetime} \\ \text{super co-frame} \end{array} \\
& & \downarrow (P, P) & & \\
\begin{array}{c} \text{Worldvolume} \\ \text{super co-frame} \end{array} & (e, \psi) & \xleftarrow{\phi^*} & (PE, P\Psi) & \begin{array}{c} \text{Tangential part} \\ \text{of super-coframe} \end{array}
\end{array} \tag{67}$$

This is what is broadly known as the “super-embedding”-condition, in the literature. Specifically:

- (i) The condition  $\phi^*PE = e$  in (67) is the **basic embedding condition** of [HS97a, (6)][HSW97a, (4)][HRS98, (2)], which earlier was known as the **geometro-dynamical condition** [BPSTV95, (2.23)];
- (ii) With the additional condition  $\phi^*\bar{P}E = 0$  in (67) this is the **superembedding condition** of [So00, (4.36-37)], see also [Ba11, (2.6-9)][BaSo23, (5.13-14)].
- (iii) The further condition  $\phi^*P\Psi = \psi$  in (67) is tacitly introduced in [So00, (4.46)], reviewed in [BaSo23, (5.26)].

In comparing to these references, notice that

- (iv) Our expression  $\phi^*(PU, \bar{P}U) =: u$  corresponds to the **harmonics** in [BPSTV95, §2.1][HSW98, (29)][So00, (4.11)], where  $U \in C^\infty(X; \text{Spin}(1, d))$ .

In closing this section, we just notice that, in addition to the super co-frame field, a super-immersion also pulls back the spin-connection  $\Omega$  on target spacetime:

**Notation 2.24 (Second fundamental super-form).** Given a  $1/2$ BPS super-immersion  $\phi$  (2.19) into a super-spacetime  $X$  with spin connection  $\Omega$ , then in supergeometric generalization of (50) the pullback of  $\Omega$  is uniquely expanded as follows:

$$\begin{aligned}
\omega^a_b & := \phi^*\Omega^a_b && \text{for transversal } a \\
& && \text{and tangential } b \\
e^{b_1}\Pi_{b_1 b_2}^a + \psi^\beta \Pi_{\beta b_2}^a & := \phi^*\Omega^a_{b_2} && \text{for transversal } a \\
& && \text{and tangential } b_2.
\end{aligned} \tag{68}$$

### 3 M5-brane super-immersions

Here we give a streamlined account of the specialization of the “super-embedding”-construction (§2) to the case of the M5-brane (due to [HS97b][So00, §5.2], reviewed in [BaSo23, §5]), focusing on the derivation of the  $H_3$ -flux density (cf. Rem. 3.13) and its Bianchi identity and (non/self-duality) equations of motion (Prop. 3.18) which drive the discussion of flux quantization on the M5 (in §4, as introduced in §1).

Our key move to make the notoriously intricate derivation more transparent is (not to use a matrix representation for the spinors but) to algebraically carve out (in §3.2) the worldvolume spin representation  $2 \cdot \mathbf{8}$  by the same

tangential/transversal projection operators that enter the definition of BPS super-immersions (Def. 2.19) in the first place.

### 3.1 Self-dual tensors in 6d

For reference and completeness, we first briefly record some properties of self-dual tensors in 6d. In this section indices run through  $0, 1, \dots, 5$ .

**Notation 3.1 (Tensors in 6d).**

- $\epsilon_{01\dots 5} = +1$  and  $\epsilon^{01\dots 5} = -1$  as in (27).
- $\tilde{H}_3 := \frac{1}{3!}(\tilde{H}_3)_{a_1 a_2 a_3} e^{a_1} e^{a_2} e^{a_3}$  denotes our generic (self-dual) rank-3 tensor  
The tilde is in order to distinguish this from the flux density  $H_3$  on the M5-brane which is *not* actually self-dual, but “non-linearly self-dual”, see below.
- $\star\tilde{H}_3 := \frac{1}{3!}(\frac{1}{3!}\epsilon_{a_1 a_2 a_3 b_1 b_2 b_3}(\tilde{H}_3)^{b_1 b_2 b_3})e^{a_1}e^{a_2}e^{a_3}$  is the Hodge dual tensor.  
Notice that below we consider this on super-spacetimes, where the Hodge duality operation makes sense in this form (only) for such differential forms with vanishing fermionic frame component ( $\psi^0$ ).  
Hence the self-duality condition is

$$\tilde{H}_3 = \star\tilde{H}_3 \quad \Leftrightarrow \quad (\tilde{H}_3)_{a_1 a_2 a_3} = \frac{1}{3!}\epsilon_{a_1 a_2 a_3 b_1 b_2 b_3}(\tilde{H}_3)^{b_1 b_2 b_3}. \quad (69)$$

- The “square of  $H_3$  on two indices”

$$(\tilde{H}_3^2)_a^b := (\tilde{H}_3)_{a c_1 c_2}(\tilde{H}_3)^{c_1 c_2 b} \quad (70)$$

plays a key role in relating the self-dual tensor  $\tilde{H}_3$  to the actual flux density  $H_3$ .

In the following it is often suggestive to regard it as a matrix, such as to write:

$$(\tilde{H}_3^2 \cdot \tilde{H}_3^2)_a^b := (\tilde{H}_3^2)_a^c(\tilde{H}_3^2)_c^b, \quad \text{tr}(\tilde{H}_3^2) := (\tilde{H}_3^2)_a^a, \quad \text{tr}(\tilde{H}_3^2 \cdot \tilde{H}_3^2) := (\tilde{H}_3^2)_a^b(\tilde{H}_3^2)_b^a. \quad (71)$$

**Lemma 3.2 (Trace of square of selfdual 3-form vanishes).** *If  $\tilde{H}_3 = \star\tilde{H}_3$  then the trace (71) vanishes:*

$$\text{tr}(\tilde{H}_3^2) = 0 \quad \text{in that} \quad (\tilde{H}_3)_{a_1 a_2 a_3}(\tilde{H}_3)^{a_1 a_2 a_3} = 0. \quad (72)$$

*Proof.*

$$\begin{aligned} (\tilde{H}_3)_{a_1 a_2 a_3}(\tilde{H}_3)^{a_1 a_2 a_3} &= \frac{1}{3!}(\tilde{H}_3)_{a_1 a_2 a_3} \epsilon^{a_1 a_2 a_3 b_1 b_2 b_3}(\tilde{H}_3)_{b_1 b_2 b_3} && \text{by (69)} \\ &= -\frac{1}{3!}(\tilde{H}_3)_{b_1 b_2 b_3} \epsilon^{b_1 b_2 b_3 a_1 a_2 a_3}(\tilde{H}_3)_{a_1 a_2 a_3} \\ &= -(\tilde{H}_3)_{a_1 a_2 a_3}(\tilde{H}_3)^{a_1 a_2 a_3} && \text{by (69)}. \end{aligned} \quad \square$$

**Lemma 3.3 (Squaring over a single index).** *If  $\tilde{H}_3 = \star\tilde{H}_3$  then (cf. [HSW97b, (9)]):*

$$(\tilde{H}_3)_{a_1 a_2 c}(\tilde{H}_3)^{c b_1 b_2} = +\delta_{[a_1}^{[b_1}(\tilde{H}_3)_{a_2]}^{b_2]}. \quad (73)$$

*Proof.*

$$\begin{aligned} &(\tilde{H}_3)_{a_1 a_2 c}(\tilde{H}_3)^{c b_1 b_2} \\ &= \left(\frac{1}{3!}\epsilon_{a_1 a_2 c e_1 e_2 e_3}(\tilde{H}_3)^{e_1 e_2 e_3}\right)\left(\frac{1}{3!}\epsilon^{c b_1 b_2 d_1 d_2 d_3}(\tilde{H}_3)_{d_1 d_2 d_3}\right) && \text{by (69)} \\ &= \frac{-5!}{3! \cdot 3!}\delta_{a_1 a_2 e_1 e_2 e_3}^{b_1 b_2 d_1 d_2 d_3}(\tilde{H}_3)^{e_1 e_2 e_3}(\tilde{H}_3)_{d_1 d_2 d_3} && \text{by (28)} \\ &= \frac{+5!}{3! \cdot 3!}\frac{6 \cdot 2! \cdot 3!}{5!}\delta_{[a_1 e_1] a_2] e_2 e_3}^{b_1 b_2 d_1 d_2 d_3}(\tilde{H}_3)^{e_1 e_2 e_3}(\tilde{H}_3)_{d_1 d_2 d_3} + \frac{-5!}{3! \cdot 3!}\frac{3 \cdot 2! \cdot 3!}{5!}\delta_{e_1 e_2}^{b_1 b_2}\delta_{a_1 a_2 e_3}^{d_1 d_2 d_3}(\tilde{H}_3)^{e_1 e_2 e_3}(\tilde{H}_3)_{d_1 d_2 d_3} && \text{by (72)} \\ &= 2\delta_{[a_1}^{[b_1}(\tilde{H}_3)_{a_2]}^{b_2]e_2 e_3}(\tilde{H}_3)_{a_2]e_2 e_3} - (\tilde{H}_3)^{b_1 b_2 e_3}(\tilde{H}_3)_{a_1 a_2 e_3}. \end{aligned} \quad \square$$

**Lemma 3.4 (Square of square is proportional to identity).** *If  $\tilde{H}_3 = \star\tilde{H}_3$  then its squared square (71) is (cf. [HSW97b, (8)]):*

$$\tilde{H}_3^2 \cdot \tilde{H}_3^2 = \frac{1}{6}\text{tr}(\tilde{H}_3^2 \cdot \tilde{H}_3^2)\text{id} \quad \text{in that} \quad (\tilde{H}_3^2)_a^c(\tilde{H}_3^2)_c^b = \frac{1}{6}\delta_a^b(\tilde{H}_3^2)_{c_1}^{c_2}(\tilde{H}_3^2)_{c_2}^{c_1}. \quad (74)$$



*Proof.*

$$\begin{aligned}
(\tilde{H}_3^2)_a^c (\tilde{H}_3^2)_c^b &= (\tilde{H}_3)_{a d_1 d_2} (\tilde{H}_3)^{d_1 d_2 c} (\tilde{H}_3)_{c e_1 e_2} (\tilde{H}_3)^{e_1 e_2 b} && \text{by def.} \\
&= (\tilde{H}_3)_{a d_1 d_2} \delta_{e_1}^{d_1} (\tilde{H}_3^2)_{e_2}^{d_2} (\tilde{H}_3)^{e_1 e_2 b} && \text{by (73)} \\
&= (\tilde{H}_3)_{a d_1 d_2} (\tilde{H}_3)^{d_1 e_2 b} (\tilde{H}_3^2)_{e_2}^{d_2} \\
&= -\delta_{[a}^{[e_2} (\tilde{H}_3^2)_{d_2]}^b (\tilde{H}_3^2)_{e_2}^{d_2} && \text{by (73)} \\
&= -\frac{1}{4} \delta_a^{e_2} (\tilde{H}_3^2)_{d_2}^b (\tilde{H}_3^2)_{e_2}^{d_2} + \frac{1}{4} \delta_a^b (\tilde{H}_3^2)_{d_2}^{e_2} (\tilde{H}_3^2)_{e_2}^{d_2} + \frac{1}{4} \delta_{d_2}^{e_2} (\tilde{H}_3^2)_a^b (\tilde{H}_3^2)_{e_2}^{d_2} - \frac{1}{4} \delta_{d_2}^b (\tilde{H}_3^2)_a^{e_2} (\tilde{H}_3^2)_{e_2}^{d_2} \\
&= -\frac{1}{4} (\tilde{H}_3^2)_a^c (\tilde{H}_3^2)_c^b + \frac{1}{4} \delta_a^b \text{tr}(\tilde{H}_3^2 \tilde{H}_3^2) + \frac{1}{4} (\tilde{H}_3^2)_a^b \underbrace{(\tilde{H}_3^2)_{e_2}^{e_2}}_{\substack{= 0 \\ (72)}} - \frac{1}{4} (\tilde{H}_3^2)_a^c (\tilde{H}_3^2)_c^b.
\end{aligned}$$

**Lemma 3.5 (Inverse of identity minus square).** *If  $\tilde{H}_3 = \star \tilde{H}_3$  and  $\text{tr}(\tilde{H}_3^2 \cdot \tilde{H}_3^2)$  (74) satisfies the non-criticality condition*

$$\text{tr}(\tilde{H}_3^2 \cdot \tilde{H}_3^2) \neq \frac{3}{2} \quad (75)$$

then (cf. [HSW97b, (10)]) the matrices  $(\text{id} \mp 2\tilde{H}_3^2)$  (70) are invertible <sup>7</sup>, with inverse:

$$(\text{id} \mp 2\tilde{H}_3^2)^{-1} = \frac{1}{1 - \frac{2}{3} \text{tr}(\tilde{H}_3^2 \cdot \tilde{H}_3^2)} (\text{id} \pm 2\tilde{H}_3^2). \quad (76)$$

*Proof.*

$$\begin{aligned}
(\text{id} \mp 2\tilde{H}_3^2) \cdot (\text{id} \pm 2\tilde{H}_3^2) &= \text{id} - 4\tilde{H}_3^2 \cdot \tilde{H}_3^2 \\
&= \left(1 - \frac{2}{3} \text{tr}(\tilde{H}_3^2 \cdot \tilde{H}_3^2)\right) \text{id} \quad \text{by (74)}.
\end{aligned}$$

**Lemma 3.6 (Anti-Selfduality of cubic form).** *If  $\tilde{H}_3 = \star \tilde{H}_3$ , then the skew-symmetric part of the cubic  $(\tilde{H}_3^2)_{a_1}^c (\tilde{H}_3)_{c a_2 a_3}$  (70) is anti-self-dual (cf. [So00, (5.82)]):*

$$(\tilde{H}_3^2)_{[d_1}^c (\tilde{H}_3)_{c|d_2 d_3]} = -\frac{1}{3!} \epsilon_{d_1 d_2 d_3 a_1 a_2 a_3} (\tilde{H}_3^2)^{a_1 c} (\tilde{H}_3)^{c a_2 a_3}. \quad (77)$$

*Proof.*

$$\begin{aligned}
&\frac{1}{3!} \epsilon_{d_1 d_2 d_3 a_1 a_2 a_3} (\tilde{H}_3)^{a_1 b_1 b_2} (\tilde{H}_3)_{b_1 b_2 c} (\tilde{H}_3)^{c a_2 a_3} \\
&= \frac{1}{3!} \epsilon_{d_1 d_2 d_3 a_1 a_2 a_3} (\tilde{H}_3)^{a_1 b_1 b_2} (\tilde{H}_3)_{b_1 b_2 c} \left( \frac{1}{3!} \epsilon^{c a_2 a_3 e_1 e_2 e_3} (\tilde{H}_3)_{e_1 e_2 e_3} \right) \quad \text{by (69)} \\
&= \frac{-2 \cdot 4!}{3! \cdot 3!} (\tilde{H}_3)^{a_1 b_1 b_2} (\tilde{H}_3)_{b_1 b_2 c} \left( \delta_{d_1 d_2 d_3 a_1}^{c e_1 e_2 e_3} (\tilde{H}_3)_{e_1 e_2 e_3} \right) \quad \text{by (28)} \\
&= \frac{-2 \cdot 4!}{3! \cdot 3!} \frac{3!}{4!} (\tilde{H}_3)^{a_1 b_1 b_2} (\tilde{H}_3)_{b_1 b_2 c} \left( \delta_{a_1}^{e_1} \delta_{d_1 d_2 d_2}^{c e_2 e_3} (\tilde{H}_3)_{e_1 e_2 e_3} \right) \quad \text{by (72)} \\
&= \frac{-2 \cdot 4!}{3! \cdot 3!} \frac{3!}{4!} 3 (\tilde{H}_3)^{a_1 b_1 b_2} (\tilde{H}_3)_{b_1 b_2 c} \left( \delta_{a_1}^{e_1} \delta_{[d_1}^c \delta_{d_2 d_3]}^{e_2 e_3} (\tilde{H}_3)_{e_1 e_2 e_3} \right) \\
&= \frac{-2 \cdot 4!}{3! \cdot 3!} \frac{3!}{4!} 3 (\tilde{H}_3)^{e_1 b_1 b_2} (\tilde{H}_3)_{b_1 b_2 [d_1} (\tilde{H}_3)_{e_1 | d_2 d_3]} \quad \text{by (28)} \\
&= -(\tilde{H}_3)_{[d_1 | b_1 b_2} (\tilde{H}_3)^{b_1 b_2 e_1} (\tilde{H}_3)_{e_1 | d_2 d_3]}.
\end{aligned}$$

## 3.2 Spinors in 6d from 11d

Instead of using a matrix representation for the Clifford algebra on the 5-brane, for our proofs in §3.3 it is key to algebraically characterize the worldvolume spin representation  $2 \cdot \mathbf{8}_+ \simeq P(\mathbf{32}) \simeq 4 \cdot \mathbf{4}$  (see (98)) as the fixed locus  $P(\mathbf{32})$  inside the target spin representation  $\mathbf{32}$  in 11d. Here we spell out how this works.

**Spinors in 11d.** For reference, we begin with briefly recalling the following standard facts (proofs and references may be found in [GSS24a, §2.2.1][HSS19, §A]): There exists an  $\mathbb{R}$ -linear representation  $\mathbf{32}$  of  $\text{Pin}^+(1, 10)$  with generators

$$\Gamma_a : \mathbf{32} \rightarrow \mathbf{32} \quad (78)$$

and equipped with a skew-symmetric bilinear form

$$(\overline{(-)})(-) : \mathbf{32} \otimes \mathbf{32} \longrightarrow \mathbb{R} \quad (79)$$

<sup>7</sup>The expression  $(\text{id} + 2\tilde{H}_3^2)_{ab}$  is interpreted [BBdSS00, (8)] as (proportional to) the effective metric on M5-branes that is seen by open M2-branes ending on them, the M-theoretic lift of the ‘‘open string metric’’ on D-branes.



which commute with these  $\text{Spin}(1,5)$ -actions on  $P(\mathbf{32})$  and on  $\overline{P}(\mathbf{32})$ , thus decomposing them according to

$$\begin{aligned} P &= \frac{1}{2}(1 + \Gamma_{6789}) \frac{1}{2}(1 + \Gamma_{5'}) + \frac{1}{2}(1 - \Gamma_{6789}) \frac{1}{2}(1 - \Gamma_{5'}) \\ \overline{P} &= \frac{1}{2}(1 - \Gamma_{6789}) \frac{1}{2}(1 + \Gamma_{5'}) + \frac{1}{2}(1 + \Gamma_{6789}) \frac{1}{2}(1 - \Gamma_{5'}), \end{aligned}$$

each into a pair of isomorphic summands, whose isomorphism is given by acting for instance with  $\Gamma_6$ :

$$\begin{aligned} \Gamma_6 \frac{1}{2}(1 + \Gamma_{6789}) \frac{1}{2}(1 + \Gamma_{5'}) &= \frac{1}{2}(1 - \Gamma_{6789}) \frac{1}{2}(1 - \Gamma_{5'}) \Gamma_6 \\ \Gamma_6 \frac{1}{2}(1 - \Gamma_{6789}) \frac{1}{2}(1 + \Gamma_{5'}) &= \frac{1}{2}(1 + \Gamma_{6789}) \frac{1}{2}(1 - \Gamma_{5'}) \Gamma_6. \end{aligned}$$

In conclusion this exhibits (cf. e.g. [HSS19, Lem. 4.12]) the irrep decomposition

$$P(\mathbf{32}) \underset{\text{Spin}(1,5)}{\simeq} 2 \cdot \mathbf{8}_+, \quad \overline{P}(\mathbf{32}) \underset{\text{Spin}(1,5)}{\simeq} 2 \cdot \mathbf{8}_- \quad \in \text{Rep}_{\mathbb{R}}(\text{Spin}(1,5)) \quad (91)$$

with respect to the tangential Clifford generators  $\Gamma_0, \Gamma_1, \dots, \Gamma_5 \in \text{Pin}^+(1,10)$ , which as such we denote  $\gamma_0, \dots, \gamma_5$ :

$$\begin{array}{c} \begin{array}{ccc} 2 \cdot \mathbf{8}_+ \underset{\text{Spin}(1,5)}{\simeq} P(\mathbf{32}) & & P(\mathbf{32}) \underset{\text{Spin}(1,5)}{\simeq} 2 \cdot \mathbf{8}_+ \\ \oplus & \oplus & \oplus \\ \oplus & \oplus & \oplus \end{array} \\ \gamma_a : \quad \begin{array}{ccc} \oplus & \oplus & \oplus \\ \oplus & \oplus & \oplus \end{array} \end{array} \begin{array}{c} \nearrow \\ \Gamma_a \\ \searrow \end{array} \begin{array}{ccc} P(\mathbf{32}) \underset{\text{Spin}(1,5)}{\simeq} 2 \cdot \mathbf{8}_+ & & \\ \oplus & \oplus & \\ \oplus & \oplus & \oplus \\ \overline{P}(\mathbf{32}) \underset{\text{Spin}(1,5)}{\simeq} 2 \cdot \mathbf{8}_- & & \end{array} \quad \text{for tangential } a. \quad (92)$$

With (90) this implies that the projection operators (88) (89) also serve to project out these tangential Clifford generators:

$$\overline{P} \Gamma^a P = \begin{cases} \gamma^a|_{2 \cdot \mathbf{8}_+} & \text{for tangential } a \\ 0 & \text{for transversal } a, \end{cases} \quad P \Gamma^a \overline{P} = \begin{cases} \gamma^a|_{2 \cdot \mathbf{8}_-} & \text{for tangential } a \\ 0 & \text{for transversal } a. \end{cases} \quad (93)$$

Therefore we may think of  $P$  as also acting on  $\mathbb{R}^{1,10}$  by projection to  $\mathbb{R}^{1,5}$ , hence as acting on all of the super-vector space  $\mathbb{R}^{1,10|\mathbf{32}}$

$$\begin{array}{c} \mathbb{R}^{1,10|\mathbf{32}} \longrightarrow \mathbb{R}^{1,5|2 \cdot \mathbf{8}} \longleftarrow \mathbb{R}^{1,10|\mathbf{32}} \\ \underbrace{\hspace{10em}}_P \quad \uparrow \end{array} \quad (94)$$

Below we make much use of this super-projector (94) for streamlined definitions and computations.

A simple example that will be useful below:

**Example 3.7.** It follows immediately from (85) that  $P(\mathbf{32})$  inherits *symmetric* bilinear spinor pairings such as

$$\left( (2 \cdot \mathbf{8}_+) \otimes (2 \cdot \mathbf{8}_+) \right)_{\text{sym}} \longleftarrow (\mathbf{32} \otimes \mathbf{32})_{\text{sym}} \xrightarrow{(\overline{(-)} \gamma^a \Gamma^b (-))} \mathbb{R} \quad \text{for tangential } a, \text{ transversal } b,$$

so that, notably, the polarization identity implies that

$$\forall_{\psi \in P(\mathbf{32})} \left( \overline{\psi} \gamma^a \Gamma^b \psi \right) (H_1)_a = 0 \quad \Leftrightarrow \quad H_1 = 0, \quad (95)$$

which we need below in (118).

On the other hand, the corresponding symmetric pairing with two tangential indices vanishes identically

$$\psi_1, \psi_2 \in P(\mathbf{32}) \quad \Rightarrow \quad \left( \overline{\psi_1} \gamma_{a_1 a_2} \psi_2 \right) = 0, \quad (96)$$

because

$$\left( \overline{\psi_1} \gamma_{a_1 a_2} \psi_2 \right) = \left( \overline{P \psi_1} \gamma_{a_1 a_2} P \psi_2 \right) = \left( \overline{\psi_1} \overline{P} \gamma_{a_1 a_2} P \psi_2 \right) = \left( \overline{\psi_1} \gamma_{a_1 a_2} \overline{P} P \psi_2 \right) = 0.$$

**Residual  $\text{Spin}(5)$ -action.** Moreover, the fact that the transverse Clifford elements commute with  $P$  and  $\overline{P}$  (90) immediately implies that  $P(\mathbf{32})$  and  $\overline{P}(\mathbf{32})$  also inherit an action of the transverse  $\text{Spin}(5) \hookrightarrow \text{Pin}^+(1,10)$  with respect to the direct product subgroup inclusion  $\text{Spin}(1,5) \times \text{Spin}(5) \hookrightarrow \text{Pin}^+(1,10)$ , in fact as  $\text{Spin}(5)$ -representations they are isomorphic, for instance via multiplication by  $\Gamma_0$  (or any other of the tangential  $\Gamma_{a \leq 5}$ )

$$\begin{array}{ccc} \text{Spin}(5) & & \text{Spin}(5) \\ \curvearrowright & & \curvearrowright \\ P(\mathbf{32}) & \xrightarrow{\sim} & \overline{P}(\mathbf{32}) \\ P\Psi & \xrightarrow{\Gamma_0 \cdot (-)} & \overline{P} \gamma^0 \Psi \end{array}$$

Moreover, as a  $\text{Spin}(5)$ -representation,  $P(\mathbf{32})$  now decomposes into representations in the images of the four mutually orthogonal projectors

$$P_{\sigma_1 \sigma_2} := \frac{1}{2}(1 + \sigma_1 \Gamma_{01}) \frac{1}{2}(1 + \sigma_2 \Gamma_{2345}), \quad \sigma_i \in \{\pm 1\}.$$

These are all isomorphic to each other, for instance via

$$\begin{aligned}\Gamma_1 P_{\sigma_1, \sigma_2} &= P_{-\sigma_1, \sigma_2} \Gamma_1, \\ \Gamma_2 P_{\sigma_1, \sigma_2} &= P_{\sigma_1, -\sigma_2} \Gamma_2,\end{aligned}$$

and thus to be denoted  $\mathbf{4} \in \text{Rep}_{\mathbb{R}}(\text{Spin}(5))$ :

$$P(\mathbf{32}) \simeq_{\mathbb{R}} (P_{++} + P_{+-} + P_{-+} + P_{--})P(\mathbf{32}) \simeq_{\text{Spin}(5)} 4 \cdot 4.$$

Consequently, we have

$$\begin{aligned}\Gamma_a : \quad & \begin{array}{ccccccc} 4 \cdot 4 \simeq_{\text{Spin}(5)} P(\mathbf{32}) & \xrightarrow{\Gamma_a} & P(\mathbf{32}) \simeq_{\text{Spin}(5)} & 4 \cdot 4 & & & \\ \oplus & & \oplus & & \oplus & & \oplus \end{array} \quad \text{for transverse } a. \\ & \begin{array}{ccccccc} 4 \cdot 4 \simeq_{\text{Spin}(5)} \bar{P}(\mathbf{32}) & \xrightarrow{\Gamma_a} & \bar{P}(\mathbf{32}) \simeq_{\text{Spin}(5)} & 2 \cdot 4 & & & \end{array} \end{aligned} \quad (97)$$

In summary this identifies the  $\text{Spin}(1, 5) \times \text{Spin}(5)$ -action on  $P(\mathbf{32})$  and  $\bar{P}(\mathbf{32})$  as:

$$2 \cdot \mathbf{8}_+ \simeq_{\text{Spin}(1, 5)} P(\mathbf{32}) \simeq_{\text{Spin}(5)} 4 \cdot 4 \simeq_{\text{Spin}(5)} \bar{P}(\mathbf{32}) \simeq_{\text{Spin}(1, 5)} 2 \cdot \mathbf{8}_-. \quad (98)$$

**Hodge duality in 6d.** From the relation  $\Gamma_{0123455'6789} = 1 \in \text{End}_{\mathbb{R}}(\mathbf{32})$  (81) it follows analogously for the tangential Clifford algebra (92) that

$$\gamma_{012345} = 1 \in \text{End}_{\mathbb{R}}(2 \cdot \mathbf{8}), \quad (99)$$

because

$$\begin{aligned}\phi \in 2 \cdot \mathbf{8} \subset \mathbf{32} \quad \Rightarrow \quad & \Gamma_{012345} \phi = \Gamma_{012345} \Gamma_{5'6789} \phi \quad \text{by (91)} \\ & = \phi \quad \text{by (81)}.\end{aligned}$$

in fact

$$\Gamma_{012345} = \Gamma_{012345} \Gamma_{0123455'6789} = \Gamma_{5'6789} \in \text{End}_{\mathbb{R}}(\mathbf{32}).$$

By (99), the Hodge duality relations on the 6d Clifford basis elements are as follows:

$$\begin{aligned}\gamma^{a_1 a_2 a_3 a_4 a_5 a_6} &= + \epsilon^{a_1 a_2 a_3 a_4 a_5 a_6} \mathbf{1} \\ \gamma^{a_1 a_2 a_3 a_4 a_5} &= + \epsilon^{a_1 a_2 a_3 a_4 a_5 b} \gamma_b \\ \gamma^{a_1 a_2 a_3 a_4} &= -\frac{1}{2} \epsilon^{a_1 a_2 a_3 a_4 b_1 b_2} \gamma_{b_1 b_2} \\ \gamma^{a_1 a_2 a_3} &= -\frac{1}{3!} \epsilon^{a_1 a_2 a_3 b_1 b_2 b_3} \gamma_{b_1 b_2 b_3} \\ \gamma^{a_1 a_2} &= +\frac{1}{4!} \epsilon^{a_1 a_2 b_1 b_2 b_3 b_4} \gamma_{b_1 b_2 b_3 b_4} \\ \gamma_{a_1} &= +\frac{1}{5!} \epsilon^{a_1 b_1 b_2 b_3 b_4 b_5} \gamma_{b_1 b_2 b_3 b_4 b_5} \\ \mathbf{1} &= -\frac{1}{6!} \epsilon^{b_1 b_2 b_3 b_4 b_5 b_6} \gamma_{b_1 b_2 b_3 b_4 b_5 b_6}.\end{aligned} \quad (100)$$

**Special Clifford relations in 6d.** From (100) the following Lem. 3.8 and Lem. 3.9 are immediate but of key importance:

**Lemma 3.8 (Self-duality of 3-index coefficients).** *The coefficients of  $\gamma^{a_1 a_2 a_3}$  are being projected onto their self-dual part:*

$$(\tilde{H}_3)_{a_1 a_2 a_3} \gamma^{a_1 a_2 a_3} = \frac{1}{2} \left( (\tilde{H}_3)_{a_1 a_2 a_3} + (\star \tilde{H}_3)_{a_1 a_2 a_3} \right) \gamma^{a_1 a_2 a_3}. \quad (101)$$

*Proof.*

$$\begin{aligned}(\tilde{H}_3)_{a_1 a_2 a_3} \gamma^{a_1 a_2 a_3} &= (\tilde{H}_3)_{a_1 a_2 a_3} \left( \frac{-1}{3!} \epsilon^{a_1 a_2 a_3 b_1 b_2 b_3} \gamma_{b_1 b_2 b_3} \right) \quad \text{by (100)} \\ &= \left( \frac{\pm 1}{3!} \epsilon^{b_1 b_2 b_3 a_1 a_2 a_3} (\tilde{H}_3)_{a_1 a_2 a_3} \right) \gamma_{b_1 b_2 b_3} \\ &= (\star \tilde{H}_3)^{b_1 b_2 b_3} \gamma_{b_1 b_2 b_3}. \quad \square\end{aligned}$$

**Lemma 3.9 (Expanding anti-chiral operators into 6+5d Clifford elements).** *The  $\mathbb{R}$ -vector space of linear maps  $2 \cdot \mathbf{8}_{\pm} \rightarrow 2 \cdot \mathbf{8}_{\mp}$  is spanned by products with any transverse Clifford elements in  $\text{Spin}(5)$  of the tangential 1-index and the self-dual combination of tangential 3-index Clifford elements (92):*

$$\text{Hom}_{\mathbb{R}}(2 \cdot \mathbf{8}_{\pm}, 2 \cdot \mathbf{8}_{\mp}) \simeq \left\langle \gamma_{a_1}, \frac{1}{2} \left( \gamma_{a_1 a_2 a_3} + \frac{1}{3!} \epsilon_{a_1 a_2 a_3 b_1 b_2 b_3} \gamma^{b_1 b_2 b_3} \right) \right\rangle_{a_i \in \{0, 1, \dots, 6\}} \cdot \text{Spin}(5). \quad (102)$$

*Proof.* By (84) any such linear map is the linear combination of  $\text{Pin}^+(1, 10)$ -elements  $\Gamma_{a_1 \dots a_{\leq 5}}$ , and among these appear precisely only those with an odd number of tangential indices, by (92) and (97), where by 6d Hodge duality (100) those with 5 tangential indices and those with anti self-dual combinations of 3-indices may be omitted.  $\square$

The following claim (103) is implicit in [HS97b, p. 2] and explicit in [So00, (5.67)][BaSo23, (5.77)] (stated there for a specific matrix representation); we spell out a proof.

**Lemma 3.10 (Conjugating  $\gamma$  with  $H_3$ ).** *If  $\tilde{H}_3 = \star \tilde{H}_3$  then*

$$\left(\frac{1}{3!}(\tilde{H}_3)_{b_1 b_2 b_3} \gamma^{b_1 b_2 b_3}\right) \gamma_a \left(\frac{1}{3!}(\tilde{H}_3)_{c_1 c_2 c_3} \gamma^{c_1 c_2 c_3}\right) = -2(\tilde{H}_3)_{a b_1 b_2} (\tilde{H}_3)^{a' b_1 b_2} \gamma_{a'} \equiv -2(\tilde{H}_3^2)_a^{a'} \gamma_{a'}. \quad (103)$$

*Proof.* First, Gamma-expansion gives

$$\begin{aligned} \left(\frac{1}{3!}(\tilde{H}_3)_{b_1 b_2 b_3} \gamma^{b_1 b_2 b_3}\right) \gamma_a \left(\frac{1}{3!}(\tilde{H}_3)_{c_1 c_2 c_3} \gamma^{c_1 c_2 c_3}\right) &= -(\tilde{H}_3)_{a c_1 c_2} (\tilde{H}_3)^{b c_1 c_2} \gamma_b + \underbrace{\frac{1}{6}(\tilde{H}_3)_{c_1 c_2 c_3} (\tilde{H}_3)^{c_1 c_2 c_3}}_{\stackrel{0}{(72)}} \gamma_a \\ &+ \frac{1}{6}(\tilde{H}_3)_{c_1 c_2 c_3} (\tilde{H}_3)_{a c_4 c_5} \gamma^{c_1 \dots c_5} - \frac{1}{4}(\tilde{H}_3)^{b c_1 c_2} (\tilde{H}_3)_{b c_3 c_4} \gamma_{a c_1 \dots c_4} \\ &- \underbrace{\frac{1}{2}(\tilde{H}_3)^{b_1 c_1 c_2} (\tilde{H}_3)_{b_2 c_1 c_2}}_{=0} \gamma_{a b_1 b_2}, \end{aligned}$$

where over the braces we noticed terms that vanish for symmetry reasons. Applying (104) to the remaining 5-index terms and then simplifying the coefficients of the only remaining 1-index term yields the claimed result. (A computer algebra check is available in [Anc].)  $\square$

**Lemma 3.11 (Contraction with  $\gamma$ ).** *If  $\tilde{H}_3 = \star \tilde{H}_3$  then*

$$(\tilde{H}_3)_{a c_4 c_5} \gamma^{c_1 \dots c_5} = \frac{4! \cdot 2!}{3!} (\tilde{H}_3)^{b_1 b_2 b_3} \delta_{b_1 b_2 b_3 a}^{c_1 c_2 c_3 a'} \gamma_{a'} \quad (104)$$

*Proof.*

$$\begin{aligned} (\tilde{H}_3)_{a c_4 c_5} \gamma^{c_1 \dots c_5} &= \left(\frac{1}{3!}(\tilde{H}_3)^{b_1 b_2 b_3} \epsilon_{a c_4 c_5 b_1 b_2 b_3}\right) \left(\epsilon^{c_1 c_2 c_3 c_4 c_5 a'} \gamma_{a'}\right) \quad \text{by (100)} \\ &= -\frac{4! \cdot 2!}{3!} (\tilde{H}_3)^{b_1 b_2 b_3} \delta_{a b_1 b_2 b_3}^{c_1 c_2 c_3 a'} \gamma_{a'} \quad \text{by (28)}. \quad \square \end{aligned}$$

### 3.3 Super-flux on M5 immersions

With the above preliminaries in hand we are now ready to work out the characterization of those  $1/2$ BPS super-immersions that correspond to M5-branes.

**Definition 3.12 (M5-brane super-immersion).** Given a super-spacetime  $(X, (E, \Psi, \Omega))$  of super-dimension  $(1, 10) | \mathbf{32}$ , we say that an *M5-brane super-immersion* into  $X$  is a  $1/2$ BPS super-immersion (“super-embedding”, Def. 2.19) of a super-manifold  $\Sigma$  of bosonic dimension  $1 + 5$ , hence (92) of super-dimension  $1 + 5 | 2 \cdot \mathbf{8}$ .

$$\begin{array}{ccc} \text{M5 brane} & \Sigma^{1,5|2 \cdot \mathbf{8}} & \xrightarrow[\text{1/2BPS super-immersion}]{\phi} & X^{1,10|\mathbf{32}} & \text{11d supergravity} \\ \text{super-worldvolume} & & & & \text{super-spacetime} \end{array}$$

**Remark 3.13 (Transversal fermionic shear of M5 super-immersions).** Given an M5 super-immersion  $\phi$  (Def. 3.12) the assumption (67) that  $(e, \psi)$  is a co-frame field on  $\Sigma$  implies (cf. [BaSo23, (5.69)]) that there exist unique components fields  $\tilde{H}$  and  $\tau_a$  on  $\Sigma$  which parametrize the transversal shear of  $\phi$  in the fermionic directions:

$$\phi^* \Psi - \psi = \phi^* (\bar{P} \Psi) = \tilde{H} \psi + \tau_a e^a. \quad (105)$$

These components pointwise map the fermionic tangent space  $T_\sigma^{\text{odd}} \Sigma \cong 2 \cdot \mathbf{8}_+$  of  $\Sigma$  into the transverse target space copy of  $2 \cdot \mathbf{8}_-$ :

$$\begin{array}{ccc} & \xrightarrow[\text{odd shear}]{\phi^* \Psi = (\psi, \tilde{H} \psi + \tau_a e^a)} & \overbrace{2 \cdot \mathbf{8}_+ \oplus 2 \cdot \mathbf{8}_-}^{\mathbf{32}} \\ T_\sigma \Sigma & \xrightarrow[\text{odd co-frame}]{\psi} & 2 \cdot \mathbf{8}_+ \end{array} \quad (106)$$

Notice that as such we may act on  $\psi$  also with transversal Clifford generators, and have with (91):

$$\psi = P(\psi), \quad \tau_a = \bar{P}(\tau_a). \quad (107)$$

Of course, here  $\tilde{H} \equiv \text{Sh}_{11}$  and  $\tau \equiv \text{Sh}_{01}$  are components (66) of the super-shear map (58), and the BPS immersion condition of Def. 2.19 implies (Prop. 2.21) that

$$\tau = 0. \quad (108)$$

However, below we still keep  $\tau$  around, to show where it would appear, cf. Rem. 3.17 and Rem. 3.20 below.

This remaining freedom in (106) of M5 super-immersions  $\phi$  to “shear” along the odd directions by a component  $\check{H}$  turns out to reflect the degrees of freedom of the flux density  $H_3$  on the brane’s worldvolume (cf. (126) in Prop. 3.18 below).

We offer the following two concrete examples of M5-brane super-immersions/embeddings (no such examples seem to exist in the literature). The first is the archetypical example which is simple but instructive, the second is arguably the next-archetypical example and already fairly laborious to construct:

**Example 3.14 (Flat M5-brane immersion).** Consider target space to be flat Minkowski super-spacetime  $X \equiv \mathbb{R}^{1,10|32}$  (or some toroidal compactification thereof) with its canonical coordinate functions  $(X^a)_{a=0}^{10}$  and  $(\theta^\alpha)_{\alpha=1}^{32}$  and co-frame field (e.g. [GSS24a, Ex. 2.76]):

$$\begin{aligned} E^a &:= dX^a + (\bar{\Theta} \Gamma^a d\Theta) \\ \Psi^\alpha &:= d\Theta^\alpha. \end{aligned} \tag{109}$$

Then consider the brane worldvolume to be the sub-supermanifold (94)

$$\Sigma \equiv \mathbb{R}^{1,6|2\cdot 8} := P(\mathbb{R}^{1,10|32}) \hookrightarrow \mathbb{R}^{1,10|32}$$

with canonical coordinate functions  $x := P \circ X$ ,  $\theta := P \circ \Theta$ , and with the super-immersion given by

$$\begin{array}{ccc} \mathbb{R}^{1,6|2\cdot 8} & \xrightarrow{\phi} & \mathbb{R}^{1,10|32} \\ x^a & \xleftarrow{\phi^*} & X^a \\ \theta + \check{H}_3 \cdot \theta & \xleftarrow{\phi^*} & \Theta \end{array} \tag{110}$$

for *constant*

$$(H_3)_{a_1 a_2 a_3} : \Sigma \rightarrow \mathbb{R}, \quad \text{with} \quad \frac{\partial}{\partial x^a} (H_3)_{a_1 a_2 a_3} = 0, \quad \frac{\partial}{\partial \theta^\alpha} (H_3)_{a_1 a_2 a_3} = 0. \tag{111}$$

From this, we find the pullback of the given co-frame field to be

$$\begin{aligned} \phi^* E^a &= \phi^* (dX^a + (\bar{\Theta} \Gamma^a d\Theta)) && \text{by (109)} \\ &= dx^a + ((\bar{\theta} + \check{H}_3 \theta) \Gamma^a d(\theta + \check{H}_3 \theta)) && \text{by (110)} \\ &= \begin{cases} dx^a + (\delta_{a'}^a - 2(\check{H}_3^2)_{a'}) (\bar{\theta} \gamma^{a'} d\theta) & | \text{tangential } a && \text{by (111),} \\ (\bar{\theta} \{ \check{H}_3, \Gamma^a \} d\theta) = 0 & | \text{transversal } a && \text{(90) \& (103)} \end{cases} \end{aligned}$$

and

$$\begin{aligned} \phi^* \Psi &= \phi^* d\Theta && \text{by (109)} \\ &= d(\theta + \check{H}_3 \theta) && \text{by (110)} \\ &= d\theta + \check{H}_3 d\theta && \text{by (111).} \end{aligned}$$

These show, by (64), that  $(E, \Psi)$  (109) is indeed a Darboux super-coframe (Def. 2.19) for this  $\phi$  (110), which is hence indeed an M5-brane super immersion (Def. 3.12).

We also see in this example that the induced torsion on the worldvolume is the canonical super-torsion *plus* a correction by  $\check{H}_3$ :

$$de^a \equiv d\left(dx^a + (\delta_{a'}^a - 2(\check{H}_3^2)_{a'}) (\bar{\theta} \gamma^{a'} d\theta)\right) = (\bar{d}\theta \gamma^a d\theta) - 2(\check{H}_3^2)_{a'} (\bar{d}\theta \gamma^{a'} d\theta).$$

This is a general phenomenon, as we see in (122) below.

**Example 3.15 (Holographic M5-Brane immersion).** The super-immersion of the M5-brane superworldvolume in parallel to the horizon of its own “black” M5-brane super-AdS<sub>7</sub>-geometry turns out to be an M5 super-immersion (hence a super-embedding) according to Def. 3.12, iff its distance from the horizon is exactly the throat radius in Poincaré coordinates. This is already a non-trivial computation which we relegate to [GSS24b].



**The torsion-constraint on M5 super-immersions.** Given a super-immersion  $\phi : \Sigma \rightarrow X$ , the pullback of the bulk torsion constraint to the worldvolume  $\Sigma$  has equivalently the following tangential and transverse components:

$$\begin{aligned} & \phi^* \left( (\overline{\Psi} \Gamma^a \Psi) = d E^a - \Omega^a_b E^b \right) \\ \stackrel{(67)}{\Leftrightarrow} & \begin{cases} \left( (\overline{\phi^* \Psi}) \gamma^a (\phi^* \Psi) \right) = d e^a - \omega^a_b e^b & \text{for tangential } a, \\ \left( (\overline{\phi^* \Psi}) \Gamma^a (\phi^* \Psi) \right) = -\Pi^a_{b_1 b_2} e^{b_1} e^{b_2} - \Pi^a_{\beta b} \psi^\beta e^b & \text{for transversal } a, \end{cases} \end{aligned} \quad (112)$$

where in the second line we made explicit the second fundamental super-form  $\Pi$  from (68).

This constraint (112) is hence a condition to be satisfied by any  $1/2$ BPS super-immersion, and as such we refer to it as the *worldvolume torsion constraint*.

**Lemma 3.16 (The worldvolume torsion constraint in components).** *The transversal worldvolume torsion constraint (112) is equivalent to the following set of conditions:*

(i) *The bosonic component of the 2nd fundamental form  $\Pi$  (68) of  $\phi$  is symmetric in its tangential indices, as in the classical case (52):*

$$\Pi^a_{b_1 b_2} = \Pi^a_{b_2 b_1} \quad \begin{array}{l} \text{for transversal } a \\ \text{and tangential } b_i; \end{array} \quad (113)$$

(ii) *the fermionic shear component  $\tau_b$  (105) is (over-)determined by the equations:*

$$-(\tau_b)_\alpha = \frac{1}{2}(\Gamma_5 \Pi)_{\alpha b}^5 = \frac{1}{2}(\Gamma_6 \Pi)_{\alpha b}^6 = \frac{1}{2}(\Gamma_7 \Pi)_{\alpha b}^7 = \frac{1}{2}(\Gamma_8 \Pi)_{\alpha b}^8 = \frac{1}{2}(\Gamma_9 \Pi)_{\alpha b}^9; \quad (114)$$

(iii) *the fermionic shear component  $\check{H}$  (105) takes the form*

$$\check{H} = \check{H}_3 := \frac{1}{3!}(\check{H}_3)_{a_1 a_2 a_3} \gamma^{a_1 a_2 a_3} \quad \text{for any} \quad \check{H}_3 = \star \tilde{H}_3, \quad (115)$$

with which the tangential part of (112) equivalently says that

(iv) *the induced worldvolume torsion is:*

$$d e^a - \omega^a_b e^b = (\overline{\tau_{b_1}} \gamma^a \tau_{b_2}) e^{b_1} e^{b_2} - 2(\overline{\tau_b} \gamma^a \check{H}_3 \psi) e^b + (\delta_{a'}^a - 2(\check{H}_3^2)_{a'}) (\overline{\psi} \gamma^{a'} \psi), \quad (116)$$

where the notation on the far right is from (70).

*Proof.* The fermionic co-frame components of the transversal torsion constraint are, at face value:

$$\begin{aligned} & \left( (\overline{\phi^* \Psi}) \Gamma^a (\phi^* \Psi) \right) + \Pi^a_{b_1 b_2} e^{b_1} e^{b_2} + \Pi^a_{\beta b} \psi^\beta e^b = 0 \\ \Leftrightarrow & \begin{cases} \left( \overline{(\psi^0)} \left( (\overline{\tau_{b_1}} \Gamma^a \tau_{b_2}) + \Pi^a_{b_1 b_2} \right) e^{b_1} e^{b_2} \right) = 0 \\ \left( \overline{(\psi^1)} \left( 2((\overline{\psi} + \check{H} \psi) \Gamma^a \tau_b) + \psi^\alpha \Pi^a_{\alpha b} \right) e^b \right) = 0 \\ \left( \overline{(\psi^2)} \left( (\overline{(\psi + \check{H} \psi)} \Gamma^a (\psi + \check{H} \psi)) \right) \right) = 0. \end{cases} \end{aligned} \quad (117)$$

We analyze these components in turn:

**The transversal torsion constraint at  $\psi^0$**  Observing that for transversal  $a$  we have

$$\begin{aligned} (\overline{\tau_{b_1}} \Gamma^a \tau_{b_2}) &= (\overline{(\overline{P} \tau_{b_1})} \Gamma^a \overline{P} \tau_{b_2}) \quad \text{by (107)} \\ &= (\overline{\tau_{b_1}} P \Gamma^a \overline{P} \tau_{b_2}) \quad \text{by (82)} \\ &= 0 \quad \text{by (90),} \end{aligned}$$

the  $(\psi^0)$ -component in (117) says equivalently that (cf. [So00, (4.59)]) the 2nd fundamental form is symmetric in its tangential indices,

$$\Pi^a_{[b_1 b_2]} = 0,$$

as in the classical situation (52).

**The transversal torsion constraint at  $\psi^1$**  Observing that the first summand of the  $(\psi^1)$ -component in (117)

is

$$\begin{aligned} \left( \overline{(\psi + \check{H}_3 \psi)} \Gamma^a \tau_b \right) &= (\overline{\psi} \overline{P} (1 + \check{H}_3) \Gamma^a \overline{P} \tau_b) \quad \text{by (107) \& (83)} \\ &= (\overline{\psi} \overline{P} \Gamma^a \overline{P} \tau_b) \quad \text{by (90)} \\ &= (\overline{\psi} \Gamma^a \tau_b) \quad \text{by (107),} \end{aligned}$$

the condition says equivalently that (cf. [So00, (5.63)])

$$2(\overline{\psi} \Gamma^a \tau_b) = -\psi^\alpha \Pi_{\alpha b}^a, \quad \text{hence equivalently that} \quad (\Gamma^a \tau_b)_\alpha = -\frac{1}{2} \Pi_{\alpha b}^a.$$

Acting on this equation with either of the transverse  $\Gamma_a$  shows its equivalence to the claimed equations (114).

**The transversal torsion constraint at  $\psi^2$**  By (102) and the required Spin(5)-equivariance (65), the most general form of  $\check{H}$  is

$$\check{H} = \underbrace{(\check{H}_1)_a \gamma^a}_{\check{H}_1} + \underbrace{\frac{1}{3!} (\check{H}_3)_{a_1 a_2 a_3} \gamma^{a_1 a_2 a_3}}_{\check{H}_3}.$$

With that, the  $(\psi^2)$ -component in (117) equals

$$\begin{aligned} & \left( \overline{(\psi + \check{H}_1 \psi + \check{H}_3 \psi)} \Gamma^a (\psi + \check{H}_1 \psi + \check{H}_3 \psi) \right) && \text{by (105)} \\ & = \left( \overline{\psi} ((1 - \check{H}_1 + \check{H}_3) \Gamma^a (1 + \check{H}_1 + \check{H}_3)) \psi \right) && \text{by (83)} \\ & = \left( \overline{\psi} \overline{P} (1 - \check{H}_1 + \check{H}_3) \Gamma^a (1 + \check{H}_1 + \check{H}_3) P \psi \right) && \text{by (107)}. \end{aligned}$$

Now multiplying out, we obtain:

$$\begin{aligned} & \overline{P} (1 - \check{H}_1 + \check{H}_3) \Gamma^a (1 + \check{H}_1 + \check{H}_3) P \\ & = \overline{P} (1 + \check{H}_3) \Gamma^a (1 + \check{H}_3) P \\ & \quad - \overline{P} \check{H}_1 \Gamma^a (1 + \check{H}_1 + \check{H}_3) P + \overline{P} (1 + \check{H}_1 + \check{H}_3) \Gamma^a \check{H}_1 P \\ & = \overline{P} \left( \Gamma^a + \{ \Gamma^a, \check{H}_3 \} + \check{H}_3 \Gamma^a \check{H}_3 \right) P \\ & \quad + \overline{P} \left( [\check{H}_1, \Gamma^a] - \check{H}_1 \Gamma^a \check{H}_3 + \check{H}_3 \Gamma^a \check{H}_1 \right) P \\ & = \begin{cases} \overline{P} \left( \gamma^a + (\check{H}_3)_{a b_1 b_2} \gamma^{a_1 a_2} + \check{H}_3 \gamma^a \check{H}_3 \right) P + \mathcal{O}(\check{H}_1) & \text{for tangential } a \\ 2 \overline{P} \check{H}_1 P \Gamma^a & \text{for transversal } a \end{cases} \quad \text{by (90)}. \end{aligned} \tag{118}$$

The last line makes it manifest, cf. (95), that the transversal component vanishes iff  $\check{H}_1 = 0$  (cf. the argument via matrix representations in [HS97b, (15)][So00, (5.66)]) — which proves (115), remembering (101) — in which case the terms denoted  $\mathcal{O}(\check{H}_1)$  in (118) vanish.

**The worldvolume torsion.** The remaining tangential component in (118) is the  $(\psi^2)$ -component of the worldvolume torsion as claimed in (116) (cf. [So00, (5.71)]):

$$\begin{aligned} \overline{P} \left( \gamma^a + (\check{H}_3)_{a b_1 b_2} \gamma^{a_1 a_2} + \check{H}_3 \gamma^a \check{H}_3 \right) P & = \overline{P} \left( \gamma^a + \check{H}_3 \gamma^a \check{H}_3 \right) P && \text{by (90)} \\ & = \overline{P} \left( (\delta_{a'}^a - 2(\check{H}_3^2)_{a'}^a) \gamma^{a'} \right) P && \text{by (103)}. \end{aligned}$$

It just remains to check the other summands of the worldvolume torsion (116): Recalling  $\phi^* \Psi = \psi + \check{H}_3 \psi + \tau_a e^a$ , the  $(e^2)$ -term is immediate, and the  $(e^1 \psi^1)$ -component is obtained as follows:

$$\begin{aligned} \overline{((1 + \check{H}_3) \psi \gamma^a \tau_b)} e^b - \overline{(\tau_b \gamma^a (1 + \check{H}_3) \psi)} e^b & = -2 \overline{(\tau_b \gamma^a (1 + \check{H}_3) \psi)} e^b && \text{by (85)} \\ & = -2 \overline{(\overline{P} \tau_b) \gamma^a (1 + \check{H}_3) P \psi} e^b && \text{by (107)} \\ & = -2 \overline{(\tau_b P \gamma^a (1 + \check{H}_3) P \psi)} e^b && \text{by (89)} \\ & = -2 \overline{(\tau_b \gamma^a \check{H}_3 \psi)} e^b && \text{by (89)}. \end{aligned}$$

This completes the proof.  $\square$

**Remark 3.17 (Simplification of the worldvolume torsion constraint).** Under the assumption  $\tau = 0$  (108) the condition (114) is equivalently just the statement that

$$\Pi_{\alpha b}^a = 0. \tag{119}$$

Hence in this case the conditions (113) and (114) are jointly equivalent to  $(e^{b'} \Pi_{b' b}^a + \psi^\alpha \Pi_{\alpha b}^a) e^b = 0$ , which in turn may equivalently be re-phrased as  $\overline{P}(d^\Omega e) = 0$ , where  $d^\Omega$  denotes the exterior covariant derivative with respect to  $\phi^* \Omega$ .

In summary, if  $\tau = 0$  then the worldvolume torsion constraint (112) according to Lem. 3.16 simplifies to the

following set of statements:

$$\overline{P}(d^\Omega e) = 0, \quad (120)$$

$$\tilde{H} = \tilde{H}_3 := \frac{1}{3!}(\tilde{H}_3)_{a_1 a_2 a_3} \gamma^{a_1 a_2 a_3}, \quad (121)$$

$$d e^a - \omega^a_b e^b = (\delta_{a'}^a - 2(\tilde{H}_3^2)_{a'}^a)(\overline{\psi} \gamma^{a'} \psi). \quad (122)$$

**The super flux densities.** Given an M5 super-immersion  $\phi : \Sigma \rightarrow X$  (Def. 3.12) with induced super co-frame field  $(e, \psi)$  on  $\Sigma$  (67), consider a differential 3-form with only bosonic co-frame components on  $\Sigma$ :

$$H_3^s := H_3 := \frac{1}{3!}(H_3)_{a_1 a_2 a_3} e^{a_1} e^{a_2} e^{a_3} \in \Omega_{\text{dR}}^1(\Sigma; b^2 \mathbb{R}). \quad (123)$$

Here the super-script  $(-)^s$  is to indicate that this is the super 3-flux analog of the super 4-flux density  $G_4^s$  (12). Hence the would-be contribution  $H_3^0$  analogous to  $G_4^0$  in (12) vanishes (cf. [So00, p. 91]). (But a candidate for non-vanishing  $H_3^0$  does appear on “exceptional-geometric” super-spacetime as observed in [FSS20a]; we further discuss this in [GSS24c]).

**Proposition 3.18 (Flux Bianchi identity on M5-brane in components).** *Given a  $1/2$ BPS-immersion of an M5-brane worldvolume (Def. 3.12), the Bianchi identity*

$$dH_3^s = \phi^* G_4^s$$

for super flux-densities of the form (123) and (12) is equivalent to the following set of conditions:

(i) the ordinary but torsion-ful Bianchi identity

$$\frac{1}{3!} \nabla_{[a_1} (H_3)_{a_2 a_3 a_4]} + \frac{1}{2!} (H_3)_{[a_1 a_2 | b]} (\overline{\tau}_{a_3} \gamma^a \tau_{a_4}) = \frac{1}{4!} (\phi^* G_4)_{[a_1 \dots a_4]}; \quad (124)$$

(ii) a rheonomy equation<sup>8</sup> for  $H_3$ :

$$\frac{1}{3!} \psi^\alpha \nabla_\alpha (H_3)_{a_1 a_2 a_3} = (H_3)_{[a_1 a_2 | b]} (\overline{\tau}_{a_3} \gamma^b (1 + \tilde{H}_3) \psi) + (\overline{\tau}_{[a_1} \gamma_{a_2 a_3]} (\psi + \tilde{H}_3 \psi)); \quad (125)$$

(iii) the 3-flux density  $H_3$  is the following function of the transverse fermionic immersion component  $\tilde{H}_3$  (115):

$$(H_3)_{abc} = \frac{-4}{1 - 2/3 \text{tr}(\tilde{H}_3^2 \cdot \tilde{H}_3^2)} (\delta_{a'}^a + 2(\tilde{H}_3^2)_a^{a'}) (\tilde{H}_3)_{a' bc}, \quad (126)$$

where this is well-defined, hence wherever  $\text{tr}(\tilde{H}_3^2 \cdot \tilde{H}_3^2)$  (74) satisfies the non-criticality condition (75).

*Proof.* The fermionic co-frame components of the Bianchi identity are, at face value:

$$\begin{aligned} & d\left(\frac{1}{3!}(H_3)_{a_1 a_2 a_3} e^{a_1} e^{a_2} e^{a_3}\right) - \frac{1}{4!}(\phi^* G_4)_{a_1 \dots a_4} e^{a_1} \dots e^{a_4} - \frac{1}{2}(\overline{(\phi^* \Psi)} \gamma_{a_1 a_2} (\phi^* \Psi)) e^{a_1} e^{a_2} = 0 \\ \Leftrightarrow & \begin{cases} (\psi^0) \left( \frac{1}{3!} \nabla_{a_1} (H_3)_{a_2 a_3 a_4} + \frac{1}{2} (H_3)_{a_1 a_2 b} (\overline{\tau}_{a_3} \gamma^b \tau_{a_4}) - \frac{1}{4!} (\phi^* G_4)_{a_1 \dots a_4} \right) e^{a_1} \dots e^{a_4} = 0 \\ (\psi^1) \left( \frac{1}{3!} \psi^\alpha \nabla_\alpha (H_3)_{a_1 a_2 a_3} - (H_3)_{a_1 a_2 b} (\overline{\tau}_{a_3} \gamma^b (1 + \tilde{H}_3) \psi) - (\overline{\tau}_{a_1} \gamma_{a_2 a_3} (\psi + \tilde{H}_3 \psi)) \right) e^{a_1} e^{a_2} e^{a_3} = 0 \\ (\psi^2) \left( \frac{1}{2} (H_3)_{a_1 a_2 a_3} (\delta_{a'_3}^{a_3} - 2(\tilde{H}_3)_{a'_3}^{a_3} b_1 b_2 (\tilde{H}_3)^{a_3 b_1 b_2}) (\overline{\psi} \gamma^{a'_3} \psi) - ((\psi + \tilde{H}_3 \psi) \gamma_{a_1 a_2} (\psi + \tilde{H}_3 \psi)) \right) e^{a_1} e^{a_2} = 0 \end{cases} \end{aligned}$$

where we used the expression (116) for the worldvolume torsion tensor,

- with which the  $(\psi^0)$ -component is obvious,
- while in the  $(\psi^1)$ -component we also used (105),
- and in the  $(\psi^2)$ -component we in addition used (116).

Hence it just remains to further unwind:

**The Flux Bianchi at  $(\psi^2)$**  for which we crucially use that  $\tilde{H}_3$  is self-dual (115):

For the summand on the right notice that

$$\begin{aligned} & \frac{1}{2} ((\psi + \tilde{H}_3 \psi) \gamma_{a_1 a_2} (\psi + \tilde{H}_3 \psi)) e^{a_1} e^{a_2} \\ &= \frac{1}{2} \left( (\overline{\psi} \tilde{H}_3 \gamma_{a_1 a_2} \psi) + (\overline{\psi} \gamma_{a_1 a_2} \tilde{H}_3 \psi) \right) e^{a_1} e^{a_2} \quad \text{by (96)} \\ &= \frac{1}{2} \left( \overline{\psi} (-2(\tilde{H}_3)_{a_1 a_2 b} \gamma^b + \frac{1}{3} (\tilde{H}_3)^{b_1 b_2 b_3} \gamma_{a_1 a_2 b_1 b_2 b_3}) \psi \right) e^{a_1} e^{a_2} \quad \text{by (86)} \\ &= -4(\tilde{H}_3)_{a_1 a_2 b} \frac{1}{2} (\overline{\psi} \gamma^b \psi) e^{a_1} e^{a_2}, \end{aligned} \quad (127)$$

<sup>8</sup>Solving equation (125) determines the values of the super-flux  $H_3$  on the super-manifold  $\Sigma$  from its value on the bosonic body  $\tilde{\Sigma}$ , hence its “flow” across superspace (whence “rheonomy” as in [CDF91, §III.3.3]).

where in the last step we used

$$\begin{aligned} (\tilde{H}_3)^{b_1 b_2 b_3} \Gamma_{a_1 a_2 b_1 b_2 b_3} &= (\tilde{H}_3)^{b_1 b_2 b_3} \epsilon_{a_1 a_2 b_1 b_2 b_3 c} \gamma^c && \text{by (100)} \\ &= -3! (\tilde{H}_3)_{a_1 a_2 c} \gamma^c && \text{by (101)}. \end{aligned}$$

This way the Bianchi identity at  $(\psi^2)$  is equivalent to (126), as claimed (cf. [HSW97b, (7)][So00, (5.80-81)]):

$$\begin{aligned} (\delta_a^{a'} - 2(\tilde{H}_3^2)_a^{a'}) (H_3)_{a'bc} &= -4(\tilde{H}_3)_{abc} && \text{by (127)} \\ \Leftrightarrow (H_3)_{abc} &= \frac{-4}{1 - 2/3 \text{tr}(\tilde{H}_3^2 \cdot \tilde{H}_3^2)} (\delta_a^{a'} + 2(\tilde{H}_3^2)_a^{a'}) (\tilde{H}_3)_{a'bc} && \text{by (76)}. \quad \square \end{aligned} \tag{128}$$

**Remark 3.19 (Non/Self-duality of the 3-flux density).** Given an M5 super-immersion  $\phi$  (3.12), then the decomposition of its 3-flux density  $H_3$  (126) into a self dual and an anti self-dual summand is (cf. [HSW97b, (18-19)])

$$(H_3)_{abc} = \frac{-4}{1 - 2/3 \text{tr}(\tilde{H}_3^2 \cdot \tilde{H}_3^2)} \left( \underbrace{\tilde{H}_{abc}}_{\text{self-dual}} + 2 \underbrace{(\tilde{H}_3^2)_a^{a'} \tilde{H}_{abc}}_{\text{anti self-dual}} \right).$$

Namely, we already know of course (115) that the first summand is self-dual, but with (126) it follows that the second summand is skew-symmetric in its indices, whence its anti self-duality follows by (77). In summary this means that (cf. [HS97b, p. 6][HSW97b][So00, p. 92]) the 3-flux density  $H_3$  on the M5-brane:

- is in general not self-dual,
- albeit determined by its self-dual part,
- with its anti self-dual part a higher order ( $\geq$  cubic) function of the self-dual part, away from criticality (75),
- so that  $H_3$  is (only) asymptotically self-dual as its absolute value goes to zero (i.e., in the small field limit).

Note, therefore, that the extensive attention that self-duality constraints on flux densities in 6d have found in the literature (e.g., [HT88][Wi97b][BM06][Sen20][La19b][An+22][RSvdW21]) does not actually apply to the full M5-brane worldvolume theory (where the would-be duality condition is at face value more complicated and yet all implied by the  $1/2$ BPS super-immersion condition), but only asymptotically to its small field limit (which in the further limit of decoupled gravity is famously expected to be a  $\mathcal{N} = (2, 0)$   $D = 6$  CFT, e.g. [SäS18]).

**Remark 3.20 (Recovering the ordinary worldvolume Bianchi identity).** We see from (124) that the expected Bianchi identity  $dH_3 = \phi^* G_4$  (1) on the ordinary bosonic worldvolume  $\tilde{\Sigma} \hookrightarrow \Sigma$  is recovered (only) if  $\tau = 0$ , which is indeed implied by the  $1/2$ BPS immersion condition, cf. Rem. 3.13 above (more implicitly assumed for instance in [HLW98, p. 4]).

With the previous two remarks we have arrived at the desired conclusion that the M5's worldvolume Bianchi identity *when promoted to super-space* subsumes both the ordinary Bianchi identity on  $H_3$  as well as its (non/self-duality) equation of motion. As explained in §1, this suggests that to obtain the completed field content on the M5-brane we are to flux-quantize this super-flux  $H_3^s$  on the super-worldvolume.

In the following §4, we discuss some consequences of such flux-quantization.

## 4 Flux quantization on M5-branes

Having established (with the result in §3) that the flux quantization (21) of the super-worldvolume super-flux on the M5-brane provides a full global completion of the M5's on-shell field content, here we discuss some properties of the resulting flux quantized fields.

- §4.1 establishes the backwards-compatibility of the flux quantized fields, locally, to the traditional formulas for gauge potentials,
- §4.2 analyzes the resulting worldvolume charges of singular strings and solitonic membranes inside the M5, under the assumption that flux quantization is in co-Homotopy theory.

### 4.1 Gauge potentials on the M5-brane

The construction of flux-quantized fields in (9) not only constrains the flux densities to reflect quantized charges, but does so by constructing the gauge potentials that exhibit the corresponding higher gauge field. Globally the nature of the gauge potentials crucially depends on the chosen flux quantization law  $\mathcal{A}$ ; but locally, on a good open cover  $\tilde{X}$  by contractible charts  $U_i \xrightarrow{U_i} X$ , the charges necessarily vanish (due to the assumption that the

classifying space  $\mathcal{A}$  is connected, hence with an essentially unique basepoint  $0_{\mathcal{A}} : * \rightarrow \mathcal{A}$ ) and the nature of the gauge potentials becomes independent of the choice of  $\mathcal{A}$ , as it should be:

$$\begin{array}{ccc}
& & * \\
& \nearrow^{\text{vanishing charge}} & \downarrow 0_{\mathcal{A}} \\
\text{Contractible chart } U_i & \xrightarrow{\sim} & \mathcal{A} \\
\downarrow \iota_i & \parallel & \downarrow \text{ch}_{\mathcal{A}} \\
\text{Domain super-space (worldvolume)} \Sigma & \xrightarrow{\vec{F} \text{ flux density}} \Omega_{\text{dR}}^1(-; \mathfrak{a})_{\text{clsd}} \xrightarrow{\eta^f} \int \Omega_{\text{dR}}^1(-; \mathfrak{a})_{\text{clsd}} & 
\end{array}
\quad (129)$$

By definition of the moduli object on the bottom right (see [SS25, p. 26][GSS24a, Ex. 2.55] following [FSS23, Def. 9.1]), the homotopy filling the diagram (129) is a concordance (deformation) of closed  $\mathfrak{a}$ -valued differential forms from zero to the given flux densities  $\vec{F}$ :

$$\vec{A} \in \Omega_{\text{dR}}^1(U_i \times [0, 1]; \mathfrak{a})_{\text{clsd}} \quad \text{s.t.} \quad \begin{cases} \iota_0^*(\vec{A}) = 0 \\ \iota_1^*(\vec{A}) = \vec{F} \end{cases} \in \Omega_{\text{dR}}^1(U_i; \mathfrak{a})_{\text{clsd}}. \quad (130)$$

This is just the notion of coboundary in  $\mathfrak{a}$ -valued de Rham cohomology ([FSS23, Def. 6.3]), in fact it reduces to ordinary de Rham coboundaries in the abelian case where  $\mathfrak{a}$  is the  $L_{\infty}$ -algebra which is  $\mathbb{R}$  concentrated in some degree ([FSS23, Prop. 6.4]). When  $\mathfrak{a}$  is not abelian, as in the case of interest where  $\mathfrak{a} = \mathfrak{I}_{S^4} S^7$  (18), then a little work is needed to extract more concise coboundary data underlying the concordances (130). This is what we do now for the worldvolume fields on the M5-brane (Prop. 4.1 below), showing how it reproduces the traditional local formulas and thereby providing these with a rule for their global completion.

**Deriving the form of local gauge potentials on the M5-brane.** For the case of 11d supergravity, we had shown in [GSS24a, Props. 1.1, 2.28] how the traditional formulas for the local C-field gauge potentials are indeed reproduced by the homotopy theory in (129) and as such become amenable to global completion. Here we extend this analysis to include the B-field on M5-brane worldvolumes, showing how it reproduces the traditional formulas (2). To this end:

(i) Recall the fiberwise Stokes Theorem (e.g. [FSS23, Lem. 6.1][FSS23, Lem. 6.1]) for differential forms  $\widehat{F}$  on a cylinder manifold:

$$d \int_{[0,1]} \widehat{F} = \iota_1^* \widehat{F} - \iota_0^* \widehat{F} - \int_{[0,1]} d\widehat{F}, \quad \text{on } X \xrightleftharpoons[\iota_1]{\iota_0} X \times [0, 1]. \quad (131)$$

(ii) Recall from (19) that closed  $\mathfrak{I}_{S^4} S^7$ -valued differential forms are given by

$$\begin{aligned}
\Omega_{\text{dR}}^1(-; \mathfrak{I}_{S^4} S^7)_{\text{clsd}} & \equiv \left\{ \begin{array}{l} H_3 \in \Omega_{\text{dR}}^1(-; b^2 \mathbb{R}) \\ G_7 \in \Omega_{\text{dR}}^1(-; b^6 \mathbb{R}) \\ G_4 \in \Omega_{\text{dR}}^1(-; b^3 \mathbb{R}) \end{array} \middle| \begin{array}{l} dH_3 = G_4 \\ dG_7 = \frac{1}{2} G_4 G_4 \\ dG_4 = 0 \end{array} \right\} \\
\downarrow \\
\Omega_{\text{dR}}^1(-; \mathfrak{I}_{S^4})_{\text{clsd}} & \equiv \left\{ \begin{array}{l} G_7 \in \Omega_{\text{dR}}^1(-; b^6 \mathbb{R}) \\ G_4 \in \Omega_{\text{dR}}^1(-; b^3 \mathbb{R}) \end{array} \middle| \begin{array}{l} dG_7 = \frac{1}{2} G_4 G_4 \\ dG_4 = 0 \end{array} \right\}
\end{aligned} \quad (132)$$

(iii) Observe that a null-concordance (130) of such data, hence a closed  $\mathfrak{I}_{S^4} S^7$ -valued differential form on the cylinder manifold  $U_i \times [0, 1]$  which on one boundary pulls back to the given form data and on the other boundary to zero, is:

$$(\widehat{G}_4, \widehat{G}_7, \widehat{H}_3) \in \Omega_{\text{dR}}^1(U_i \times [0, 1]; \mathfrak{I}_{S^4} S^7)_{\text{clsd}} \quad \text{s.t.} \quad \begin{cases} \iota_0^*(\widehat{G}_4, \widehat{G}_7, \widehat{H}_3) = 0 \\ \iota_1^*(\widehat{G}_4, \widehat{G}_7, \widehat{H}_3) = (G_4, G_7, H_3). \end{cases} \quad (133)$$

Similarly, given a pair  $(\widehat{G}_4, \widehat{G}_7, \widehat{H}_3), (\widehat{G}'_4, \widehat{G}'_7, \widehat{H}'_3)$  of such null-concordances for the same  $(G_4, G_7, H_3)$ , a *concordance-of-concordances* between them is

$$(\widehat{\widehat{G}}_4, \widehat{\widehat{G}}_7, \widehat{\widehat{H}}_3) \in \Omega_{\text{dR}}^1(U_i \times [0, 1]_t \times [0, 1]_s; \mathfrak{I}_{S^4} S^7)_{\text{clsd}} \quad \text{s.t.} \quad \begin{cases} \iota_{s=0}^*(\widehat{\widehat{G}}_4, \widehat{\widehat{G}}_7, \widehat{\widehat{H}}_3) = (\widehat{G}_4, \widehat{G}_7, \widehat{H}_3) \\ \iota_{s=1}^*(\widehat{\widehat{G}}_4, \widehat{\widehat{G}}_7, \widehat{\widehat{H}}_3) = (\widehat{G}'_4, \widehat{G}'_7, \widehat{H}'_3) \\ \iota_{t=0}^*(\widehat{\widehat{G}}_4, \widehat{\widehat{G}}_7, \widehat{\widehat{H}}_3) = 0 \\ \iota_{t=1}^*(\widehat{\widehat{G}}_4, \widehat{\widehat{G}}_7, \widehat{\widehat{H}}_3) = \text{pr}_{U_i}^*(G_4, G_7, H_3), \end{cases} \quad (134)$$

where in the last line  $\text{pr}_{U_i} : U_i \times [0, 1]_s \rightarrow U_i$  is the canonical projection.

**Proposition 4.1 (B- & C-field gauge potentials are local  $\mathbb{I}_{S^4} S^7$ -valued de Rham null coboundaries).**

Given flux densities  $(G_4, G_7, H_3) \in \Omega_{\text{dR}}^1(U_i; \mathbb{I}_{S^4} S^7)_{\text{clsd}}$  (132),

(i) there is a natural surjection from their null concordances (133) to triples of gauge potentials as shown here:

$$\left\{ \begin{array}{c} \xrightarrow{\quad * \quad} \\ \text{---} \xrightarrow{\quad \widehat{G}_4, \widehat{G}_7, \widehat{H}_3 \quad} \xrightarrow{\quad} \\ U_i \xrightarrow{(G_4, G_7, H_3)} \Omega_{\text{dR}}^1(-; \mathbb{I}_{S^4} S^7)_{\text{clsd}} \xrightarrow{\eta^\flat} \int(\Omega_{\text{dR}}^1(-; \mathbb{I}_{S^4} S^7)_{\text{clsd}}) \end{array} \right\} \rightarrow \left\{ \begin{array}{l} C_3 \in \Omega_{\text{dR}}^3(U_i) \mid d C_3 = G_4 \\ C_6 \in \Omega_{\text{dR}}^3(U_i) \mid d C_6 = G_7 - \frac{1}{2} C_3 G_4 \\ B_2 \in \Omega_{\text{dR}}^2(U_i) \mid d B_2 = H_3 - C_3 \end{array} \right\} \quad (135)$$

(ii) This surjection takes concordances-of-concordances (134) to gauge equivalences of gauge potentials of the following form

$$(C_3, C_6, B_2) \sim (C'_3, C'_6, B'_2) \Leftrightarrow \exists \left. \begin{array}{l} C_2 \in \Omega_{\text{dR}}^2(U_i) \\ C_5 \in \Omega_{\text{dR}}^5(U_i) \\ B_1 \in \Omega_{\text{dR}}^1(U_i) \end{array} \right\} \text{ such that } \left\{ \begin{array}{l} d C_2 = C'_3 - C_3 \\ d C_5 = C'_6 - C_6 - \frac{1}{2} C'_3 C_3 \\ d B_1 = B'_2 - B_2 + C_2. \end{array} \right. \quad (136)$$

*Proof.* We take the map  $(\widehat{G}_4, \widehat{G}_7, \widehat{H}_3) \mapsto (C_3, C_6, B_2)$  to be given on the C-field flux densities as in [GSS24a, (70)]

$$C_3 := \int_{[0,1]} \widehat{G}_4, \quad C_6 := \int_{[0,1]} \left( \widehat{G}_7 - \frac{1}{2} \underbrace{\left( \int_{[0,-]} \widehat{G}_4 \right)}_{\widehat{C}_3} \widehat{G}_4 \right) \quad (137)$$

and analogously on the B-field flux density to be:

$$B_2 := \int_{[0,1]} \widehat{H}_3. \quad (138)$$

To see that this satisfies the relations on the right of (135): For the first two lines this is [GSS24a, (70)], while for the last line we compute as follows:

$$\begin{aligned} d B_2 &= d \int_{[0,1]} \widehat{H}_3 && \text{by (138)} \\ &= \iota_1^* \widehat{H}_3 - \int_{[0,1]} d \widehat{H}_3 && \text{by (131)} \\ &= H_3 - \int_{[0,1]} \widehat{G}_4 && \text{by (133)} \\ &= H_3 - C_3 && \text{by (137)}. \end{aligned}$$

To see that this map is indeed a surjection, we exhibit a section  $(C_3, C_6, B_2) \mapsto (\widehat{G}_4, \widehat{G}_7, \widehat{H}_3)$  extending the lifts of  $(C_3, C_6)$  from [GSS24a, (72)] to  $H_3$  as follows:

$$\left. \begin{array}{l} \widehat{G}_4 := t G_4 + dt C_3 \\ \widehat{G}_7 := t^2 G_7 + 2t dt C_6 \\ \widehat{H}_3 := t H_3 + dt B_2 \end{array} \right\} \text{ which indeed satisfies } \left\{ \begin{array}{l} d(t G_4 + dt C_3) = 0 \\ d(t^2 G_7 + 2t dt C_6) = \frac{1}{2} (t G_4 + dt C_3) (t G_4 + dt C_3) \\ d(t H_3 + dt B_2) = (t G_4 + dt C_3). \end{array} \right.$$

Finally, to see that the map respects equivalences, consider a pair of null-concordances  $(\widehat{G}_4, \widehat{G}_7, \widehat{H}_3), (\widehat{G}'_4, \widehat{G}'_7, \widehat{H}'_3)$  with a concordance-of-concordances  $(\widehat{\widehat{G}}_4, \widehat{\widehat{G}}_7, \widehat{\widehat{H}}_3)$  between them, and produce a gauge equivalence as in (136) from this by taking, as in [GSS24a, (73)],

$$C_2 := \int_{s \in [0,1]} \int_{t \in [0,1]} \widehat{\widehat{G}}_4, \quad C_5 := \int_{s \in [0,1]} \int_{t \in [0,1]} \left( \widehat{\widehat{G}}_7 - \frac{1}{2} \left( \int_{t' \in [0,-]} \widehat{\widehat{G}}_4 \right) \widehat{\widehat{G}}_4 \right) - \frac{1}{2} C_2 C_3, \quad (139)$$

and now in addition

$$B_1 := \int_{s \in [0,1]} \int_{t \in [0,1]} \widehat{\widehat{H}}_3. \quad (140)$$

That this indeed satisfies the required relations follows for  $C_2$  and  $C_5$  by [GSS24a, (74)] and for  $B_1$  by the following computation:

$$\begin{aligned}
d B_1 &\equiv d \int_{s \in [0,1]} \int_{t \in [0,1]} \widehat{H}_3 && \text{by (140)} \\
&= \iota_{s=1}^* \int_{t \in [0,1]} \widehat{H}_3 - \iota_{s=0}^* \int_{t \in [0,1]} \widehat{H}_3 - \int_{s \in [0,1]} d \int_{t \in [0,1]} \widehat{H}_3 && \text{by (131)} \\
&= \int_{t \in [0,1]} \iota_{s=1}^* \widehat{H}_3 - \int_{t \in [0,1]} \iota_{s=0}^* \widehat{H}_3 - \int_{s \in [0,1]} H_3 + \int_{s \in [0,1]} \int_{t \in [0,1]} d \widehat{H}_3 && \text{by (131)} \\
&= \int_{t \in [0,1]} \widehat{H}'_3 - \int_{t \in [0,1]} \widehat{H}_3 + \int_{s \in [0,1]} \int_{t \in [0,1]} \widehat{G}_4 && \text{by (134)} \\
&= \widehat{B}'_2 - \widehat{B}_2 + C_2 && \text{by (138) \& (139).} \quad \square
\end{aligned}$$

**Remark 4.2 (Reproducing the traditional local gauge potential).** Equation (135) in Prop. 4.1 says, in particular, that the traditional formula (2) for the gauge potential on the M5-brane is reproduced locally.

## 4.2 Skyrmions and Anyons on M5

Finally, we spell out key consequences of quantizing the  $H_3$ -flux density on M5-branes in co-Homotopy cohomology theory, according to (22), highlighting how this leads to quantum observables of skyrmions and of anyonic quantum states (156), thus supporting the idea that the completed field content on the M5-brane generically reflects properties of strongly coupled/correlated quantum systems.

The method of non-perturbative quantization of the topological charge sector which we use here is that of [SS24b], and the approach to anyonic quantum states is broadly that of [SS22][SS23b], but where in these previous discussions we focused on intersecting brane configurations, here we give an alternative construction with single M5-branes that is supported by the above super-space analysis.

**M5-branes near the horizon of their own black brane solution.** In doing so, we focus on the special but important case where the pullback of the background M-brane charge to the M5-brane worldvolume trivializes,  $\phi^*(c_3, c_6) \simeq 0$ . This may happen if the background charge vanishes by itself in the first place, for instance if the target spacetime is flat Minkowski space  $\mathbb{R}^{1,10}$  (as in Ex. 3.14), or else if the M5-worldvolume does not wrap cycles on which the background charge is supported; for instance if it stretches along the asymptotic boundary of the near horizon geometry  $\text{AdS}_7 \times S^4$  of its own “black” brane background (as discussed in [CKvP98][PST99][CKKTvP98, §3.3], in microscopic resolution of AdS/CFT duality).

Since this pullback charge serves as the twist of the twisted 3-co-Homotopy on the worldvolume, under Hypothesis H (22), it follows that in this case the M5 worldvolume B-field is quantized in plain 3-co-Homotopy (recalling from ftn. 4 that for the purpose of the present discussion we are disregarding further tangential twists of Cohomotopy):

$$\begin{array}{ccc}
\text{If background charge} & \text{then} & \text{the charge-twisted} \\
\text{vanishes on worldvolume} & \Rightarrow & \text{3-Cohomotopy} \\
\phi^*(c_3, c_6) \simeq 0 & & \pi^{3+\phi^*(c_3+c_6)}(\Sigma) \\
& & \text{reduces to} \\
& & \text{plain} \\
& & \text{3-Cohomotopy} \\
& & \pi^3(\Sigma)
\end{array}
=
\left( \left\{ \begin{array}{ccc} & & S^7 \\ & \nearrow^{b_2} & \downarrow h_{\mathbb{H}} \\ \Sigma & \xrightarrow{\phi} X & \xrightarrow{(c_3, c_6)} S^4 \end{array} \right\} \right)_{/\text{rel.hmtp.}}
=
\left( \left\{ \begin{array}{ccc} & & S^3 & \longrightarrow & S^7 \\ & \nearrow^{b_2} & \downarrow & \text{(pb)} & \downarrow h_{\mathbb{H}} \\ \Sigma & \longrightarrow & * & \longrightarrow & S^4 \\ & \searrow^{\phi} & \swarrow^{\llcorner} & \nearrow^{(c_3, c_6)} & \\ & & X & & \end{array} \right\} \right)_{/\text{rel.hmtp.}} \quad (141)$$

**Self-dual string charge quantization.** With this and in direct generalization of traditional Dirac monopole charge quantization

$$\begin{array}{ccc}
\text{Charges of Dirac monopole} & H^2(\underbrace{\mathbb{R}^{1,3} \setminus \mathbb{R}^{0,1}}_{\text{Spacetime around}}; \mathbb{Z}) \simeq H^2(\underbrace{\mathbb{R}^{0,1} \times \mathbb{R}_{>0}}_{\text{contractible}} \times S^2; \mathbb{Z}) \simeq H^2(S^2; \mathbb{Z}) \simeq \mathbb{Z} & \text{Integer number of} \\
\text{by trad. flux quantization} & & \text{magnetic monopoles}
\end{array}$$

the archetypical charge quantization situation on an M5-brane is that for its monopole string solution (the *self-dual string soliton* [HLW98, §3]), hence with M5-worldvolume topology of the form (using [HLW98, (3.16)])

$$\Sigma \simeq \mathbb{R}^{1,5} \setminus \mathbb{R}^{1,1} \simeq \mathbb{R}^{1,1} \times \mathbb{R}_{>0} \times S^3. \quad (142)$$



The corresponding charge quantization law implied by Hypothesis H, via (141), gives string charges in the 3-Cohomotopy of the 3-sphere. Via the *Hopf degree theorem* this is canonically identified with the ordinary integral cohomology of the 3-sphere (cf. [FSS20b, (35)])

$$M^3 \text{ a closed orientable 3-fold} \quad \Rightarrow \quad \pi^3(M^3) \simeq H^3(M^3; \mathbb{Z}) \quad (143)$$

and thereby given by the group of integers:

$$\begin{array}{ccc} \text{Charges of self-dual string} & & \text{coincide with the} \\ \text{according to} & \pi^3(\Sigma) \equiv \pi^3(\underbrace{\mathbb{R}^{1,1} \times \mathbb{R}_{>0}}_{\text{contractible}} \times S^3) \simeq \pi^3(S^3) \simeq H^3(S^3) \simeq \mathbb{Z} & \text{traditional charges} \\ \text{Hypothesis H} & & \text{in ordinary cohomology.} \end{array} \quad \text{Hopf degree theorem (143)}$$

Hence in this case the charges in co-Homotopy coincide with those seen in ordinary cohomology and the traditionally (and often tacitly) expected charge quantization law of the self-dual string is recovered.

However, even in this situation, the cohomotopical perspective provides further insight:

**Pixelated flux.** The authors of [HLLSZ19] suggest (cf. their Fig. 2) to think of the  $N$  units of flux through the 3-sphere surrounding an integer-charged brane as being witnessed by a distribution of  $N$  points (“pixels”) on the sphere. While this perspective is suggested by the physical picture, it is not really supported by the mathematics of charge quantization in ordinary cohomology.

However, for charge quantization in co-Homotopy, the original **Pontrjagin theorem** establishes a natural bijection between (cohomotopical) charges and actual branes in the guise of (cobordism classes of) submanifolds of the domain space, which in this situation reproduces much the picture of pixelation:

Concretely (see [SS23a, Prop. 3.24 & pp. 13][SS20a, §2.1]), for  $S \hookrightarrow M$  a smooth submanifold of co-dimension 3 inside a closed smooth manifold  $M$ , then a *normal framing* of  $S$  (namely a trivialization of its normal bundle) canonically induces a map  $M \rightarrow S^3$  (given by accordingly projecting a tubular neighborhood of  $S$  onto  $\mathbb{R}^3 \simeq S^3 \setminus \{s_0\}$  and mapping its complement to  $s_0$ ), which under Hypothesis H we understand as assigning the *Cohomotopy charge* carried by the brane  $S$ .

Now Pontrjagin’s theorem means that two such branes  $S, S'$  carry the same Cohomotopy charge iff they are (normally framed-)cobordant, namely that assigning Cohomotopy charge gives a bijection:

$$\begin{array}{ccc} \text{Cobordism classes of} & & \\ \text{normally framed submanifolds} & \text{Cob}_{\text{Fr}}^3(\Sigma) \xrightarrow{\sim \text{assign brane charge}} \pi^3(\Sigma) & \text{3-Cohomotopy} \\ \text{of co-dimension 3} & & \end{array} \quad (144)$$

thus accurately identifying branes by their charges, and *vice versa*.

But if we apply this correspondence to the above situation, then it identifies (a) integer flux  $N \in \mathbb{Z}$  through the  $S^3$  around the self-dual string soliton with (b)  $|N|$  points on  $S^3$  (the co-dimension 3 submanifold) each carrying charge  $\text{sgn}(N)$  (one of two distinct normal framings, reflecting branes and anti-branes, respectively, cf. [SS23a, p. 12][SS20a, p. 12]). This Cohomotopy theory substantiates the picture of [HLLSZ19, Fig. 2] (adapted on the right).

$$\begin{array}{ccc} \pi^3(S^3) & \xrightarrow{\sim} & \text{Cob}_{\text{Fr}}^3(S^3) \\ N & \mapsto & \left[ \text{A sphere with } N \text{ red dots} \right] \end{array} \quad (145)$$

**Skyrmions on M5.** Alongside *singular branes* like the self-dual string (142) (the flux field it sources would be singular if the actual locus of the singular string were not removed from the M5-worldvolume), flux quantization allows to discuss genuine *solitonic branes* which source a flux density that is non-singular everywhere and is instead topologically stabilized by the constraint that it vanishes at infinity ([SS25, §2.2]). For example, in ordinary electromagnetism there are (recalled in [SS25, §2.1]) besides the singular branes being the Dirac monopoles (which remain hypothetical) also solitonic branes being *Abrikosov vortices* (which are experimentally well observed).

Another example of solitonic objects in this sense are *Skyrmions* (cf. [ANW93][RZ16][Mant22]), which are solitons in the  $SU(2)$ -valued pion field (possibly including higher vector meson field contributions), that at least approximate baryon bound states in confined quantum chromodynamics (and which in the Witten-Sakai-Sugimoto model are essentially identified with wrapped D4-branes, cf. [Su16]).

Concretely, the solitonic nature of Skyrmions requires that the spatial pion field  $f : \mathbb{R}^3 \rightarrow SU(2)$  takes the trivial value  $1 \in SU(2)$  “at infinity”. This may neatly be formalized (cf. [SS23a, Rem. 2.3 & p. 14]) by “adjoining the point at infinity” to  $\mathbb{R}^3$  via passage to its *Alexandroff one-point compactification*  $\mathbb{R}_{\cup\{\infty\}}^3 \simeq S^3$  and requiring  $f$  to extend to a map on this compactification such that there it takes the literal point  $\infty$  to 1:

$$\begin{array}{ccc} \text{Euclidean space with} & & \\ \text{point at infinity adjoined} & \mathbb{R}_{\cup\{\infty\}}^3 \xrightarrow[\text{pion field}]{f} \text{SU}(2) & \\ \infty & \mapsto & 1. \end{array}$$

The *baryon number* of such as Skyrmion configuration (e.g., [BMS10, (4.26)][Mant22, (4.26)]) is then the homotopy class of this map, under the Hopf degree theorem (143), noticing that  $SU(2) \underset{\text{homeo}}{\simeq} S^3$ :

$$\text{Baryon number of Skyrmion } [f] \in \pi_0(\text{Maps}^*/(\mathbb{R}_{\cup\{\infty\}}^3, SU(2))) \simeq \pi^3(\mathbb{R}_{\cup\{\infty\}}^3) \simeq \pi^3(S^3) \simeq H^3(S^3; \mathbb{Z}) \simeq \mathbb{Z}. \quad (146)$$

This makes explicit that baryon number in Skyrmion theory is equivalently the Cohomotopy charge embodied by the pion field, of just the same form as the solitonic B-field charge on an M5-brane worldvolume domain of the form

$$\Sigma \equiv \mathbb{R}^{1,2} \times \mathbb{R}_{\cup\{\infty\}}^3, \quad (147)$$

in that:<sup>9</sup>

$$\pi^3(\Sigma) \equiv \pi^3(\underbrace{\mathbb{R}^{1,2}}_{\text{contractible}} \times \mathbb{R}_{\cup\{\infty\}}^3) \simeq \pi^3(\mathbb{R}_{\cup\{\infty\}}^3) \simeq \pi^3(S^3) \simeq H^3(S^3; \mathbb{Z}) \simeq \mathbb{Z}.$$

Beyond these sets of charges, flux quantization provides us with their *moduli spaces*:

**Moduli spaces of Skyrmons.** Flux quantized fields in the form (9) do not just form a set, but naturally a (supergeometric) higher groupoid (a “space”, review includes [FSS23, §1]) whose (higher) morphisms are the (higher) gauge transformations (hence which is the finite version of the on-shell BRST complex of the higher gauge theory). Concretely, this is the homotopy fiber product of the smooth super-set of on-shell flux densities with the moduli space of charges, where the latter is, in our situation (141), the pointed mapping space

$$\text{Moduli space of co-Homotopy charges } \tilde{\pi}^3(\Sigma) := \text{Maps}^*/(\Sigma, S^3) \xrightarrow{\pi_0} \tilde{\pi}^3(\Sigma) \quad \text{Set of co-Homotopy charges} \quad (148)$$

Therefore, from now on we understand  $\Sigma$  as being pointed by a “point at infinity”, and its co-Homotopy to be the corresponding “reduced” co-Homotopy  $\tilde{\pi}^3$  (classes of point-preserving maps) such as to implement any constraints of charges vanishing at infinity.<sup>10</sup>

This entails that for  $(X, \infty_x)$  and  $(Y, \infty_y)$  a pair of spaces with designated points at infinity, their appropriate product space is the “smash product”

$$X \wedge Y := \frac{X \times Y}{X \times \{\infty_y\} \cup \{\infty_x\} \times Y} \quad \text{pointed by } (\infty_x, \infty_y)$$

in terms of which our Minkowskian M5 worldvolume (147) properly reads as follows:<sup>11</sup>

$$\Sigma \equiv \mathbb{R}_{\cup\{\infty\}}^{1,2} \wedge \mathbb{R}_{\cup\{\infty\}}^3 \Rightarrow \tilde{\pi}^3(\Sigma) \simeq \tilde{\pi}^3(\mathbb{R}_{\cup\{\infty\}}^3) \simeq \mathbb{Z} \quad \boxed{\mathbb{R}^{1,1} \times \mathbb{R}^3 \times \mathbb{R}^1} \quad (149)$$

where the “brane diagram” on the right indicates the extension of the Skyrmion as seen via its Cohomotopy charges.

Remarkably, the charged points that, so far, appeared only through their *net number* in  $\mathbb{Z}$  now “come to life” as we pass to their co-Homotopy moduli space (148), in that this happens to equivalently be (the group completion  $\mathbb{G}$  of) the *configuration space of points* in space,  $\text{Conf}(\mathbb{R}^3)$ , whose elements are finite subsets of  $\mathbb{R}^3$  and whose paths are continuous *motions* of these (by [Se73, Thm. 1]):

$$\text{co-Homotopy moduli space of Skyrmons } \tilde{\pi}^3(\mathbb{R}_{\cup\{\infty\}}^3) \underset{\text{hntp}}{\simeq} \mathbb{G}(\text{Conf}(\mathbb{R}^3)) \quad \text{Configuration space of points and anti-points.} \quad (150)$$

Here the group completion

$$\mathbb{G}(\text{Conf}(\mathbb{R}^3)) := \Omega(B_{\perp}\text{Conf}(\mathbb{R}^3))$$

is with respect to the topological monoid structure on  $\text{Conf}(\mathbb{R}^3)$  via (suitably adjusted) disjoint union of configurations, hence by adjoining “anti-points” (carrying negative unit charge) to the ordinary points (carrying positive unit charge) in the configurations.

**Remark 4.3 (Torsion contribution in flux quantization).** While the classifying spaces  $S^3$  (for co-Homotopy) and  $B^3\mathbb{Z}$  (for ordinary cohomology) have the same rational homotopy type

$$\mathfrak{L}S^3 \simeq \mathfrak{L}B^3\mathbb{Z},$$

so that both would qualify as valid charge quantization laws on the M5-brane if its coupling to the background C-field were ignored, they differ drastically in torsion contributions. It is the unbounded torsion in the homotopy groups of  $S^3$ , hence in the higher homotopy groups of spheres, which conspires to make 3-co-Homotopy reflect these configuration spaces (150) of solitonic branes. Cf. also Rem. 4.4 below.

<sup>9</sup>A similar consideration appears in [In00, p. 7], albeit not for the B-field flux in 3-Cohomotopy (maps to  $S^3$ ) but for the worldvolume scalar fields regarded as maps to  $S^4$  as in (23).

<sup>10</sup>Notice that the point at infinity may be disjoint, denoted  $\Sigma_{\sqcup\{\infty\}} := \Sigma \sqcup \{\infty\}$ , whereby reduced co-Homotopy subsumes plain co-Homotopy:  $\tilde{\pi}^3(\Sigma_{\sqcup\{\infty\}}) = \pi^3(\Sigma)$  (similarly for any other generalized cohomology theory).

<sup>11</sup>Recall that this yoga of pointed spaces just serves to neatly encode fall-off conditions on the fields under consideration.

Of course, with the plain Minkowskian worldvolume topology used so far (149), the worldvolume Skyrmons actually live in 1+5 dimensions and are themselves 2-branes instead of vortex-like: It remains to pass to a suitable double dimensional reduction in the remaining two spatial directions in order to model anyonic defects.

**Topological quantum observables on Skyrmons.** To that end, first consider KK-compactifying the background spacetime, and jointly the M5-brane worldvolume, on a circle  $S_A^1$ ,

$$\Sigma \equiv \mathbb{R}_{\sqcup\{\infty\}}^{1,1} \wedge \mathbb{R}_{\cup\{\infty\}}^3 \wedge (S_A^1)_{\sqcup\{\infty\}} \quad \boxed{\mathbb{R}^{1,1} \times \mathbb{R}^3 \times S_A^1} \quad (151)$$

which we think of as the ‘‘M-theory circle’’ fiber in M/IIA duality. Now  $\tilde{\pi}^3(\Sigma)$  being a *moduli space* (instead of just a set) of charges implies (by ‘‘closed smash monoidal structure’’, cf. [SS24b, §A.2]) that the moduli on this KK-compactified worldvolume are equivalently the free loop space  $\mathcal{L}$  of the (group completed) configuration space:

$$\begin{aligned} \tilde{\pi}^3(\Sigma) &\simeq \text{Maps}^*/((S_A^1)_{\sqcup\{\infty\}} \wedge \mathbb{R}_{\cup\{\infty\}}^3, S^3) \simeq \text{Maps}(S_A^1, \text{Maps}^*(\mathbb{R}_{\cup\{\infty\}}^3, S^3)) \\ &\equiv \mathcal{L}(\tilde{\pi}^3(\mathbb{R}_{\cup\{\infty\}}^3)) \simeq \mathcal{L}(\mathbb{G}\text{Conf}(\mathbb{R}^3)). \end{aligned}$$

However, in the strongly-coupled regime that we are after, the circle  $S_A^1 \simeq (\mathbb{R}_A^1)_{\sqcup\{\infty\}}$  is meant to ‘‘decompactify’’, which must mean that we are to fix the asymptotic charges  $c_\infty$  at  $\infty \in (\mathbb{R}_A^1)_{\cup\infty}$ , hence to consider as the (topological) non-perturbative moduli space of Skyrmons on M5 the space of (not free) loops of configurations (but) based at  $c_\infty$ :

$$\Omega_{c_\infty}(\tilde{\pi}^3(\mathbb{R}_{\cup\{\infty\}}^3)) \simeq \Omega_{c_\infty} \mathbb{G}(\text{Conf}(\mathbb{R})).$$

With this charge moduli space understood as the topological sector of the integrated BRST-complex of the field theory, the topological quantum observables should correspond to compactly supported complex functions on this space, and hence *higher observables* should be given by the homology groups of this space [SS24b, §3]:

$$\text{Obs}_\bullet := H_\bullet(\Omega_{c_\infty} \mathbb{G}\text{Conf}(\mathbb{R}^3); \mathbb{C}) \in \text{HopfAlg}_{\mathbb{C}}^{\mathbb{Z}}. \quad (152)$$

In fact, under concatenation of loops, this graded group forms a non-commutative graded *Pontrjagin-Hopf algebra*, and by comparison with the case of Yang-Mills theory [SS24b, Thm. 3.1] we may regard this as the algebra of topological quantum observables on our higher gauge theory, regarded as the topological sector of discrete light cone quantization of the system [SS24b, §4].

This turns out to be particularly interesting for ‘‘open’’ M5-branes:

**Open M5-branes.** To complete the desired dimensional reduction of the M5-worldvolume to 1+3 dimensions, consider now  $\mathbb{Z}_2$ -orbifolding one of the dimensions transverse to the Skyrmons, via the reflection action (the sign representation of  $\mathbb{Z}_2$ ) as in heterotic M-theory (Hořava-Witten theory [HW96]), so that the M5 worldvolume (151) now becomes the orbifold

$$\Sigma \equiv \mathbb{R}_{\sqcup\{\infty\}}^{1,1} \wedge (\mathbb{R}^2 \times \mathbb{R}_H^1 // \mathbb{Z}_2)_{\cup\{\infty\}} \wedge (S_A^1)_{\sqcup\{\infty\}} \quad \boxed{\mathbb{R}^{1,1} \times \mathbb{R}^2 \times S_H^1 \times S_A^1} \quad (153)$$

where the orbifolded torus  $S_A^1 \times S_H^1 // \mathbb{Z}_2$  is that from [HW96, Fig. 2]. Essentially this compactification of the worldvolume of M5-branes is also considered for discussion of Skyrmons in [ILP18] (except that here we take  $S_A^1$  to be tangential instead of transversal to the Skyrmons, in order to reduce them to anyons, below).

Such M5-brane configurations wrapping  $S_H^1 // \mathbb{Z}_2$  are known as ‘‘open M5-branes’’ [BGT06, Fig. 3]<sup>12</sup> (denoted ‘‘M5 worldvolume’’ in [FSS20a, (52)], and by a gray bar in [FSS21b, p. 2]), whose orbi-singularity may be identified with a *non-supersymmetric* 4-brane [KOTY23], hence here with a 3-brane as we think of the  $S_A^1$ -factor shrunk away – cf. the figure below (156). This process of obtaining a non-supersymmetric 3-brane by wrapping the M5 on a supersymmetry-breaking torus is similar to the construction in the WSS model for holographic QCD [Wi98, §4] which instead of the  $\mathbb{Z}_2$ -orbifold of the torus  $S_H^1 \times S_A^1$  envisions compactification on a plain torus but equipped with supersymmetry-breaking spin structure.

**Charge moduli on open M5-branes.** The proper way to measure charges on such orbifolds is in proper orbifold cohomology [SS20b] (familiar for D-brane charges measured in orbifold/equivariant K-theory [SV10][SS21b, Ex. 4.5.4]), which for the case of flux quantization in co-Homotopy means ([SS20a, §3][SS20b, §5.2][SS20c]) to measure

<sup>12</sup>Strictly speaking, the discussion in [BGT06] is for solitonic/singular M5-branes, while here we are concerned with the analogous situation for the *probe* incarnation of the open M5-brane (its ‘‘non-linear sigma-model’’), hence without backreaction.

in orbifold/equivariant co-Homotopy, namely with the moduli space (148) in the case (149) replaced by the pointed equivariant mapping space:

$$\text{Equivariant co-Homotopy moduli } \tilde{\pi}_{\mathbb{Z}_2}^{2,1}((\mathbb{R}^2 \times \mathbb{R}_H^1) \cup \{\infty\}) := \text{Maps}_{\mathbb{Z}_2}^* \left( (\mathbb{R}^2 \times \mathbb{R}_H^1) \cup \{\infty\}, (\mathbb{R}^2 \times \mathbb{R}_H^1) \cup \{\infty\} \right) \text{Equivariant pointed mapping space}$$

Now the equivariant generalization of Segal's theorem ([RS00, Thm. 2]) that these orbifold moduli are equivalent to (group completed) equivariant configurations of points, namely to  $\mathbb{Z}_2$ -invariant finite subsets of  $\mathbb{R}^2 \times \mathbb{R}_H^1$ :

$$\tilde{\pi}^{2,1} \left( (\mathbb{R}^2 \times \mathbb{R}_H^1) \cup \{\infty\} \right) \underset{\text{hmtp}}{\simeq} \mathbb{G} \left( \text{Conf}(\mathbb{R}^2 \times \mathbb{R}_H^1)^{\mathbb{Z}_2} \right).$$

But this means that any one of the points (branes) in a configuration

- either moves freely in the Hořava-Witten bulk  $\mathbb{R}^2 \times \mathbb{R}_{>0} \simeq \mathbb{R}^3$  (exactly mirrored by a point in  $\mathbb{R}^2 \times \mathbb{R}_{<0}$ )
- or is stuck on the heterotic plane  $\mathbb{R}^2 \times \{0\} \simeq \mathbb{R}^2$ ,

hence it means that the moduli space is now the product of spaces of configurations in the Hořava-Witten bulk and on the heterotic plane (cf. also [Xi06, (1.2), Thm. 4.1]):

$$\text{Heterotic co-Homotopy charge moduli space } \tilde{\pi}^{2,1} \left( (\mathbb{R}^2 \times \mathbb{R}_H^1) \cup \{\infty\} \right) \underset{\text{hmtp}}{\simeq} \underbrace{\mathbb{G}\text{Conf}(\mathbb{R}^3)}_{\text{Brane configurations in HW-bulk } \simeq (150)} \times \underbrace{\mathbb{G}\text{Conf}(\mathbb{R}^2)}_{\text{Brane configurations on heterotic plane}}. \quad (154)$$

This is most curious, because:

**Vortex braiding on open M5 branes.** The configuration space of points in  $\mathbb{R}^2$  that has appeared on the right in (150) is the classifying space of the Artin braid groups  $\text{Br}(n)$  ([FN62, §7], cf. [Wi20, pp. 9]), whose loop space at given  $c_\infty = N$  is the braid group itself:

$$\text{Conf}(\mathbb{R}^2) \simeq \coprod_{n \in \mathbb{N}} B\text{Br}(N), \quad \Omega_N \text{Conf}(\mathbb{R}^2) \simeq \text{Br}(N).$$

Therefore the algebra of topological light cone quantum observables (152) on our open M5-brane fields now contains the group algebra of the braid group:

$$\mathbb{C}[\text{Br}(N)] = H_0(\Omega_N \text{Conf}(\mathbb{R}^2)) \hookrightarrow H_\bullet \left( \Omega_{c_\infty} \tilde{\pi}^{2,1} \left( (\mathbb{R}^2 \times \mathbb{R}_H^1) \cup \{\infty\} \right) \right). \quad (155)$$

Looking back through the construction, we see that the braiding happening here is that of the skyrmions in 1+5 dimensions (solitonic 2-branes) which have been dimensionally reduced to solitonic 1-branes in 1+3 dimensions (akin to Abrikosov vortices).

At this point one expects these objects to be anyonic. Indeed, we may now derive that this is the case:

**Anyonic quantum states on open M5.** Given a quantum (star-)algebra of observables as in (155) the corresponding *quantum states* are identified with the positive linear functions  $\rho$  on the vector space of observables (these assigning the expectation values  $\rho(A)$  of any observable  $A$  in the given quantum state, cf. [CSS23, §2.2] in our context):

$$\text{QStates}_{\text{vrtx}} := \left\{ \text{Obs} \xrightarrow[\text{linear}]{\rho} \mathbb{C} \mid \forall_{A \in \text{Obs}} \rho(A^*A) \geq 0 \in \mathbb{R} \subset \mathbb{C} \right\}.$$

Hence, the quantum states of those vortex charges on the compactified M5-brane are the positive linear functionals on the braid group algebra  $\mathbb{C}[\text{Br}(N)]$  (155).

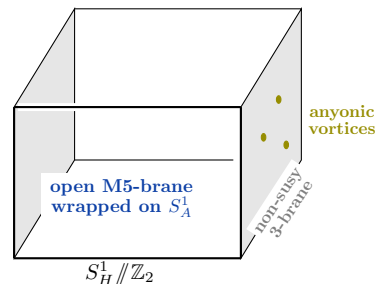
Now the *Gelfand-Raikov theorem* [Gr43, (2)][Dix77, Thm. 13.4.5(ii)] says that the positive linear functionals on a group algebra are exactly the expectation values with respect to a cyclic state  $|\psi\rangle$  of unitary representations  $U$  of that group on some Hilbert space:

$$\left. \begin{array}{l} \text{Braid group representations} \\ \left\{ \begin{array}{l} \mathcal{H} \text{ Hilbert space} \\ \text{Br}(N) \xrightarrow{U} \text{U}(\mathcal{H}) \text{ unitary rep} \\ |\psi\rangle \in \mathcal{H} \text{ cyclic vector} \end{array} \right\} / \sim \\ (\mathcal{H}, U, |\psi\rangle) \end{array} \right\} \underset{\text{are identified with}}{\xrightarrow{\sim}} \left. \begin{array}{l} \text{topological quantum states} \\ \text{of vortex solitons} \\ \text{on open M5-branes} \\ \left\{ \mathbb{C}[\text{Br}(N)] \xrightarrow{\rho} \mathbb{C} \text{ pos. lin. func.} \right\} = \text{States}_{\text{vrtx}} \end{array} \right\} \quad (156)$$

$$\longmapsto \left( \rho : \sum_{g \in \text{Br}(N)} c_g \cdot g \mapsto \sum_{g \in \text{Br}(N)} c_g \langle \psi | U(g) | \psi \rangle \right).$$

But here  $U$  is a braid group representation which hence exhibits  $\mathcal{H}$  as a space of anyon quantum states  $|\psi\rangle$  (cf. e.g. [NSS<sup>+</sup>08][Ro22] and in our context [SS23b][SS23c][MySS24, §3]).

In summary, we have found that flux quantization on M5-branes (under Hypothesis H) makes the topological quantum states of the vortex solitons (154) on the boundary of the open M5-brane (153) (wrapped over  $S_A^1$ ) be anyonic, as expected in strongly-correlated (topologically ordered) quantum systems. We discuss this effect in more detail in the followup [SS24c].



**Remark 4.4 (Non-abelian solitonic effects through flux quantization in non-abelian cohomology).**

(i) For appreciating these results, notice that even though we do not consider “coincident” brane worldvolumes here — on which only common lore [Wi96, p. 8] expects non-abelian gauge groups, such as  $SU(2)$  — a degree of non-abelianness is introduced even on the single M5-brane by quantizing its flux in a *non-abelian cohomology theory* [FSS23, §II] like 3-Cohomotopy.

(ii) Concretely (cf. [FSS23, Rem. 2.1]), where ordinary 3-cohomology  $H^3(-; \mathbb{Z}) \simeq H^1(-; B^2\mathbb{Z}) = \pi_0 \text{Maps}(-; BB^2\mathbb{Z})$  is an abelian cohomology theory in that the Eilenberg-MacLane space  $B^2\mathbb{Z} = K(\mathbb{Z}, 2)$  is an abelian  $\infty$ -group (an  $\infty$ -loop space), this is not the case for 3-Cohomotopy  $\pi^3(-) = H^1(-; \Omega S^3) = \pi_0 \text{Map}(-; B\Omega S^3)$ , since the  $\infty$ -group  $\Omega S^3$  is just a braided  $\infty$ -group but not abelian (it admits only two deloopings), cf. Rem. 4.3 above.

(iii) Specifically, it is through the equivalence of underlying homotopy types  $SU(2) \simeq S^3$  that the 3-cohomotopically flux-quantized B-field on the single M5-brane has Skyrmion-like field configurations even in the absence of an ordinary  $SU(2)$ -gauge field. More discussion of this phenomenon on M5-branes is in [FSS21c].

## 5 Conclusion

We have established that and how the on-shell field content on M5-branes is to be completed by a choice of flux quantization law (p. 4) for the higher gauge field on super-space (where the flux Bianchi identity already implies the duality equation of motion, Prop. 3.18).

In doing so, we relied on a rigorous and streamlined re-derivation (in §3) of the flux sector of the “super-embedding”-construction of the M5-brane sigma-model. We suggest that our concise natural geometric re-formulation of the “super-embedding”-conditions (Def. 2.19 in §2, cf. Rem. 2.23) helps with understanding the phase spaces of super  $p$ -brane sigma-models — in the present case but also in its generalizations such as to “super-exceptional” geometry (to which we turn in [GSS24c]).

With this in hand, we used previous results to find that among the admissible flux quantization laws on the M5-brane is a form of twisted co-Homotopy theory (21), thereby showing that this yields exact global field content on the M5 without the need of further constraints (which had previously remained open).

Assuming this choice (“Hypothesis H”), we have discussed, in §4, some key examples of the resulting moduli spaces and quantum states of topological charges, highlighting that Skyrmion-like solitonic charges appear quite generically on M5-branes, and that on “open” M5-branes the quantum states of the resulting vortex-like solitons in 1+3 dimensions are anyonic (156). (This complements previous results [SS23b][SS23c] where anyonic quantum statistics was argued for *intersecting* M5-brane configurations, which however are not as readily connected to a full on-shell superspace model as considered here. Notice that previously the realization of anyonic brane states had remained conjectural, cf. [dBS13, p. 65].)

This result supports the general idea that the M5-brane may serve as a much needed general model for otherwise elusive quantum phenomena in the strongly coupled/correlated non-perturbative regime and may point the way to a more microscopically detailed form of holography in high-energy and solid-state physics.

We discuss applications of the present result to holography in [GSS24b], to quantum materials in [SS24c] and plan to discuss an application to exceptional supergravity in [GSS24c].



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